

Minimum Spanning Tree

Outline and Reading

- ◆ Minimum Spanning Trees (§12.7)
 - Definitions
 - Cycle property
 - Partition property
- ◆ Prim-Jarník's Algorithm (§12.7.2)
- ◆ Kruskal's Algorithm (§12.7.1)

Minimum Spanning Tree

Spanning subgraph

- Subgraph of a graph G containing all the vertices of G

Spanning tree

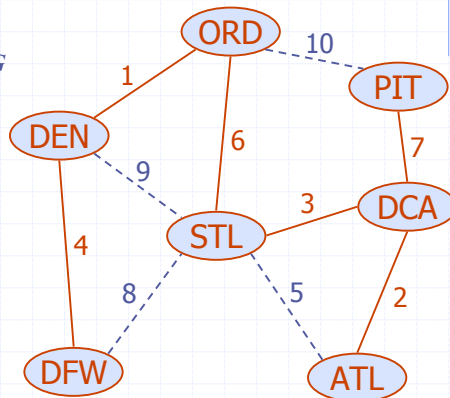
- Spanning subgraph that is itself a (free) tree

Minimum spanning tree (MST)

- Spanning tree of a weighted graph with minimum total edge weight

◆ Applications

- Communications networks
- Transportation networks



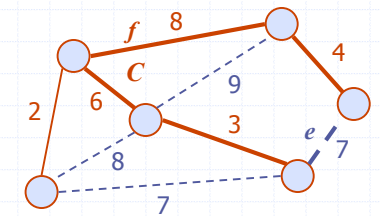
Cycle Property

Cycle Property:

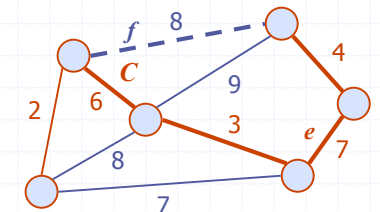
- Let T be a minimum spanning tree of a weighted graph G
- Let e be an edge of G that is not in T and C let be the cycle formed by e with T
- For every edge f of C , $weight(f) \leq weight(e)$

Proof:

- By contradiction
- If $weight(f) > weight(e)$ we can get a spanning tree of smaller weight by replacing e with f



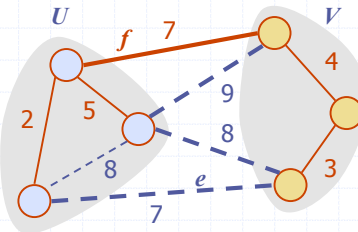
Replacing f with e yields a better spanning tree



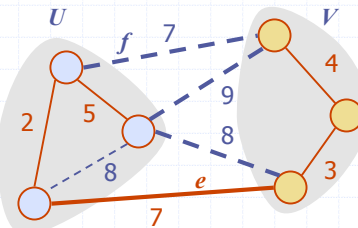
Partition Property

Partition Property:

- Consider a partition of the vertices of G into subsets U and V
- Let e be an edge of minimum weight across the partition
- There is a minimum spanning tree of G containing edge e



Replacing f with e yields another MST

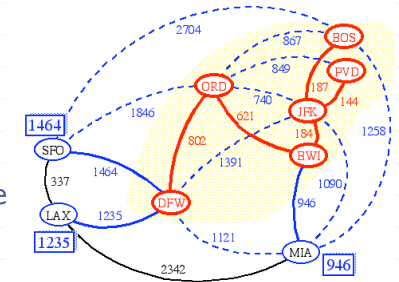


Proof:

- Let T be an MST of G
- If T does not contain e , consider the cycle C formed by e with T and let f be an edge of C across the partition
- By the cycle property, $weight(f) \leq weight(e)$
- Thus, $weight(f) = weight(e)$
- We obtain another MST by replacing f with e

Prim-Jarnik's Algorithm (§ 12.7.2)

- Similar to Dijkstra's algorithm (for a connected graph)
- We pick an arbitrary vertex s and we grow the MST as a cloud of vertices, starting from s
- We store with each vertex v a label $d(v)$ = the smallest weight of an edge connecting v to a vertex in the cloud
- At each step:
 - We add to the cloud the vertex u outside the cloud with the smallest distance label
 - We update the labels of the vertices adjacent to u



Prim-Jarnik's Algorithm (cont.)

- A priority queue stores the vertices outside the cloud
 - Key: distance
 - Element: vertex
- Locator-based methods
 - $insert(k,e)$ returns a locator
 - $replaceKey(l,k)$ changes the key of an item
- We store three labels with each vertex:
 - Distance
 - Parent edge in MST
 - Locator in priority queue

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Algorithm PrimJarnikMST( $G$ )
 $Q \leftarrow$  new heap-based priority queue
 $s \leftarrow$  a vertex of  $G$ 
for all  $v \in G.vertices()$ 
    if  $v = s$ 
         $setDistance(v, 0)$ 
    else
         $setDistance(v, \infty)$ 
         $setParent(v, \emptyset)$ 
         $l \leftarrow Q.insert(getDistance(v), v)$ 
         $setLocator(v, l)$ 
    while  $\neg Q.isEmpty()$ 
         $u \leftarrow Q.removeMin()$ 
        for all  $e \in G.incidentEdges(u)$ 
             $z \leftarrow G.opposite(u, e)$ 
             $r \leftarrow weight(e)$ 
            if  $r < getDistance(z)$ 
                 $setDistance(z, r)$ 
                 $setParent(z, e)$ 
                 $Q.replaceKey(getLocator(z), r)$ 
    
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