# COMP1927 17x1 Computing 2 

## Complexity

# Problems, Algorithms, Programs and Processes 

- Problem: A problem that needs to be solved
- Algorithm: Well defined instructions for completing the problem
- Program: Implementation of the algorithm in a particular programming language
- Process: An instance of the program as it is being executed on a particular machine


## Analysis of software

What makes "good" software?

- Correct: returns expected result for all valid inputs guaranteed through formal specification
- Reliable: behaves "sensibly" for non-valid inputs/errors and handled gracefully
Correctness/Reliability ensured through robust testing
- Maintainable: clear, well-structure code

Coding style, recommended conventions

- Efficient: produces results quickly (even for large inputs) Efficiency determined through algorithm efficiency

We may sometimes also be interested in other measures

- memory/disk space, network traffic, disk IO etc


## Algorithm Efficiency

- The algorithm is by far the most important determinant of the efficiency of a program
- Algorithm efficiency determined through algorithm analysis, can save factors of thousands or millions in the running time
- Small speed ups in terms of operating systems, compilers, computers and implementation details are irrelevant. They may give small speed ups but usually only by a small constant factor


## Algorithm Analysis

Branch of computer science to determine choice of the best algorithm for a particular task.

- Mathematical Analysis
- Analyse asymptotic time complexity - the limiting behaviour of the execution time of an algorithm when the size of the problem goes to infinity
- Usually denoted in big-O notation.
- Can be done at design-stage (pseudo-code)
- Empirical Analysis
- Post-implementation stage
- Once it is implemented and correct, evaluate which algorithm takes longer e.g., using the time command


## Timing

- Note we are not interested in the absolute time it takes to run.
- We are interested in the relative time it takes as the problem increases
- Absolute times differ on different machines and with different languages


## Time Complexity Analysis

- Enables us to understand the performance of algorithms
- Define a function to characterize execution cost (气time)
- Identify the core operation in the algorithm
- Identify the value to measure the size of the input ( $\boldsymbol{N}$ ) (e.g. \#items in data structure, length of input file, no of chars in string etc)
- Express cost in terms of \#operations = $f(n)$, which is the time-complexity as a function of input size
- Shows how the cost increases with increase in input size
- Is the algorithm feasible for $100,10000,100000$ ?


## Big O-notation Formal Definition

The big O-notation is used to classify the work complexity of algorithms

Definition: A function $f(n)$ is said to be in (the set) $\mathrm{O}(g(n))$ if there exist constants $c$ and $N_{o}$ such that $f(n)<c{ }^{*} g(n)$ for all $n$ $>N_{o}$


## Informal Definition of Big-O Notation

- Big-O notation represents the asymptotic worst case (unless stated otherwise) time complexity
- Big-O expressions do not have constants or low-order terms as when $n$ gets larger these do not matter
- For example: For a problem of size n , if the cost of the worst case is
$1.5 n^{2}+3 n+10$
in Big-O notation would be $\mathrm{O}\left(\mathrm{n}^{2}\right)$


## Exercise: Time Complexity

## Example: finding max value in an unsorted array

int findMax(int a[], int N) \{
int $\mathrm{i}, \max =\mathrm{a}[0]$;
for ( $\mathrm{i}=1 ; \mathrm{i}<\mathrm{N} ; \mathrm{i}++$ )
if (a[i] > max) max $=a[i]$; return max;
\}

Core operation? ... compare a [i] to max How many times? ... clearly N-1 ... O(n)
Execution cost grows linearly (i.e. $2 \times$ \#elements $\Rightarrow$ $2 \times$ cost)

## Exercise: Time Complexity

## Example: finding max value in a sorted array

int findMax(int a[], int N) \{ return $a[\mathrm{~N}-1]$;
\}

No iteration needed; max is always last.
Core operation? ... index into array
How many times? ... once ... $O(1)$
Execution cost is constant (same regardless of \#elements)

## Predicting Time

- If I know my algorithm is quadratic and I know that it takes 1.2 seconds to run on a data set of size 1000
- Approximately how long would you expect to wait for a data set of size 2000?
- What about 10000 ?
- What about 100000 ?


## Empirical Analysis

- Use the 'time' command in linux.

Run on different sized inputs time ./prog < input > /dev/null not interested in real-time interested in user-time What is the relationship between

- input size
- time

| Size of <br> input(n) | Time |
| :--- | :--- |
| 100000 |  |
| 1000000 |  |
| 10000000 |  |
| 100000000 |  |

## Big-O Notation

- All constant functions are in $\mathrm{O}(1)$
- All linear functions are in $\mathrm{O}(n)$
- All logarithmic function are in the same class $\mathrm{O}(\log (n))$
- $\mathrm{O}\left(\log _{2}(n)\right)=\mathrm{O}\left(\log _{3}(n)\right)=\ldots$.
${ }^{*}\left(\right.$ since $\left.\log _{b}(a) * \log _{a}(n)=\log _{b}(n)\right)$
- We say an algorithm is $\mathrm{O}(g(n))$ if, for an input of size $n$, the algorithm requires $T(n)$ steps, with $T(n)$ in $\mathrm{O}(g(n)$ ), and $\mathrm{O}(g(n)$ ) minimal
- binary search is $O(\log (n))$
- linear search is $O(N)$
- finding maxium in an unsorted sequence is $O(N)$


## Common Categories

- $O(1)$ : constant - instructions in the program are executed a fixed number of times, independent of the size of the input
- $O(\log N)$ : logarithmic - some divide \& conquer algorithms with trivial splitting and combining operations
- $O(N)$ : linear - every element of the input has to be processed, usually in a straight forward way
- $O\left(N^{*} \log N\right)$ : Divide \&Conquer algorithms where splitting or combining operation is proportional to the input
- $O\left(N^{2}\right)$ : quadratic. Algorithms which have to compare each input value with every other input value. Problematic for large input
- $O\left(N^{3}\right)$ : cubic, only feasible for very small problem sizes
- $O\left(2^{N}\right)$ : exponential, of almost no practical use


## Complexity Matters

| $\mathbf{n}$ | $\boldsymbol{l o g} \mathbf{n}$ | nlogn | $\mathbf{n}^{\wedge 2}$ | $\mathbf{2}^{\wedge} \mathbf{n}$ |
| :--- | :--- | :--- | :--- | :--- |
| 10 | 4 | 40 | 100 | 1024 |
| 100 | 7 | 700 | 10000 | $1.3 E_{+}+30$ |
| 1000 | 10 | 10000 | 1000000 | REALLY <br> BIG |
| 10000 | 14 | 140000 | 100000000 |  |
| 100000 | 17 | 1700000 | 10000000000 |  |
| 1000000 | 20 | 20000000 | 1000000000000 |  |

## Exercise

What would be the time complexity of inserting an element at the beginning of

- a linked list
- an array

What would be the time complexity of inserting an element at the end of

- a linked list
- an array


## Searching

An extremely common application in computing

- given a (large) collection of items and a key value
- find the item(s) in the collection containing that key
- an item is defined as $\left\{k e y\right.$, val $_{1}$, val $\left._{2}\right\}$ (i.e. a struct)
- key = value used to distinguish items (e.g. student ID)

Keys may be ...

- primary ... key value uniquely identifies one item
- secondary ... many items may have the same key value

Applications: Google, databases, .....

## Searching (cont)

If we are dealing largely with primary keys, then search problem can be encapsulated as:

Item search(Collection c, Key k) \{ ... \}
Possible return values are:

- an Item
- "NOT FOUND" value

For secondary keys return an array (possibly empty) of matching items

Item *search(Collection c, key k, int *nmatches) $\{\ldots .$.

## Searching in Linear Structures

Search in an unsorted array or list
Item searchArray(Key k, Item a[], int n) \{ int i; for ( $\mathrm{i}=0 ; \mathrm{i}<\mathrm{n} ; \mathrm{i}++$ ) \{ if ( $a[i] \cdot k e y==k$ )
return a[i];
\} return NOT_FOUND;
\}
Item searchList(Key k, List L) \{ List n;
for ( $\mathrm{n}=\mathrm{L} ; \mathrm{n}$ != NULL; $\mathrm{n}=\mathrm{n}->\mathrm{next}$ )
\{ if ( $n->$ key $)==k$ )
return n ->data;
\} return NOT_FOUND;

## Linear Search Cost

- Core operation? ... compare a [i].key to k
- What is the worst cast cost?
- How many comparisons between data instances were made?
- How many times does each line run in the worst case?

C0: line 2: For loop $n+1$ times
C1: line 3: n comparisons
C2: line 4: 0 times (worst case)
C3: line 5: 1 time (worst case)
Total: $\mathrm{C} 0(\mathrm{n}+1)+\mathrm{C} 1(\mathrm{n})+\mathrm{C} 3=\mathrm{O}(\mathrm{n})$

- For an unsorted sequence that is the best we can do


## Searching in a Sorted Array

Given an array a of N elements, with $\mathrm{a}[\mathrm{i}]<=\mathrm{a}[\mathrm{j}]$ for any pair of indices $\mathrm{i}, \mathrm{j}$, with $\mathrm{i}<=\mathrm{j}<\mathrm{N}$,

- search for a key $k$ in the array

Item searchSortedArray(Key k, Item a[], int n) \{
int found $=0$;
int finished $=0$;
int $\mathrm{i}=0$;
while ((i < N) \& \& (!found) \& \& (!finished))\{
found $=(a[i] \cdot k e y==k)$;
finished = ( k < $[\mathrm{i}]$. key $)$; exploit the fact that a is sorte i++;

## Searching in a Sorted Array

How many steps are required to search an array of $N$ elements

- Best case: $T_{N}=1$
- Worst case: $T_{N}=N$
- Average: $T_{N}=N / 2$

Still a linear algorithm, like searching in a unsorted array

## Binary Search in a sorted array

- We start in the middle of the array:
- if $a[N / 2]==e$, we found the element and we're done
- and, if necessary, `split' array in half to continue search
- if $\mathrm{a}[\mathrm{N} / 2]<\mathrm{e}$, continue search on $\mathrm{a}[0]$ to $\mathrm{a}[\mathrm{N} / 2-1]$
- if $a[N / 2]>e$, continue search on $a[N / 2+1]$ to $a[N-1]$
- This algorithm is called binary search.


## Binary Search (cont)

- We maintain two indices, $I$ and $r$, to denote leftmost and rightmost array index of current part of the array
- initially $\mathrm{l}=0$ and $\mathrm{r}=\mathrm{N}-1$
- iteration stops when:
- left and right index define an empty array, element not found
- $\mathrm{EgI}>\mathrm{r}$
- $\mathrm{a}[(1+r) / 2]$ holds the element we're looking for
- if: $a[(l+r) / 2]$ is larger than element, continue search on left
$a[1] . . a[(1+r) / 2-1]$
else continue search on right
$a[(1+r) / 2+1] . . a[r]$


## Binary Search

- How many comparisons do we need for an array of size $N$ ?
- Best case:
- $T_{N}=1$
- Worst case:
- $T_{1}=1$
- $T_{N}=1+T_{N / 2}$
- $T_{N}=\log _{2} N+1$
- $O(\log n)$

Binary search is a

- logarithmic algorithm
-O- linear -O- log (N)


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