Processes and Threads Implementation

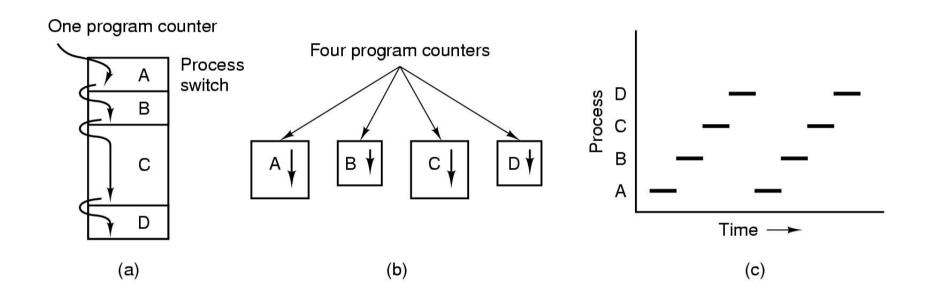


Learning Outcomes

- An understanding of the typical implementation strategies of processes and threads
 - Including an appreciation of the trade-offs between the implementation approaches
 - Kernel-threads versus user-level threads
- A detailed understanding of "context switching"



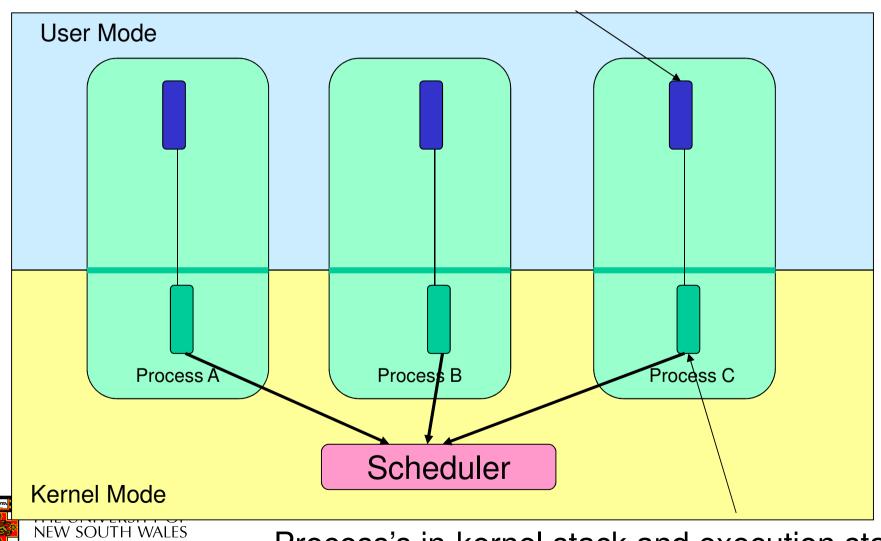
Summary: The Process Model



- Multiprogramming of four programs
- Conceptual model of 4 independent, sequential processes (with a single thread each)
- Only one program active at any instant

Processes

Process's user-level stack and execution state



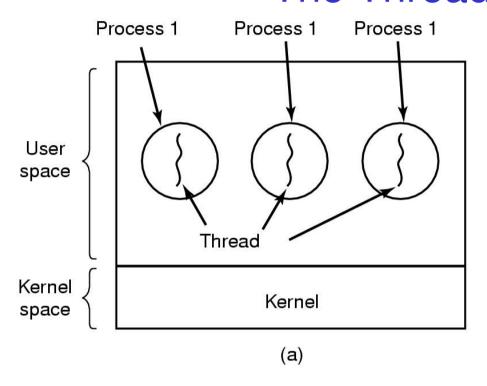
Process's in-kernel stack and execution state

Processes

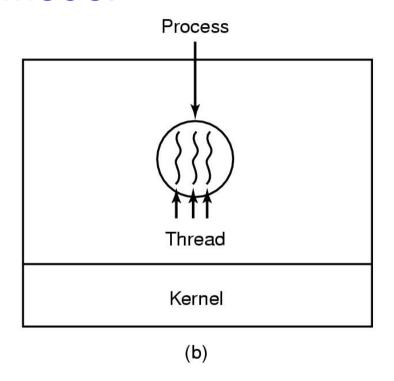
- User-mode
 - Processes (programs) scheduled by the kernel
 - Isolated from each other
 - No concurrency issues between each other
- System-calls transition into and return from the kernel
- Kernel-mode
 - Nearly all activities still associated with a process
 - Kernel memory shared between all processes
 - Concurrency issues exist between processes concurrently executing in a system call



Threads The Thread Model



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- (a) Three processes each with one thread
- (b) One process with three threads

The Thread Model

Per process items

Address space

Global variables

Open files

Child processes

Pending alarms

Signals and signal handlers

Accounting information

Per thread items

Program counter

Registers

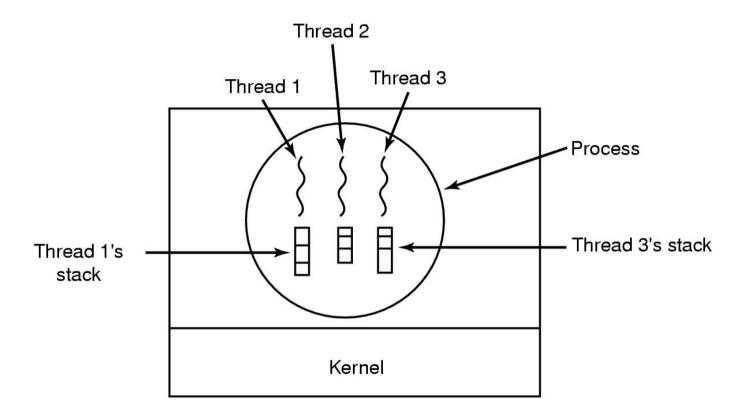
Stack

State

- Items shared by all threads in a process
- Items that exist per thread



The Thread Model



Each thread has its own stack

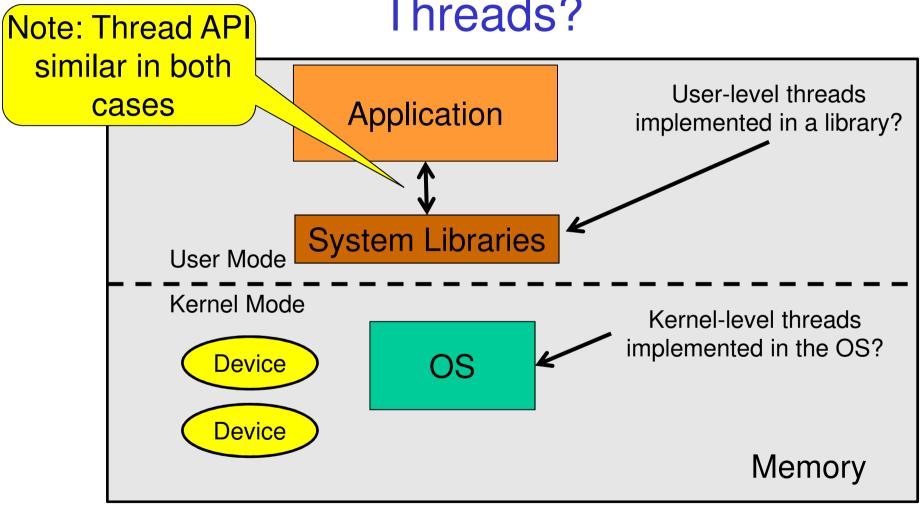


A Subset of POSIX threads API

```
pthread create(pthread t *, const pthread attr t *,
int
          void *(*)(void *), void *);
void
      pthread exit(void *);
      pthread_mutex_init(pthread_mutex_t *, const pthread_mutexattr t *);
int
int
      pthread mutex destroy(pthread mutex t *);
      pthread mutex lock(pthread mutex t *);
int
int
      pthread mutex unlock(pthread mutex t *);
      pthread rwlock init(pthread rwlock t *,
int
          const pthread rwlockattr t *);
      pthread rwlock destroy(pthread rwlock t *);
int
int
      pthread rwlock rdlock(pthread rwlock t *);
int
      pthread rwlock wrlock(pthread rwlock t *);
      pthread rwlock unlock(pthread rwlock t *);
int
```

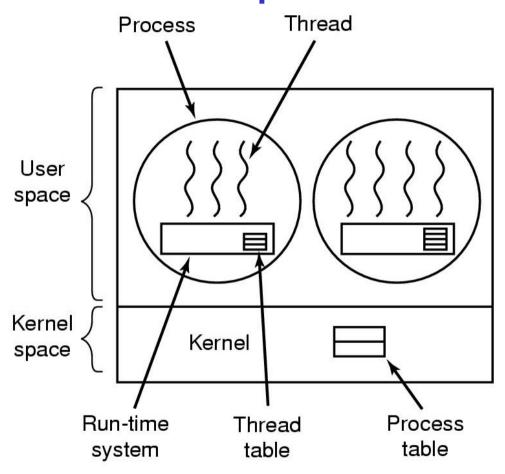


Where to Implement Application
Threads?





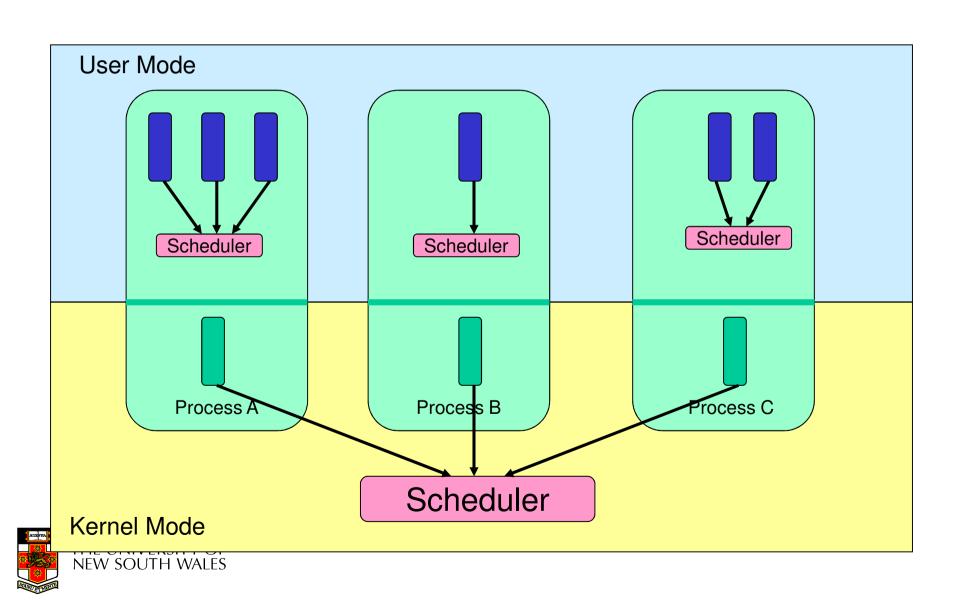
Implementing Threads in User Space



A user-level threads package



User-level Threads



User-level Threads

- Implementation at user-level
 - User-level Thread Control Block (TCB), ready queue, blocked queue, and dispatcher
 - Kernel has no knowledge of the threads (it only sees a single process)
 - If a thread blocks waiting for a resource held by another thread, its state is saved and the dispatcher switches to another ready thread
 - Thread management (create, exit, yield, wait)
 are implemented in a runtime support library



User-Level Threads

Pros

- Thread management and switching at user level is much faster than doing it in kernel level
 - No need to trap (take syscall exception) into kernel and back to switch
- Dispatcher algorithm can be tuned to the application
 - E.g. use priorities
- Can be implemented on any OS (thread or non-thread aware)
- Can easily support massive numbers of threads on a perapplication basis
 - Use normal application virtual memory
 - Kernel memory more constrained. Difficult to efficiently support wildly differing numbers of threads for different applications.



User-level Threads

- Cons
 - Threads have to yield() manually (no timer interrupt delivery to user-level)
 - Co-operative multithreading
 - A single poorly design/implemented thread can monopolise the available CPU time
 - There are work-arounds (e.g. a timer signal per second to enable pre-emptive multithreading), they are course grain and a kludge.
 - Does not take advantage of multiple CPUs (in reality, we still have a single threaded process as far as the kernel is concerned)



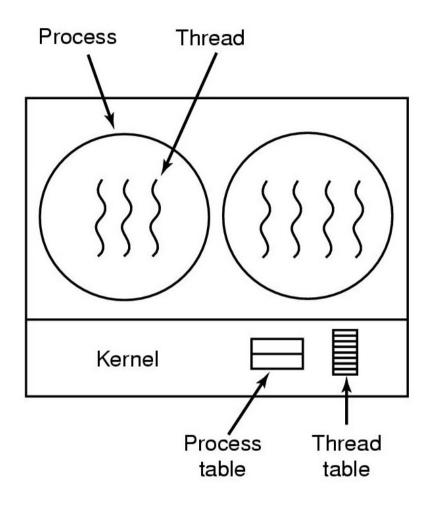
User-Level Threads

Cons

- If a thread makes a blocking system call (or takes a page fault),
 the process (and all the internal threads) blocks
 - Can't overlap I/O with computation



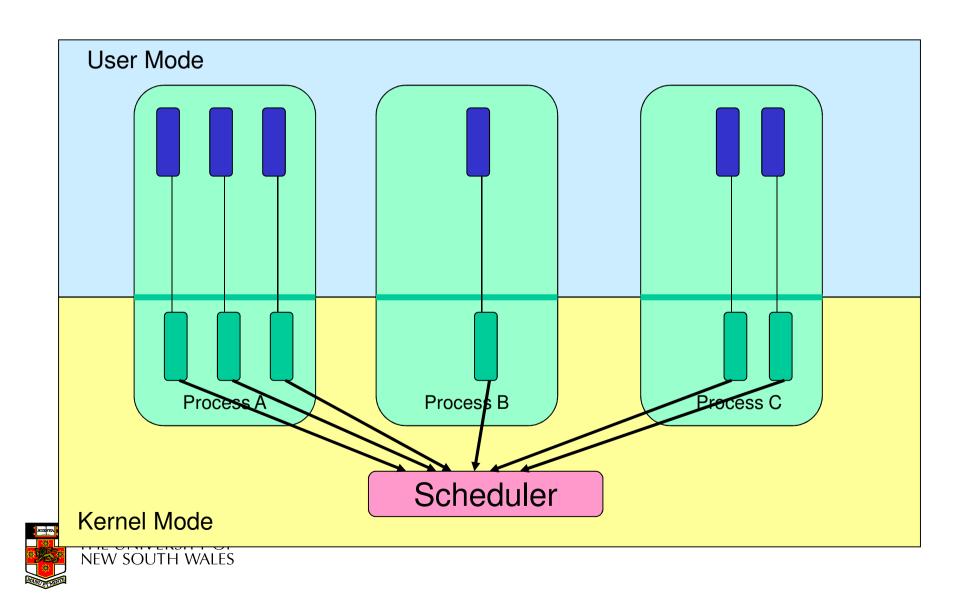
Implementing Threads in the Kernel



A threads package managed by the kernel



Kernel-Level Threads



Kernel Threads

- Threads are implemented in the kernel
 - TCBs are stored in the kernel
 - A subset of information in a traditional PCB
 - The subset related to execution context
 - TCBs have a PCB associated with them
 - Resources associated with the group of threads (the process)
 - Thread management calls are implemented as system calls
 - E.g. create, wait, exit



Kernel Threads

Cons

- Thread creation and destruction, and blocking and unblocking threads requires kernel entry and exit.
 - More expensive than user-level equivalent

Pros

- Preemptive multithreading
- Parallelism
 - Can overlap blocking I/O with computation
 - Can take advantage of a multiprocessor



Multiprogramming Implementation

- 1. Hardware stacks program counter, etc.
- 2. Hardware loads new program counter from interrupt vector.
- 3. Assembly language procedure saves registers.
- 4. Assembly language procedure sets up new stack.
- 5. C interrupt service runs (typically reads and buffers input).
- 6. Scheduler decides which process is to run next.
- 7. C procedure returns to the assembly code.
- 8. Assembly language procedure starts up new current process.

Skeleton of what lowest level of OS does when an interrupt occurs – a context switch



Context Switch Terminology

- A context switch can refer to
 - A switch between threads
 - Involving saving and restoring of state associated with a thread
 - A switch between processes
 - Involving the above, plus extra state associated with a process.
 - E.g. memory maps



Context Switch Occurrence

- A switch between process/threads can happen any time the OS is invoked
 - On a system call
 - Mandatory if system call blocks or on exit();
 - On an exception
 - Mandatory if offender is killed
 - On an interrupt
 - Triggering a dispatch is the main purpose of the timer interrupt

A thread switch can happen between any two instructions

Note instructions do not equal program statements



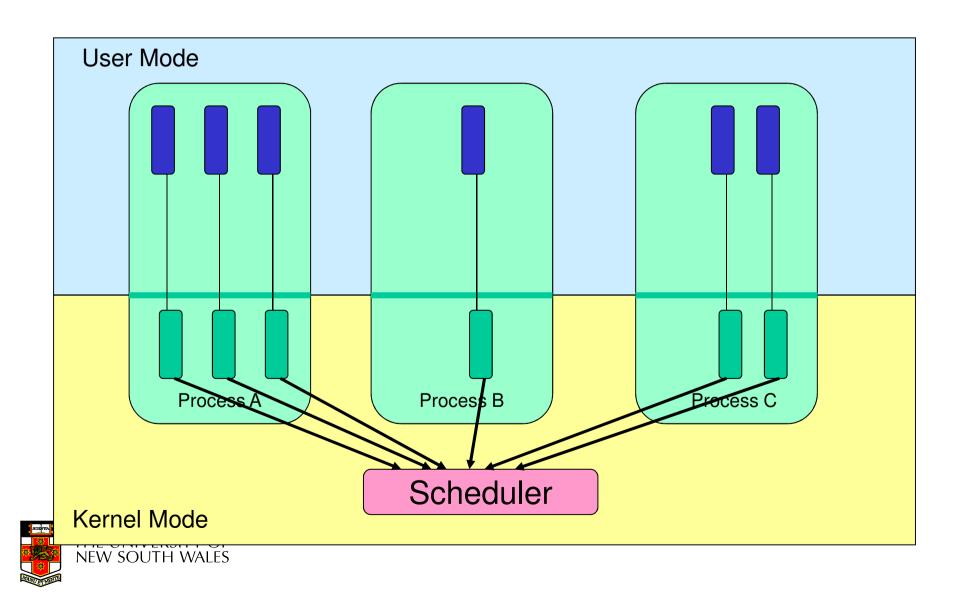
Context Switch

- Context switch must be transparent for processes/threads
 - When dispatched again, process/thread should not notice that something else was running in the meantime (except for elapsed time)
- ⇒OS must save all state that affects the thread
- This state is called the *process/thread context*
- Switching between process/threads consequently results in a *context switch*.

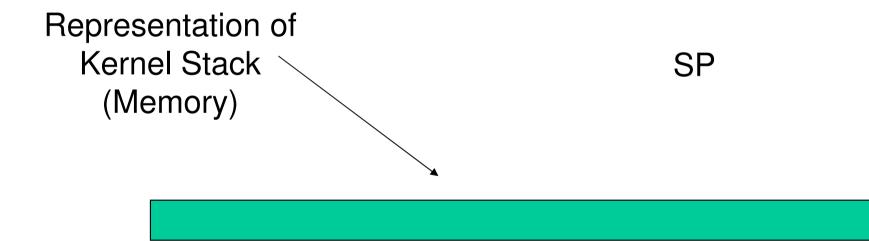


Simplified Explicit Thread Switch

Assume Kernel-Level Threads



 Running in user mode, SP points to userlevel stack (not shown on slide)





 Take an exception, syscall, or interrupt, and we switch to the kernel stack



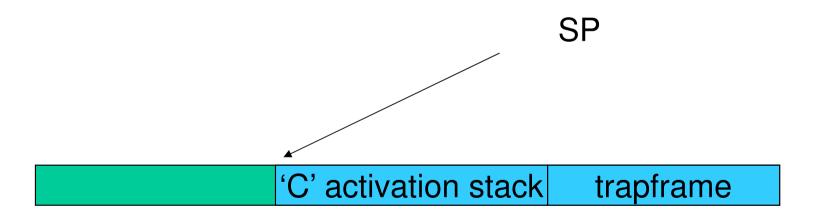


- We push a *trapframe* on the stack
 - Also called exception frame, user-level context....
 - Includes the user-level PC and SP



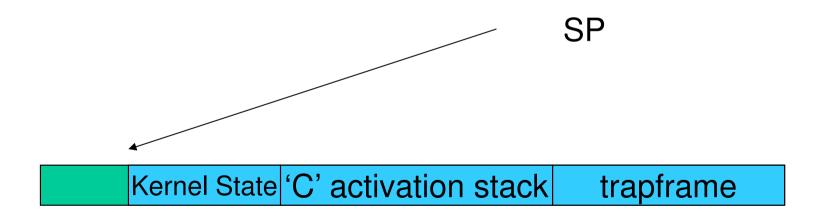


- Call 'C' code to process syscall, exception, or interrupt
 - Results in a 'C' activation stack building up



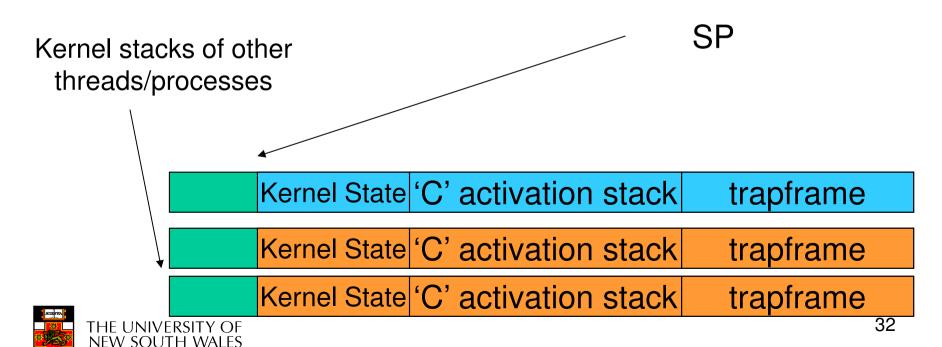


- The kernel decides to perform a context switch
 - It chooses a target thread (or process)
 - It pushes remaining kernel context onto the stack





- Any other existing thread must
 - be in kernel mode (on a uni processor),
 - and have a similar stack layout to the stack we are currently using

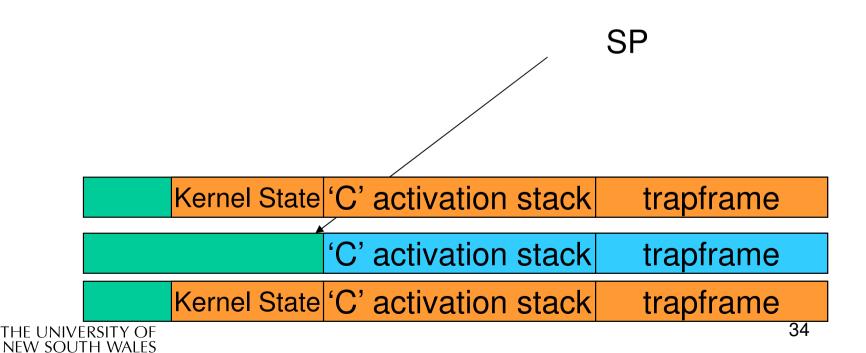


- We save the current SP in the PCB (or TCB), and load the SP of the target thread.
 - Thus we have switched contexts

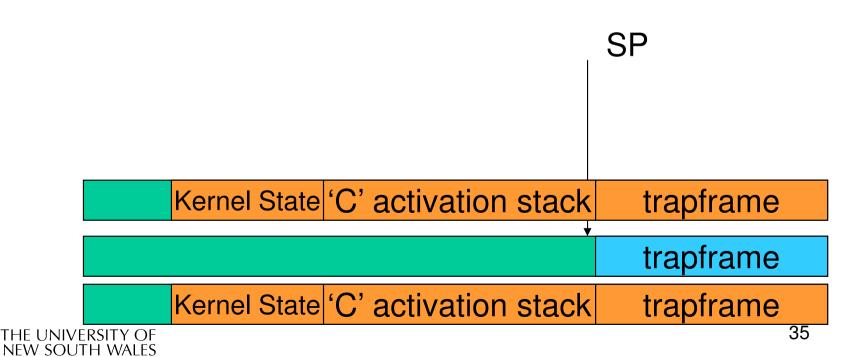
	SP		
	Kernel State	'C' activation stack	trapframe
	Kernel State	'C' activation stack	trapframe
VERSITY OF	Kernel State	'C' activation stack	trapframe



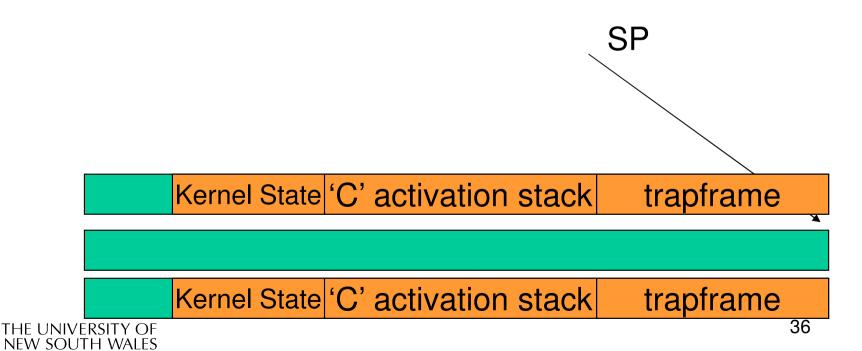
 Load the target thread's previous context, and return to C



 The C continues and (in this example) returns to user mode.



The user-level context is restored



The user-level SP is restored

SP

Kernel State 'C' activation stack trapframe

Kernel State 'C' activation stack trapframe



The Interesting Part of a Thread Switch

 What does the "push kernel state" part do???

SP

Kernel State 'C' activation stack trapframe

Kernel State 'C' activation stack trapframe



Simplified OS/161 thread_switch

```
static
void
thread_switch(threadstate_t newstate, struct wchan *wc)
struct thread *cur, *next;
cur = curthread;
do {
   next = threadlist_remhead(&curcpu->c_runqueue);
   if (next == NULL) {
        cpu idle();
} while (next == NULL);
/* do the switch (in assembler in switch.S) */
switchframe switch(&cur->t context, &next->t context);
```

Lots of code removed – only basics of pick next thread and run it remain



switchframe switch:

```
* a0 contains the address of the switchframe pointer in the old thread.
* a1 contains the address of the switchframe pointer in the new thread.
* The switchframe pointer is really the stack pointer. The other
* registers get saved on the stack, namely:
    s0-s6. s8
    gp, ra
* The order must match <mips/switchframe.h>.
* Note that while we'd ordinarily need to save $7 too, because we
* use it to hold curthread saving it would interfere with the way
* curthread is managed by thread.c. So we'll just let thread.c
* manage it.
```



```
/* Allocate stack space for saving 10 registers. 10*4 = 40 */
addi sp, sp, -40
                                               Save the registers
/* Save the registers */
sw ra, 36(sp)
                                                     that the 'C'
sw gp, 32(sp)
                                                procedure calling
sw s8, 28(sp)
sw s6, 24(sp)
                                                     convention
sw s5, 20(sp)
                                                       expects
sw s4, 16(sp)
                                                      preserved
sw s3, 12(sp)
sw s2, 8(sp)
sw s1, 4(sp)
sw s0, 0(sp)
/* Store the old stack pointer in the old thread */
sw sp, 0(a0)
```



```
/* Get the new stack pointer from the new thread */
lw sp, 0(a1)
          /* delay slot for load */
nop
/* Now, restore the registers */
lw s0, 0(sp)
lw s1, 4(sp)
lw s2, 8(sp)
lw s3, 12(sp)
lw s4, 16(sp)
lw s5, 20(sp)
lw s6, 24(sp)
lw s8, 28(sp)
lw gp, 32(sp)
lw ra, 36(sp)
              /* delay slot for load */
nop
```



```
/* and return. */
j ra
addi sp, sp, 40 /* in delay slot */
```



Thread a Thread b Revisiting **Thread Switch** switchframe_switch(a,b) -switchframe_switch(b,a) switchframe_switch(a,b)

