



COMP4161: Advanced Topics in Software Verification

$\{P\} \dots \{Q\}$

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Last Time

- Syntax of a simple imperative language
- Operational semantics
- Program proof on operational semantics
- Hoare logic rules
- Soundness of Hoare logic

Content

→ Foundations & Principles

- Intro, Lambda calculus, natural deduction [1,2]
- Higher Order Logic, Isar (part 1) [2,3^a]
- Term rewriting [3,4]

→ Proof & Specification Techniques

- Inductively defined sets, rule induction, datatype induction, primitive recursion [4,5]
- General recursive functions, termination proofs [7^b]
- Proof automation, Hoare logic, proofs about programs, invariants [8]
- C verification [9,10]
- Practice, questions, exam prep [10^c]

^aa1 due; ^ba2 due; ^ca3 due

Automation?

Last time: Hoare rule application is nicer than using operational semantic.

BUT:

- it's still kind of tedious
- it seems boring & mechanical

Automation?

Invariant

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Example:

$$\begin{array}{l} \{M = 0 \wedge N = 0\} \\ \text{WHILE } M \neq a \text{ INV } \{N = M * b\} \text{ DO } N := N + b; M := M + 1 \text{ OD} \\ \{N = a * b\} \end{array}$$

Weakest Preconditions

pre c Q = weakest P such that $\{P\} c \{Q\}$

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pre $(c_1; c_2)$ Q	=	pre c_1 (pre c_2 Q)
pre (IF b THEN c_1 ELSE c_2) Q	=	

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$\text{vc } (\text{IF } b \ \text{THEN } c_1 \ \text{ELSE } c_2) \ Q$	=	$\text{vc } c_1 \ Q \wedge \text{vc } c_2 \ Q$

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$$\text{vc } c \ Q \wedge (P \Longrightarrow \text{pre } c \ Q) \Longrightarrow \{P\} \ c \ \{Q\}$$

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- $x := \lambda\sigma. 1$ instead of $x := 1$ sucks
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 - works well if you state full program and only use vcg

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- declare program variables with each Hoare triple
 - nice, usual syntax
 - works well if you state full program and only use vcg
- separate program variables from Hoare triple (use extensible records), indicate usage as function syntactically
 - more syntactic overhead
 - program pieces compose nicely

Demo

Arrays

Depending on language, model arrays as functions:

→ Array access = function application:

$$a[i] = a\ i$$

→ Array update = function update:

$$a[i] ::= v = a ::= a(i := v)$$

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Use lists to express length:

- Array access = nth:
 $a[i] = a\ !\ i$
- Array update = list update:
 $a[i] ::= v = a ::= a[i := v]$
- Array length = list length:
 $a.length = \text{length } a$

Pointers

Choice 1

datatype ref = Ref int | Null

types heap = int \Rightarrow val

datatype val = Int int | Bool bool | Struct_x int int bool | ...

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→ hp :: heap, p :: ref

→ Pointer access: *p = the_Int (hp (the_addr p))

→ Pointer update: *p ::= v = hp ::= hp ((the_addr p) := v)

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datatype ref = Ref int | Null

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→ Pointer access: *p = the_Int (hp (the_addr p))

→ Pointer update: *p ::= v = hp ::= hp ((the_addr p) := v)

→ a bit klunky

→ gets even worse with structs

→ lots of value extraction (the_Int) in spec and program

Pointers

Choice 2 (Burstall '72, Bornat '00)

Example: struct with next pointer and element

datatype	ref	= Ref int Null
types	next_hp	= int \Rightarrow ref
types	elem_hp	= int \Rightarrow int

Pointers

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Example: struct with next pointer and element

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types next_hp = int \Rightarrow ref

types elem_hp = int \Rightarrow int

→ next :: next_hp, elem :: elem_hp, p :: ref

→ Pointer access: $p \rightarrow \text{next} = \text{next } (\text{the_addr } p)$

→ Pointer update: $p \rightarrow \text{next} ::= v = \text{next} ::= \text{next } ((\text{the_addr } p) ::= v)$

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In general:

→ a separate heap for each struct field

→ buys you $p \rightarrow \text{next} \neq p \rightarrow \text{elem}$ automatically (aliasing)

→ still assumes type safe language

Demo

We have seen today ...

- Weakest precondition
- Verification conditions
- Example program proofs
- Arrays, pointers