SCALABILITY, I/O AND ALL THAT AOS 2009.10.16

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Scalability

- Essentially the same kernel across wide range of hardware or not?
- Performance scales with hardware or does it?
Same kernel source, same core algorithms (in general); conditional compilation does change some features.
Phase Changes

- Processor change
- Uni → SMP
- UP → SMT
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- NUMA
- Cluster
Scalability Issues

- Number of Processors
- Number of Spindles
- Amount of Memory
- Power Consumption...
- Scalability depends on Workload
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IDEAL SCALABILITY
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**SYSTEM PERFORMANCE**

Throughput

Applied load

1 processor
The ideal system performance curve has three parts. At the left, throughput is determined by the rate at which work requests arrive; there is little or no queueing, and latency is governed by how long a job takes to do. In the middle, where the curve is, jobs sometimes arrive while a previous job is still running. Latency is governed by both the time a job takes, and the time it spends queued – which depends on how long previously queued jobs take. At the right of the curve, latency is determined almost entirely by queuing time; and throughput is determined solely by the time the server takes to do a job. In this state, one or more resources on the server are bottlenecked; removing the bottleneck will move the curve up and the bent part of the curve to the right.
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SYSTEM PERFORMANCE

Throughput

Latency

Applied load

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Gunther’s law:

\[ C(d) = \frac{d}{1 + \alpha(d - 1) + \beta d(d - 1)} \]

where:
- \( d \) is demand
- \( \alpha \) is the amount of serialisation: represents Amdahl’s law
- \( \beta \) is the contention in the system.
SCALABILITY CONSIDERATIONS

- On-chip cache (ns)
- Local L2 cache (10s of ns)
- Local RAM (100s of ns)
- Other processor’s cache (µs)
- Disc backing store (10s of ms)
SCALABILITY CONSIDERATIONS

Other factors

• Locking ‘grain’
• Interrupts — to one processor or to any?
• Disc and other I/O parallelism
• Cache fights
• TLB contention
NUMA

- Non-Uniform Memory Architecture
- Processors joined by a high speed network.
- Typically use hypercube or bristled hypercube topologies
- Nodes may be SMP (Compaq) or use crossbar (SGI)
- ccNUMA (cache-coherent NUMA) puts DSM in hardware.
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GOALS OF NUMA

1. Better performance at lower cost (two processors are cheaper than one twice-performance processor — and when the twice-performance processor is developed it can be plugged into the earlier architecture)

2. Hide architecture from user-mode programs

3. Scalable performance enhancement
NUMA CONCEPTS

RAD the Resource-affinity-domain, (aka ‘Cell’)

SMP Symmetric Multi-Processing — All processors have equal status

Master-Slave Some system calls, interrupts must run on Master processor.
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NUMA CONCEPTS

Hypercube etc
**NUMA CONCEPTS**

- ‘Bristled’ hypercube (e.g., SGI Altix).
- Plain hypercube (e.g., Compaq).
- $O(\sqrt[3]{n})$ hops for $n$ nodes.
- Each node has local memory.
- Some nodes have I/O (e.g., Disc, framebuffer, serial, parallel, etc).
- Clocks may be synchronised with NTP, or be delivered from a central master.
- Nodes may not be exactly homogeneous.
Origin 2000 Node architecture

Node 0

Proc A

Proc B

Mem DIR

Hub

I/O Xbar

Scalable Interconnect Network

Node 1

Node 512
Memory Hierarchy Re-visited

- On-chip cache (ns)
- Local L2 cache (10s of ns)
- Local RAM (100s of ns)
- Other local processor’s cache (µs)
- Remote processor’s RAM or cache (ms)
- Disc backing store (10s of ms)
**Processes have state**

- memory footprint
- parent
- PID
- queued signals
- open files
- network endpoints
PIDS

- Want a single global PID pool
- Can manage in two ways
  - Single pool-manager, used by all, or
  - Use RAD ID as part of PID.
- Either way need a globally-consistent mapping pid→proc struct
SCHEDULING AND DISPATCHING

- Memory switching is expensive
- Therefore try to schedule memory-sharing threads at the same time.
- Two approaches
  1. Gang Scheduling
  2. Job models
Dispatching

- Per-processor run queue
- Thread queued to same processor as last time
- Thread runs in same cell as last time, if possible.
- Otherwise either goes onto queue for idle processor, or onto global queue.
- At dispatch time, threads taken from local pushback queue, or per-processor queue or global queue.
Gang Scheduling

- Threads run in a memory space
- Schedule memory spaces, let threads fend for themselves (RR or FIFO depending on user selection)
- Try to spread threads over ‘nearby’ cells.
SCHEDULING AND DISPATCHING

Job Currency scheduling

- SGI/Cray Irix concept
- ‘Job’ is set of threads+processes that are scheduled together.
- Each job given a ‘weight’ in proportion to priority
- At regular intervals, time is handed out to jobs in proportion to weights
- Jobs divided into ‘over entitlement’ and ‘under entitlement’
- Threads belonging to under-entitlement jobs have
higher pri than the rest: queue resorted on every scheduling interval

- Threads round robin within priority band
Job Currency Scheduling (cont)

• Scales to a few hundred processors only!
• Not as good as gang for many purposes
• Needs combination with topology scheduler.
General Principles

- Locality of reference (use per-processor data area where appropriate)
- Replicate read-only data, including user Text segment for MT progs;
- use ‘const’ in kernel code; linker support for replicated RO-sections.
- Try to move shared elements ‘close’ to users; stripe shared memory.
- Use fine-grain MR-locks where appropriate
- Use fetch-and-op operations rather than locked sections
where possible.
Cache-Friendly Data Layout

- Group data in cache blocks by usage
- Keep data consumers to the minimum
  - per thread
  - per processor
  - per proc
  - per proc
  - Replicate read-mostly data
More general guidelines:

- Keep differently locked-data in different cache blocks.
- Group read-mostly data into a single cache-block.
- Put read-write data in the same cache block as its lock.
- Group data according to how frequently it is accessed.
- Minimise number of cache blocks for most frequent code paths.
TopoLocation Scheduling

(e.g., SGI’s ‘Miser’ program, Compaq’s Processor Sets)

- Reserve RADs for particular job(s)
- Can reserve nearby memory in other RADs as well if nec.
- (pinning, processor sets)
Some Conclusions

- Can get scalable performance out of ccNUMA
- Needs careful attention to detail in OS
- Tuning for one architecture can break others.
REFERENCES

- Schimmel, ‘Unix Systems for Modern Architectures’
SCALABILITY IN PRACTICE

RX2600, OSDL’s reimplementation of AIM7
On an HP RX2600 with two processors, the OSDL Aim7 benchmark is perfectly scalable.
Altix, single spindle
But on the Altix, the scalability is awful. What’s going wrong? We don’t have access as root (borrowed machine from UWaterloo), and may not install our own instrumented kernels to see what’s going on, so let’s speculate that there’s an I/O problem (as we know the benchmark scales with processors on an SMP machine), and try with a faster disc:
Altix, RAID
Better, but we still don’t see the near-perfect scalability we expect. So try with a ram-disk:
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SCALABILITY IN PRACTICE

Altix, RAM disk, ext3

Jobs Per Minute

Number of clients

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SCALABILITY, I/O AND ALL THAT...
Even here there is a problem. It looks like there’s a major problem in the I/O subsystem on a NUMA machine in Linux 2.4.21-sgi.
2.6, HP Olympia, CPU-only load
So let’s try 2.6.11, on an HP Olympia with 12 processors spread across 4 nodes. Again, a CPU-intensive, no Disk I/O workload shows reasonable scalability with number of processors.
Disk Intensive workload, tmpfs
This shows very poor scalability. The 12-way actually performs worse than the 8-way.
Analysis

- Microstate Accounting
- q-syscollect
- Lock Metering
Microstate accounting showed much time on the CPU; `q-syscollect` showed much time in `ia64_spinlock_contention`, so we ran with lockmetering:
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**Scalability in Practice**

<table>
<thead>
<tr>
<th>SPINLOCKS</th>
<th>HOLD</th>
<th>WAIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>UTIL</td>
<td>CON</td>
<td>MEAN (MAX)</td>
</tr>
<tr>
<td>72.3%</td>
<td>13.1%</td>
<td>0.5us (9.5us)</td>
</tr>
<tr>
<td>find_lock_page+0x30</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.01%</td>
<td>85.3%</td>
<td>1.7us (6.2us)</td>
</tr>
<tr>
<td>find_lock_page+0x130</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
struct page *find_lock_page(struct address_space *mapping,
                           unsigned long offset)
{
    struct page *page;
    spin_lock_irq(&mapping->tree_lock);

    repeat:
    page = radix_tree_lookup(&mapping->page_tree, offset);
    if (page) {
        page_cache_get(page);
        if (TestSetPageLocked(page)) {
            spin_unlock_irq(&mapping->tree_lock);
            lock_page(page);
            spin_lock_irq(&mapping->tree_lock);
        }
    }
    ...
So let’s replace the spinlock with a rwlock...
Disk-intensive workload, tmpfs, rwlock

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Scalability in Practice

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Scalability, I/O and all that...
And bingo, it scales much better.
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SCALABILITY IN PRACTICE

- Slope still positive
  - Spare capacity available
  - Latency a problem
SCALABILITY IN PRACTICE

Other File Systems On Ram disk

ext3

xfs

<table>
<thead>
<tr>
<th>Number of Clients</th>
<th>Jobs per Minute</th>
</tr>
</thead>
<tbody>
<tr>
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<td>0</td>
</tr>
<tr>
<td>10</td>
<td>2000</td>
</tr>
<tr>
<td>20</td>
<td>4000</td>
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<tr>
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<td>6000</td>
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<tr>
<td>40</td>
<td>8000</td>
</tr>
<tr>
<td>50</td>
<td>10000</td>
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<td>50</td>
<td>25000</td>
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<td>60</td>
<td>30000</td>
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<td>40000</td>
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<td>90</td>
<td>45000</td>
</tr>
<tr>
<td>100</td>
<td>50000</td>
</tr>
</tbody>
</table>
Microstate accounting output, ext3
Scalability in Practice

Scalability by spindles

ext3

xfs

Jobs per Minute

Number of Clients
TACKLING SCALABILITY PROBLEMS

- Find the bottleneck
- fix or work around it
- check performance doesn’t suffer too much on the low end.
- Experiment with different algorithms
INTERRUPTS

- Steal time from current process
- Therefore can cause negative scalability.
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INTERRUPTS
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Schedulers and Dispatchers

Diagram showing the flow from Dispatcher to Priorities (Pri_0 to Pri_4) and back to Scheduler.
Scheduler Classes

- Real-Time
- Time share schedulers
- Entitlement Schedulers
- Batch Schedulers
ISOCHRONOUS SCHEDULERS

- For Multi-Media apps
- Guarantee a proportion of the processor.
Dynamic Window CPU Scheduler (DWCS)
Entitlement Schedulers

- Aim to share resources in proportion to *entitlement*
- Shares
- Or proportions (must be < 100%)
- Feed-forward (e.g. Lottery scheduler)
- Feed-Back (e.g., Kay & Lauder 1988)
SHARES

- Allow entitlement holders to come and go.
- Each *user* is given shares
- Entitlement = \( \frac{S_u}{\sum_i S_i} \)
- where *i* runs over all active *users*.
SIMPLE ENTITLEMENT SCHEDULER
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**SIMPLE ENTITLEMENT SCHEDULER**

0*3 → 0*6 → 0*2
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**Simple Entitlement Scheduler**

- $0^3 \rightarrow 0^6 \rightarrow 0^2$
- $0^6 \rightarrow 0^2 \rightarrow 1^3$

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SIMPLE ENTITLEMENT SCHEDULER

\[ 0^3 \rightarrow 0^6 \rightarrow 0^2 \]
\[ 0^6 \rightarrow 0^2 \rightarrow 1^3 \]
\[ 0^2 \rightarrow 1^3 \rightarrow 1^6 \]
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**Simple Entitlement Scheduler**

- $0^3 \rightarrow 0^6 \rightarrow 0^2$
- $0^6 \rightarrow 0^2 \rightarrow 1^3$
- $0^2 \rightarrow 1^3 \rightarrow 1^6$
- $1^2 \rightarrow 1^3 \rightarrow 1^6$
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**SIMPLE ENTITLEMENT SCHEDULER**

```
0*3 -> 0*6 -> 0*2
0*6 -> 0*2 -> 1*3
0*2 -> 1*3 -> 1*6
1*2 -> 1*3 -> 1*6
1*3 -> 2*2 -> 1*6
```
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SIMPLE ENTITLEMENT SCHEDULER

- 0*3 → 0*6 → 0*2
- 0*6 → 0*2 → 1*3
- 0*2 → 1*3 → 1*6
- 1*2 → 1*3 → 1*6
- 1*3 → 2*2 → 1*6
- 2*2 → 1*6 → 2*3
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**Simple Entitlement Scheduler**

```
<table>
<thead>
<tr>
<th>0*3</th>
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</tr>
<tr>
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<td>1*6</td>
</tr>
<tr>
<td>2*2</td>
<td>1*6</td>
<td>2*3</td>
</tr>
</tbody>
</table>
```
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**Simple Entitlement Scheduler**

- \(0^3\) \(0^6\) \(0^2\)
- \(0^6\) \(0^2\) \(1^3\)
- \(0^2\) \(1^3\) \(1^6\)
- \(1^2\) \(1^3\) \(1^6\)
- \(1^3\) \(2^2\) \(1^6\)
- \(2^2\) \(1^6\) \(2^3\)

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PROBLEMS

- Infinities.
- Processes that sleep.
- Processes too low level.
LOTTERY SCHEDULERS

- Each entity has some tickets
- Randomly select a ticket at each decision point
- Entities get time in proportion to how many tickets they hold.
LOTTERY SCHEDULERS

P1 has 2 tickets

P2 has 3 tickets

P3 has one ticket
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INACTIVE ENTITY PROBLEM

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Inactive Entity Problem

- Need feedback loop
- Boost under-utilising processes
- Slow down over-utilising processes
- Can lead to starvation
Use Kalman estimator as usage

\[ u_i = \alpha u_{i-1} + (1 - \alpha) \rho \]

where the half life of the system is \( \frac{\ln 0.5}{\ln \alpha} \)

Can update once after multiple time steps:

\[ u_m = \alpha^{m-i} u_i + (1 - \alpha^n) + (1 - \alpha) \rho \]
• Priority is then $\frac{u}{\varepsilon}$ where $\varepsilon$ is entitlement.

• Hierarchical possible: $\varepsilon = \varepsilon_u \varepsilon_p \varepsilon_t$ providing
  \[ \forall x \in u, p, t : \sum_x \varepsilon_x = 1 \]
results:

- Patent granted
- Forms basis of ARMttech (used in Citrix).
- Earlier version in Solaris Resource Manager
- Free version was posted to LKML.
- Works very well, with low overhead.
Disks and File Systems

- heads, tracks, sectors
- seek is very expensive