COMP 3221

Microprocessors and Embedded Systems

Lecture 8: C/Assembler Data Processing

http://www.cse.unsw.edu.au/~cs3221

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Review C Operators/Operands (#1/2)

° Operators: +, -, *, /, % (mod); •7/4==1, 7%4==3

° Operands:

- Variables: lower, upper, fahr, celsius
- Constants: 0, 1000, -17, 15.4

[°] Assignment Statement:

Variable = expression

• Examples:

```
celsius = 5*(fahr-32)/9;
```

```
a = b+c+d-e;
```

<u>Overview</u>

- ° C operators, operands
- ° Variables in Assembly: Registers
- ° Comments in Assembly
- ° Data Processing Instructions
- ° Addition and Subtraction in Assembly

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C Operators/Operands (#2/2)

° In C (and most High Level Languages) variables declared first and given a type

 Example: int fahr, celsius; char a, b, c, d, e;

° Each variable can ONLY represent a value of the type it was declared as (cannot mix and match int and char variables).

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Assembly Design: Key Concepts

° Keep it simple!

- Limit what can be a variable and what can't
- Limit types of operations that can be done to absolute minimum
 - if an operation can be decomposed into a simpler operation, don't include it.
 - For example 7%4 operation is complex. We break it into simpler operations in Assembly

Assembly Variables: Registers (#1/4)

° Unlike HLL, assembly cannot use variables

• Why not? Keep Hardware Simple

^o Assembly Operands are registers

- limited number of special locations built directly into the hardware
- operations can only be performed on these!

 Benefit: Since registers are directly in hardware, they are very fast

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Assembly Variables: Registers (#2/4)

^o Drawback: Since registers are in hardware, there are a predetermined number of them

• Solution: ARM code must be very carefully put together to efficiently use registers

°16 registers in ARM

Why 16? Smaller is faster

° Each ARM register is 32 bits wide

Groups of 32 bits called a word in ARM

Assembly Variables: Registers (#3/4)

- ° Registers are numbered from 0 to 15
- ^o Each register can be referred to by number or name
- ° Number references:

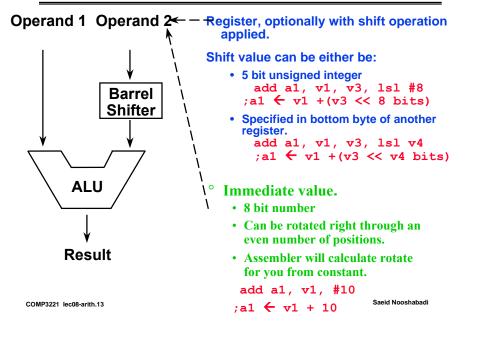
r0, r1, r2, ... r15

- $^{\circ}$ **r15** = **pc** has special significant:
- °**r15** is program counter pointing to instructions being fetched from memory

Assembly Variables: Registers (#4/4) **Comments in Assembly** ^o By convention, each register also has a name to make it easier to code ^o Another way to make your code more readable: comments! ° For now: ^o Hash (;) is used for ARMS comments r0 - r3 **→** • anything from (;) mark to end of line is a comment and will a1 - a4be ignored (correspond to C functions arguments, Used for scratch • GNU ARM assembler accepts (@) instead of (;) as well pad too!) r4 - r10 **→** v1 - v7^o Note: Different from C. (correspond to function variables) • C comments have format /* comment */, so they can span many lines ^o In general, use names to make your code more readable GNU ARM assembler accepts /* comments*/ as well. Saeid Nooshabadi Saeid Nooshabadi COMP3221 lec08-arith.10 COMP3221 lec08-arith.9 **Data processing Instructions Assembly Instructions** Largest category of ARM instructions, all sharing the same instruction format. ° In assembly language, each statement ° Contains: (called an Instruction), executes exactly one · Arithmetic operations of a short list of simple commands Comparisons (no results saved - just set condition code flags NZCV) Logical operations ^o Unlike in C (and most other High Level Data movement between registers Languages), each line of assembly code ° This is a load / store architecture contains at most 1 instruction • These instruction only work on registers, NOT memory. [°] They each perform a specific operation on operands. 4 field Format: 1 2, 3, 4 where: 1) operation by name 2) operand getting result ("destination") 3) 1st operand for operation ("source1") 4) second operand: register or shifted register or immediate (numerical constant)

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Using the Barrel Shifter: The Second Operand



Addition and Subtraction (#1/3)

° Addition in Assembly

 Example: 	add	v1,v2,v3 (in ARM)
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Equivalent to: a = b + c (in C)

where registers v1 , v2 , v3 are associated with variables a , b , c

° Subtraction in Assembly

• Example: sub v4, v5, v6 (in ARM)

Equivalent to: d = e - f(in C)

where registers v4 , v5 , v6 are associated with variables d , e , f

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Addition and Subtraction (#2/3)

° How do we do this?

• f = (g + h) - (i + j);

° Use intermediate register

add v1,v2,v3 ; f = g + h add a1,v4,v5 ; a1 = i + j ; need to save i+j, but can't use f, so use a1 sub v1,v1,a1 ; f=(g+h)-(i+j)

Addition and Subtraction (#3/3)

° How do the following C statement? a = b + c + d - e;

° Break into multiple instructions

add v1, v2, v3 ; a = b + c add v1, v1, v4 ; a = a + d sub v1, v1, v5 ; a = a - e

- [°] Notice: A single line of C may break up into several lines of ARM instructions.
- ^o Notice: Everything after the (;) mark on each line is ignored (comments)

Addition/Subtraction with Immediates (#1/2)

° Immediates are numerical constants.

^o They appear often in code, so there are special instructions for them.

° Add Immediate:

add v1, v2, #10 (in ARM)

f = g + 10 (in C)

where registers v1, v2 are associated with variables f, g

^o Syntax similar to add instruction with register, except that last argument is a number instead of a register. This number should be preceded by (#) symbol

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Addition/Subtraction with Immediates (#2/2)

° Similarly

add v1,v2,#-10 f = g - 10 (in C) where registers v1,v2 are associated with variables f, g

° OR

sub v1, v2, #10 f = g - 10 (in C) where registers v1, v2 are associated with variables f, g

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Data Movement Instruction

^o Addition with zero is conveniently used to move content of one register to another register, so:

add v1, v2, #0 (in ARM)

```
f = g (in C)
```

where registers v1,v2 are associated with variables f, $\ g$

° This is so often used in code that ARM has an specific instruction for it:

mov v1, v2

° Another useful instruction often used to provide delay in a loop is

mov v1, v1 ; this also called nop (No Operation)

• This does nothing useful

Reverse Subtraction Instruction

[°] Normal Subtraction:

• Example: sub v4, v5, v6 (in ARM); v4 ← v5 - v6 Equivalent to: d = e - f (in C)

where registers v4 , v5 , v6 are associated with variables d , $\,$ e , $\,$ f

° Reverse Subtraction:

• Example: $rsb v4, v5, v6 (in ARM); v4 \leftarrow v6 - v5$ Equivalent to: d = -(e) + f(in C)

where registers v4, v5, v6 are associated with variables d, e, f

°rsb is useful in many situations

COMPACE A Reading Materials (Week #3) • Steve Furber: ARM System On-Chip; 2nd Ed, constructions. • Are Architecture Reference Manual –On CD ROM • A Material Ma