# Chapter 6

# Deadlocks

6.1. Resources

- 6.2. Introduction to deadlocks
- 6.3. The ostrich algorithm
- 6.6. Deadlock prevention
- 6.4. Deadlock detection and recovery
- 6.5. Deadlock avoidance
- 6.7. Other issues



#### Learning Outcomes

- Understand what deadlock is and how it can occur when giving mutually exclusive access to multiple resources.
- Understand several approaches to mitigating the issue of deadlock in operating systems.
  - Including deadlock *prevention, detection and recovery,* and deadlock *avoidance.*



#### Resources

- Examples of computer resources
  - printers
  - tape drives
  - Tables in a database
- Processes need access to resources in reasonable order
- Preemptable resources
  - can be taken away from a process with no ill effects
- Nonpreemptable resources
  - will cause the process to fail if taken away



### Resources & Deadlocks

- Suppose a process holds resource A and requests resource B
  - at same time another process holds B and requests A
  - both are blocked and remain so Deadlocked
- Deadlocks occur when ...
  - processes are granted exclusive access to devices, locks, tables, etc..
  - we refer to these entities generally as <u>resources</u>



#### **Resource Access**

- Sequence of events required to use a resource
  - 1. request the resource
  - 2. use the resource
  - 3. release the resource
- Must wait if request is denied
  - requesting process may be blocked
  - may fail with error code



#### Two example resource usage patterns

```
semaphore res_1, res_2;
void proc A() {
 down(&res 1);
 down(&res 2);
 use_both_res();
 up(&res_2);
 up(&res 1);
void proc B() {
 down(&res_1);
 down(&res 2);
 use_both_res();
 up(\&res 2);
 up(&res 1);
```

```
semaphore res_1, res_2;
void proc_A() {
 down(&res_1);
 down(&res 2);
 use_both_res();
 up(&res 2);
 up(&res 1);
void proc B() {
 down(&res_2);
 down(&res 1);
 use_both_res();
 up(&res 1);
 up(&res 2);
```



### Introduction to Deadlocks

• Formal definition :

A set of processes is deadlocked if each process in the set is waiting for an event that only another process in the set can cause

- Usually the event is release of a currently held resource
- None of the processes can ...
  - run
  - release resources
  - be awakened



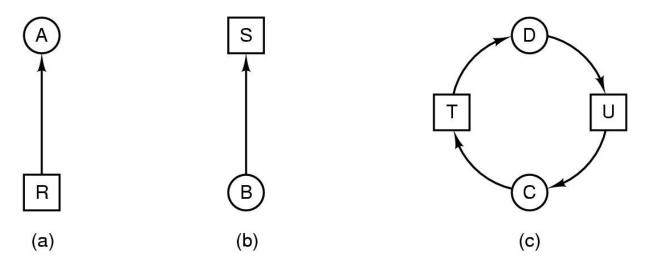
# Four Conditions for Deadlock

- 1. Mutual exclusion condition
  - each resource assigned to 1 process or is available
- 2. Hold and wait condition
  - process holding resources can request additional
- 3. No preemption condition
  - previously granted resources cannot be forcibly taken away
- 4. Circular wait condition
  - must be a circular chain of 2 or more processes
  - each is waiting for resource held by next member of the chain



# **Deadlock Modeling**

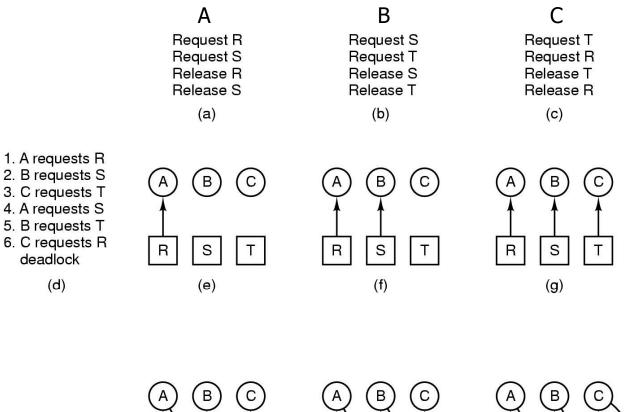
Modeled with directed graphs



- resource R assigned to process A
- process B is requesting/waiting for resource S
- process C and D are in deadlock over resources T and U

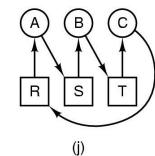


### **Deadlock Modeling**



B C A S T R (h)

R



#### How deadlock occurs

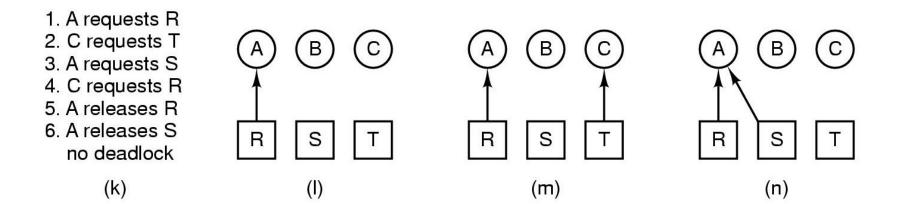
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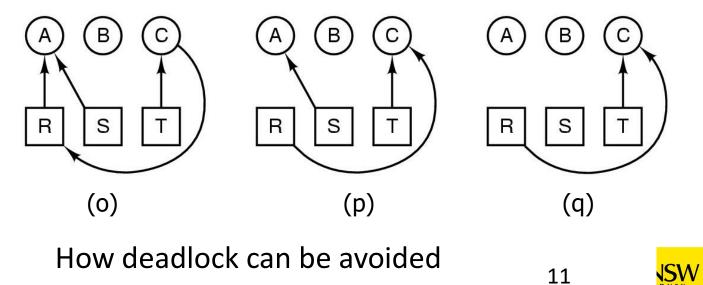
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Т



#### **Deadlock Modeling**





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### Deadlock

#### Strategies for dealing with Deadlocks

- 1. just ignore the problem altogether
- 2. prevention

•

- negating one of the four necessary conditions
- 3. detection and recovery
- 4. dynamic avoidance
  - careful resource allocation



# Approach 1: The Ostrich Algorithm

- Pretend there is no problem
- Reasonable if
  - deadlocks occur very rarely
  - cost of prevention is high
    - Example of "cost", only one process runs at a time
- UNIX and Windows takes this approach for some of the more complex resource relationships to manage
- It's a trade off between
  - Convenience (engineering approach)
  - Correctness (mathematical approach)



# Approach 2: Deadlock Prevention

- Resource allocation rules prevent deadlock by prevent one of the four conditions required for deadlock from occurring
  - Mutual exclusion
  - Hold and wait
  - No preemption
  - Circular Wait



#### Approach 2 Deadlock Prevention Attacking the Mutual Exclusion Condition

- Not feasible in general
  - Some devices/resource are intrinsically not shareable.



# Attacking the Hold and Wait Condition

- Require processes to request resources before starting
  - a process never has to wait for what it needs
- Issues
  - may not know required resources at start of run
    - $\Rightarrow$  not always possible
  - also ties up resources other processes could be using
- Variations:
  - process must give up all resources if it would block holding a resource
  - then request all immediately needed
  - prone to livelock



### Livelock

- Livelocked processes are not blocked, change state regularly, but never make progress.
- Example: Two people passing each other in a corridor that attempt to step out of each other's way in the same direction, indefinitely.
  - Both are actively changing state
  - Both never pass each other.



#### Deadlock Example

/\* PROCESS 0 \*/ /\* PROCESS 1 \*/ flag[0] = true;while (flag[1]) /\* do nothing \*/; /\* critical section\*/; /\* critical section\*/; flag[0] = false; flag[1] = false;

```
flag[1] = true;
while (flag[0])
          /* do nothing */;
```



### Livelock Example

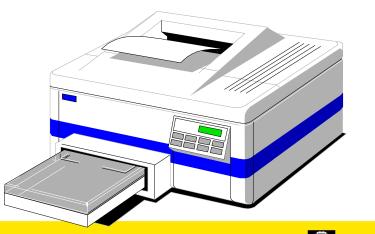
```
/* PROCESS 0 */ /* PROCESS 1 */
flag[0] = true;
while (flag[1]){
   flag[0] = false;
   /*delay */;
   flag[0] = true;
}
flag[0] = false;
```

```
flag[1] = true;
                     while (flag[0]) {
                          flag[1] = false;
                         /*delay */;
                        flag[1] = true;
/*critical section*/; /* critical section*/;
               flag[1] = false;
```



#### Attacking the No Preemption Condition

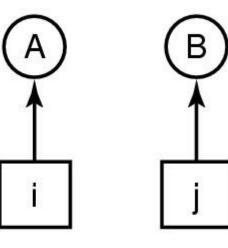
- This is not a viable option
- Consider a process given the printer
  - halfway through its job
  - now forcibly take away printer
  - !!??





# Attacking the Circular Wait Condition

Imagesetter
 Scanner
 Plotter
 Tape drive
 CD Rom drive



(a)

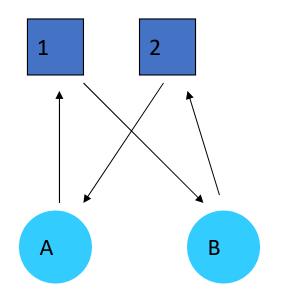
(b)

• Numerically ordered resources



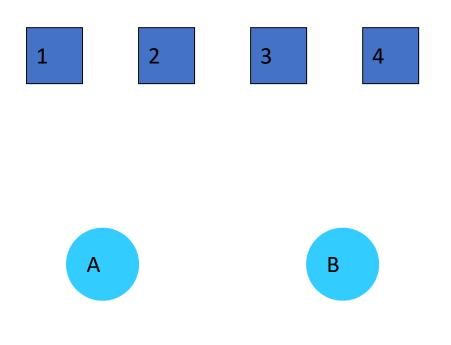
### Attacking the Circular Wait Condition

- The displayed deadlock cannot happen
  - If A requires **1**, it must acquire it before acquiring **2**
  - Note: If B has 1, all higher numbered resources must be free or held by processes who doesn't need 1
- Resources ordering is a common technique in practice!!!!!





### Example





#### Summary of approaches to deadlock prevention

Condition

- Mutual Exclusion
- Hold and Wait
- No Preemption
- Circular Wait

Approach

- Not feasible
- Request resources initially
- Take resources away
- Order resources

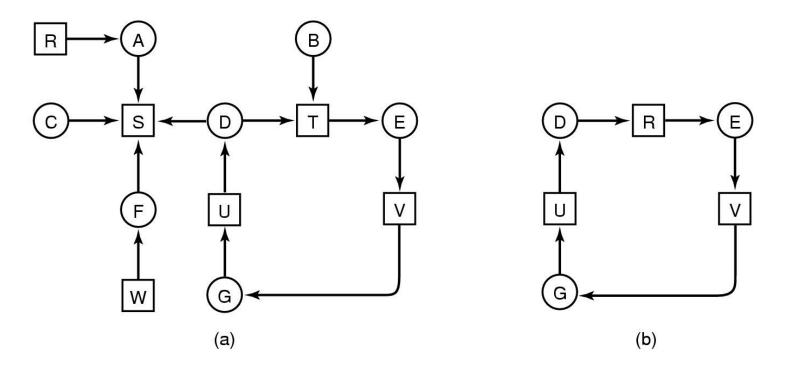


# Approach 3: Detection and Recovery

- Need a method to determine if a system is deadlocked.
- Assuming deadlocked is detected, we need a method of recovery to restore progress to the system.



# Approach 3 Detection with One Resource of Each Type



- Note the resource ownership and requests
- A cycle can be found within the graph, denoting deadlock



## What about resources with multiple units?

#### • Examples

- KBs of memory to execute
- DVD drives to duplicate a disk
- Blocks on disk to store files
- We need an approach for dealing with resources that consist of more than a single unit.



# Detection with Multiple Resources of Each Type

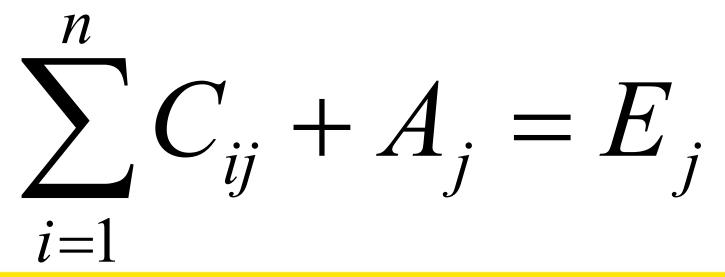
Resources in existence<br/> $(E_1, E_2, E_3, ..., E_m)$ Resources available<br/> $(A_1, A_2, A_3, ..., A_m)$ Current allocation matrixRequest matrix $\begin{bmatrix} C_{11} & C_{12} & C_{13} & \cdots & C_{1m} \\ C_{21} & C_{22} & C_{23} & \cdots & C_{2m} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ C_{n1} & C_{n2} & C_{n3} & \cdots & C_{nm} \end{bmatrix}$  $\begin{bmatrix} R_{11} & R_{12} & R_{13} & \cdots & R_{1m} \\ R_{21} & R_{22} & R_{23} & \cdots & R_{2m} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ R_{n1} & R_{n2} & R_{n3} & \cdots & R_{nm} \end{bmatrix}$ Row n is current allocation<br/>to process nResources available<br/> $(A_1, A_2, A_3, ..., A_m)$ 

Data structures needed by deadlock detection algorithm



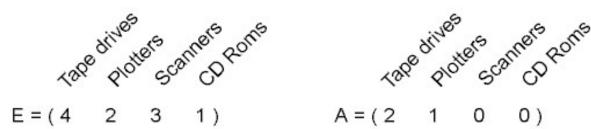
#### Note the following invariant

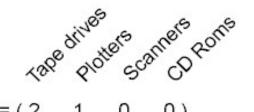
Sum of current resource allocation + resources available = resources that exist





# Detection with Multiple Resources of Each Type





Current allocation matrix					Request matrix				
C =	0 2 0	0 0 1	1 0 2	0 1 0	R =	2 1 2	0 0 1	0 1 0	1 0 0

#### An example for the deadlock detection algorithm



#### **Detection Algorithm**

- 1. Look for an unmarked process *Pi*, for which the *i*-th row of R is less than or equal to A
- 2. If found, add the *i*-th row of C to A, and mark *Pi*. Go to step 1
- 3. If no such process exists, terminate.

Remaining processes are deadlocked



$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 2 & 1 & 0 & 0 \end{pmatrix}$$
$$C = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{pmatrix}$$



$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 2 & 1 & 0 & 0 \end{pmatrix}$$
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$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 2 & 2 & 2 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{pmatrix}$$





$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 4 & 2 & 2 & 1 \end{pmatrix}$$
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$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 4 & 2 & 2 & 1 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{pmatrix}$$



$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 4 & 2 & 2 & 1 \end{pmatrix}$$
$$= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{pmatrix}$$



$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 4 & 2 & 3 & 1 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{pmatrix}$$



- Algorithm terminates with no unmarked processes
  - We have no dead lock



 Suppose, P3 needs a CD-ROM as well as 2 Tapes and a Plotter

$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix} \qquad A = \begin{pmatrix} 2 & 1 & 0 & 0 \end{pmatrix}$$
$$C = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{pmatrix} \qquad R = \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{pmatrix}$$



# Recovery from Deadlock

- Recovery through preemption
  - take a resource from some other process
  - depends on nature of the resource
- Recovery through rollback
  - checkpoint a process periodically
  - use this saved state
  - restart the process if it is found deadlocked
    - No guarantee is won't deadlock again



# Recovery from Deadlock

- Recovery through killing processes
  - crudest but simplest way to break a deadlock
  - kill one of the processes in the deadlock cycle
  - the other processes get its resources
  - choose process that can be rerun from the beginning

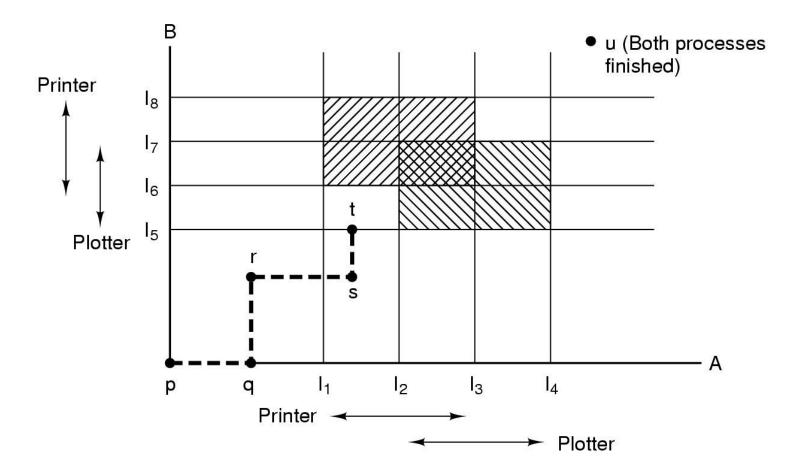


# Approach 4 Deadlock Avoidance

- Instead of detecting deadlock, can we simply avoid it?
  - YES, but only if enough information is available in advance.
    - Maximum number of each resource required



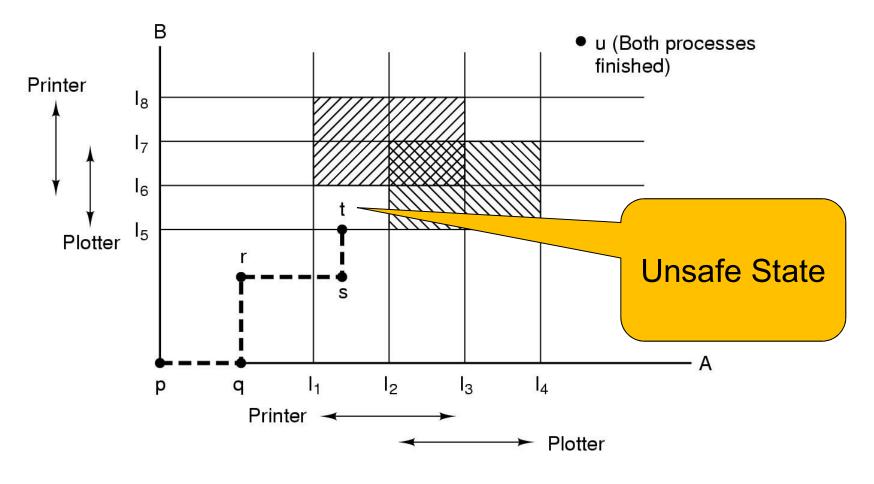
# Deadlock Avoidance Resource Trajectories



Two process resource trajectories



# Deadlock Avoidance Resource Trajectories



Two process resource trajectories



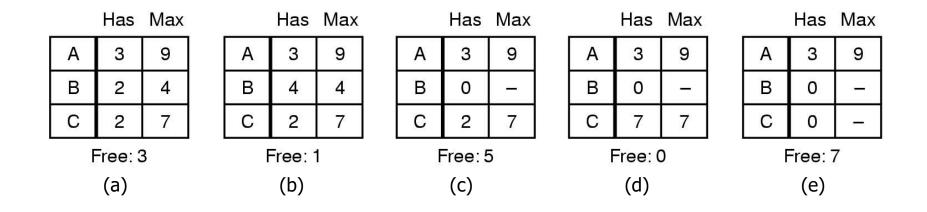
# Safe and Unsafe States

- A state is *safe* if
  - The system is not deadlocked
  - There exists a scheduling order that results in every process running to completion, even if they all request their maximum resources immediately



# Safe and Unsafe States

# Note: We have 10 units of the resource

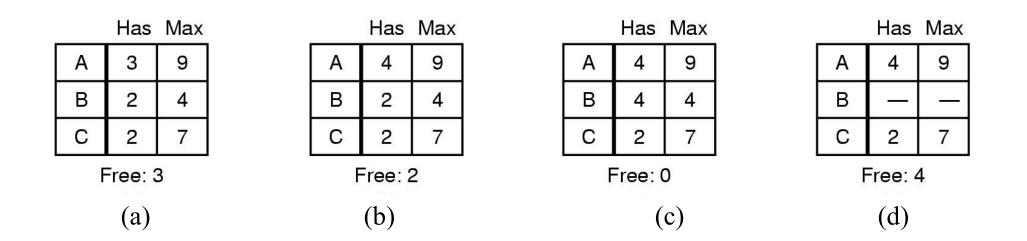


#### Demonstration that the state in (a) is safe



# Safe and Unsafe States

A requests one extra unit resulting in (b)



#### Demonstration that the state in b is not safe



# Safe and Unsafe State

- Unsafe states are not necessarily deadlocked
  - With a lucky sequence, all processes may complete
  - However, we *cannot guarantee* that they will complete (not deadlock)
- Safe states guarantee we will eventually complete all processes
- Deadlock avoidance algorithm:
  - Only grant requests that result in safe states

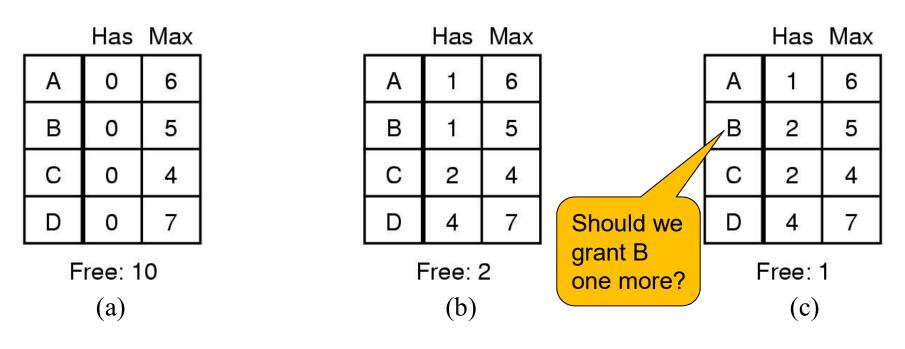


# **Bankers Algorithm**

- Modelled on a Banker with Customers
  - The banker has a limited amount of money to loan customers
    - Limited number of resources
  - Each customer can borrow money up to the customer's credit limit
    - Maximum number of resources required
- Basic Idea
  - Keep the bank in a *safe* state
    - So all customers are happy even if they all request to borrow up to their credit limit at the same time.
  - Customers wishing to borrow such that the bank would enter an unsafe state must wait until somebody else repays their loan such that the the transaction becomes safe.



### The Banker's Algorithm for a Single Resource

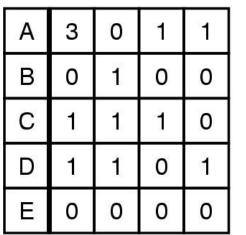


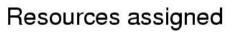
- Three resource allocation states
  - safe
  - safe
  - unsafe



### Banker's Algorithm for Multiple Resources









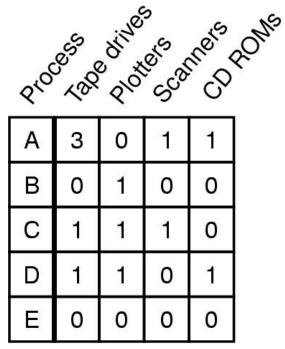
Α	1	1	0	0	E = (6342)
В	0	1	-	2	P = (5322) A = (1020)
С	3	1	0	0	// (///////////////////////////////////
D	0	0	Ţ	0	
Е	2	1	1	0	

Resources still needed

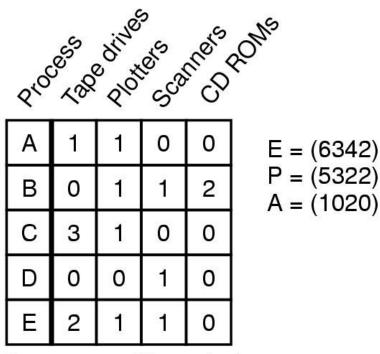
Example of banker's algorithm with multiple resources System should start in safe state!



### Banker's Algorithm for Multiple Resources



Resources assigned



Resources still needed

Example of banker's algorithm with multiple resources Should we allow a request by B 1 scanner to succeed??



### Banker's Algorithm for Multiple Resources



А	3	0	1	1
В	0	1	0	0
С	1	1	1	0
D	1	1	0	1
Е	0	0	0	0



А	1	1	0	0	E
В	0	1	1	2	E P A
С	3	1	0	0	
D	0	0	1	0	5
Е	2	1	1	0	

E = (6342) P = (5322) A = (1020)

Resources assigned

Resources still needed

Example of banker's algorithm with multiple resources Should we allow a request by B and E for 1 scanner to succeed??



# Bankers Algorithm is not commonly used in practice

- It is difficult (sometimes impossible) to know in advance
  - the resources a process will require
  - the number of processes in a dynamic system



### Starvation

- A process never receives the resource it is waiting for, despite the resource (repeatedly) becoming free, the resource is always allocated to another waiting process.
  - Example: An algorithm to allocate a resource may be to give the resource to the shortest job first
  - Works great for multiple short jobs in a system
  - May cause a long job to wait indefinitely, even though not blocked.
- One solution:
  - First-come, first-serve policy

