



COMP4161: Advanced Topics in Software Verification

# HOL

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# Last time...



- natural deduction rules for  $\wedge$ ,  $\vee$ ,  $\longrightarrow$ ,  $\neg$ , iff...
- proof by assumption, by intro rule, elim rule
- safe and unsafe rules
- indent your proofs! (one space per subgoal)
- prefer implicit backtracking (chaining) or *rule\_tac*, instead of *back*
- *prefer* and *defer*
- *oops* and *sorry*

# Content



- Intro & motivation, getting started [1]
- Foundations & Principles
  - Lambda Calculus, natural deduction [1,2]
  - Higher Order Logic, Isar (part 1) [3<sup>a</sup>]
  - Term rewriting [4]
- Proof & Specification Techniques
  - Inductively defined sets, rule induction [5]
  - Datatypes, recursion, induction, Isar (part 2) [6, 7<sup>b</sup>]
  - Hoare logic, proofs about programs, invariants [8]
  - C verification [9]
  - Practice, questions, exam prep [10<sup>c</sup>]

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<sup>a</sup>a1 due; <sup>b</sup>a2 due; <sup>c</sup>a3 due

# Quantifiers

- Scope of parameters: whole subgoal
- Scope of  $\forall, \exists, \dots$ : ends with ; or  $\implies$

## Example:

$$\bigwedge x y. \llbracket \forall y. P y \longrightarrow Q z y; \quad Q x y \rrbracket \implies \exists x. Q x y$$

means

$$\bigwedge x y. \llbracket (\forall y_1. P y_1 \longrightarrow Q z y_1); \quad Q x y \rrbracket \implies (\exists x_1. Q x_1 y)$$

# Natural deduction for quantifiers

$$\frac{\bigwedge x. P\ x}{\forall x. P\ x} \text{ allI}$$

$$\frac{\forall x. P\ x \quad P\ ?x \implies R}{R} \text{ allE}$$

$$\frac{P\ ?x}{\exists x. P\ x} \text{ exI}$$

$$\frac{\exists x. P\ x \quad \bigwedge x. P\ x \implies R}{R} \text{ exE}$$

- **allI** and **exE** introduce new parameters ( $\bigwedge x$ ).
- **allE** and **exI** introduce new unknowns ( $?x$ ).

# Instantiating Rules



**apply** (rule\_tac  $x = \text{"term"}$  in *rule*)

Like **rule**, but  $?x$  in *rule* is instantiated by *term* before application.

Similar: **erule\_tac**

**!**  $x$  is in *rule*, not in goal **!**

# Two Successful Proofs



$$1. \forall x. \exists y. x = y$$

**apply** (rule allI)

$$1. \bigwedge x. \exists y. x = y$$

best practice

**apply** (rule\_tac x = "x" in exI)

$$1. \bigwedge x. x = x$$

**apply** (rule refl)

**simpler & clearer**

exploration

**apply** (rule exI)

$$1. \bigwedge x. x = ?y \ x$$

**apply** (rule refl)

$$?y \mapsto \lambda u. u$$

**shorter & trickier**



# Two Unsuccessful Proofs



$$1. \exists y. \forall x. x = y$$

**apply** (rule\_tac  $x = ???$  in ex1)

**apply** (rule ex1)

$$1. \forall x. x = ?y$$

**apply** (rule all1)

$$1. \bigwedge x. x = ?y$$

**apply** (rule refl)

$$?y \mapsto x \text{ yields } \bigwedge x'. x' = x$$

**Principle:**

$?f\ x_1 \dots x_n$  **can only be replaced by term  $t$**

**if**  $params(t) \subseteq x_1, \dots, x_n$

# Safe and Unsafe Rules



Safe allI, exE

Unsafe allE, exI

**Create parameters first, unknowns later**

# Demo: Quantifier Proofs

# Parameter names



Parameter names are chosen by Isabelle

1.  $\forall x. \exists y. x = y$

**apply** (rule allI)

1.  $\bigwedge x. \exists y. x = y$

**apply** (rule\_tac x = "x" in exI)

**Brittle!**

# Renaming parameters



1.  $\forall x. \exists y. x = y$

**apply** (rule allI)

1.  $\bigwedge x. \exists y. x = y$

**apply** (rename\_tac N)

1.  $\bigwedge N. \exists y. N = y$

**apply** (rule\_tac x = "N" in exI)

**In general:**

**(rename\_tac  $x_1 \dots x_n$ )** renames the rightmost (inner)  $n$  parameters to  $x_1 \dots x_n$

# Forward Proof: frule and drule



**apply** (frule < rule >)

Rule:  $\llbracket A_1; \dots; A_m \rrbracket \implies A$

Subgoal: 1.  $\llbracket B_1; \dots; B_n \rrbracket \implies C$

Substitution:  $\sigma(B_i) \equiv \sigma(A_1)$

New subgoals: 1.  $\sigma(\llbracket B_1; \dots; B_n \rrbracket \implies A_2)$

$\vdots$

m-1.  $\sigma(\llbracket B_1; \dots; B_n \rrbracket \implies A_m)$

m.  $\sigma(\llbracket B_1; \dots; B_n; A \rrbracket \implies C)$

Like **frule** but also deletes  $B_i$ : **apply** (drule < rule >)

# Examples for Forward Rules

$$\frac{P \wedge Q}{P} \text{ conjunct1} \quad \frac{P \wedge Q}{Q} \text{ conjunct2}$$

$$\frac{P \longrightarrow Q \quad P}{Q} \text{ mp}$$

$$\frac{\forall x. P \ x}{P \ ?_x} \text{ spec}$$

# Forward Proof: OF



$$r \text{ [OF } r_1 \dots r_n]$$

*Prove assumption 1 of theorem  $r$  with theorem  $r_1$ , and assumption 2 with theorem  $r_2$ , and ...*

$$\text{Rule } r \quad \llbracket A_1; \dots; A_m \rrbracket \Longrightarrow A$$

$$\text{Rule } r_1 \quad \llbracket B_1; \dots; B_n \rrbracket \Longrightarrow B$$

$$\text{Substitution} \quad \sigma(B) \equiv \sigma(A_1)$$

$$r \text{ [OF } r_1] \quad \sigma(\llbracket B_1; \dots; B_n; A_2; \dots; A_m \rrbracket \Longrightarrow A)$$



# Forward proofs: THEN



$r_1$  [THEN  $r_2$ ] means  $r_2$  [OF  $r_1$ ]

# Demo: Forward Proofs

# Hilbert's Epsilon Operator



(David Hilbert, 1862-1943)

$\varepsilon x. P x$  is a value that satisfies  $P$  (if such a value exists)

$\varepsilon$  also known as **description operator**.

In Isabelle the  $\varepsilon$ -operator is written  $\text{SOME } x. P x$

$$\frac{P ?_x}{P (\text{SOME } x. P x)} \text{ someI}$$

# More Epsilon



$\varepsilon$  implies Axiom of Choice:

$$\forall x. \exists y. Q\ x\ y \implies \exists f. \forall x. Q\ x\ (f\ x)$$

Existential and universal quantification can be defined with  $\varepsilon$ .

Isabelle also knows the definite description operator **THE** (aka  $\iota$ ):

$$\frac{}{(\text{THE } x. x = a) = a} \text{the\_eq\_trivial}$$

# Some Automation



## More Proof Methods:

**apply** (intro <intro-rules>) repeatedly applies intro rules

**apply** (elim <elim-rules>) repeatedly applies elim rules

**apply** clarify  
applies all safe rules  
that do not split the goal

**apply** safe  
applies all safe rules

**apply** blast  
an automatic tableaux prover  
(works well on predicate logic)

**apply** fast  
another automatic search tactic

# Epsilon and Automation Demo

# We have learned so far...



- Proof rules for predicate calculus
- Safe and unsafe rules
- Forward Proof
- The Epsilon Operator
- Some automation

# Isar (Part 1)

A Language for Structured Proofs



# Motivation



Is this true:  $(A \longrightarrow B) = (B \vee \neg A)$  ?

# Motivation



Is this true:  $(A \longrightarrow B) = (B \vee \neg A)$  ?

YES!

```
apply (rule iffI)
  apply (cases A)
    apply (rule disjI1)
      apply (erule impE)
        apply assumption
      apply assumption
    apply (rule disjI2)
      apply assumption
    apply (rule impI)
      apply (erule disjE)
        apply assumption
      apply (erule notE)
        apply assumption
    done
```

or by blast

OK it's true. But WHY?

# Motivation



WHY is this true:  $(A \longrightarrow B) = (B \vee \neg A)$  ?

Demo

## apply scripts

- unreadable
- hard to maintain
- do not scale

**No structure.**

## What about..

- Elegance?
- Explaining deeper insights?
- Large developments?

**Isar!**

# A typical Isar proof



```
proof
  assume formula0
  have formula1    by simp
  ⋮
  have formulan    by blast
  show formulan+1 by ...
qed
```

proves  $\textit{formula}_0 \implies \textit{formula}_{n+1}$

(analogous to **assumes**/**shows** in lemma statements)

# Isar core syntax



proof = **proof** [method] statement\* **qed**  
| **by** method

method = (simp ...) | (blast ...) | (rule ...) | ...

statement = **fix** variables ( $\wedge$ )  
| **assume** proposition ( $\implies$ )  
| [**from** name<sup>+</sup>] (**have** | **show**) proposition proof  
| **next** (separates subgoals)

proposition = [name:] formula

# proof and qed



**proof** [method] statement\* **qed**

**lemma** " $\llbracket A; B \rrbracket \implies A \wedge B$ "

**proof** (rule conjI)

**assume** A: "A"

**from** A **show** "A" **by** assumption

**next**

**assume** B: "B"

**from** B **show** "B" **by** assumption

**qed**

- **proof** (<method>)   applies method to the stated goal
- **proof**               applies a single rule that fits
- **proof** -             does nothing to the goal

# How do I know what to Assume and Show?



**Look at the proof state!**

**lemma** " $\llbracket A; B \rrbracket \implies A \wedge B$ "

**proof** (rule conjI)

- **proof** (rule conjI) changes proof state to
  1.  $\llbracket A; B \rrbracket \implies A$
  2.  $\llbracket A; B \rrbracket \implies B$
- so we need 2 shows: **show** " $A$ " and **show** " $B$ "
- We are allowed to **assume**  $A$ ,  
because  $A$  is in the assumptions of the proof state.



# The Three Modes of Isar



- **[prove]**:  
goal has been stated, proof needs to follow.
- **[state]**:  
proof block has opened or subgoal has been proved,  
new *from* statement, goal statement or assumptions can follow.
- **[chain]**:  
*from* statement has been made, goal statement needs to follow.

lemma "  $\llbracket A; B \rrbracket \implies A \wedge B$ " **[prove]**

proof (rule conjI) **[state]**

  assume A: "A" **[state]**

  from A **[chain]** show "A" **[prove]** by assumption **[state]**

next **[state]** ...

# Have



Can be used to make intermediate steps.

**Example:**

**lemma** " $(x :: \text{nat}) + 1 = 1 + x$ "

**proof** -

**have** A: " $x + 1 = \text{Suc } x$ " **by** simp

**have** B: " $1 + x = \text{Suc } x$ " **by** simp

**show** " $x + 1 = 1 + x$ " **by** (simp only: A B)

**qed**

# Demo

# Backward and Forward



**Backward reasoning: ... have " $A \wedge B$ " proof**

- **proof** picks an **intro** rule automatically
- conclusion of rule must unify with  $A \wedge B$

**Forward reasoning: ...**

**assume AB: " $A \wedge B$ "**

**from AB have "... " proof**

- now **proof** picks an **elim** rule automatically
- triggered by **from**
- first assumption of rule must unify with AB

**General case: from  $A_1 \dots A_n$  have  $R$  proof**

- first  $n$  assumptions of rule must unify with  $A_1 \dots A_n$
- conclusion of rule must unify with  $R$

# Fix and Obtain



**fix**  $v_1 \dots v_n$

Introduces new arbitrary but fixed variables  
( $\sim$  parameters,  $\wedge$ )

**obtain**  $v_1 \dots v_n$  **where**  $\langle \text{prop} \rangle \langle \text{proof} \rangle$

Introduces new variables together with property

# Demo

# Fancy Abbreviations



this = the previous fact proved or assumed

**then** = **from** this

**thus** = **then show**

**hence** = **then have**

**with**  $A_1 \dots A_n$  = **from**  $A_1 \dots A_n$  this

**?thesis** = the last enclosing goal statement

# Moreover and Ultimately



have  $X_1: P_1 \dots$

have  $X_2: P_2 \dots$

$\vdots$

have  $X_n: P_n \dots$

from  $X_1 \dots X_n$  show  $\dots$

have  $P_1 \dots$

**moreover** have  $P_2 \dots$

$\vdots$

**moreover** have  $P_n \dots$

**ultimately** show  $\dots$

wastes lots of brain power  
on names  $X_1 \dots X_n$



# General Case Distinctions



**show** *formula*

**proof** -

**have**  $P_1 \vee P_2 \vee P_3$  <proof>

**moreover** { **assume**  $P_1$  ... **have** ?thesis <proof> }

**moreover** { **assume**  $P_2$  ... **have** ?thesis <proof> }

**moreover** { **assume**  $P_3$  ... **have** ?thesis <proof> }

**ultimately show** ?thesis **by** blast

**qed**

{ ... } is a proof block similar to **proof** ... **qed**

{ **assume**  $P_1$  ... **have**  $P$  <proof> }

stands for  $P_1 \implies P$

# Mixing proof styles



```
from ...  
have ...  
  apply -      make incoming facts assumptions  
  apply (...)  
  :  
  apply (...)  
done
```

# We have learned so far...



- Isar style proofs
- proof, qed
- assumes, shows
- fix, obtain
- moreover, ultimately
- forward, backward
- mixing proof styles