



Linux, Locking and Lots of Processors

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A little bit of history

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 - File system model
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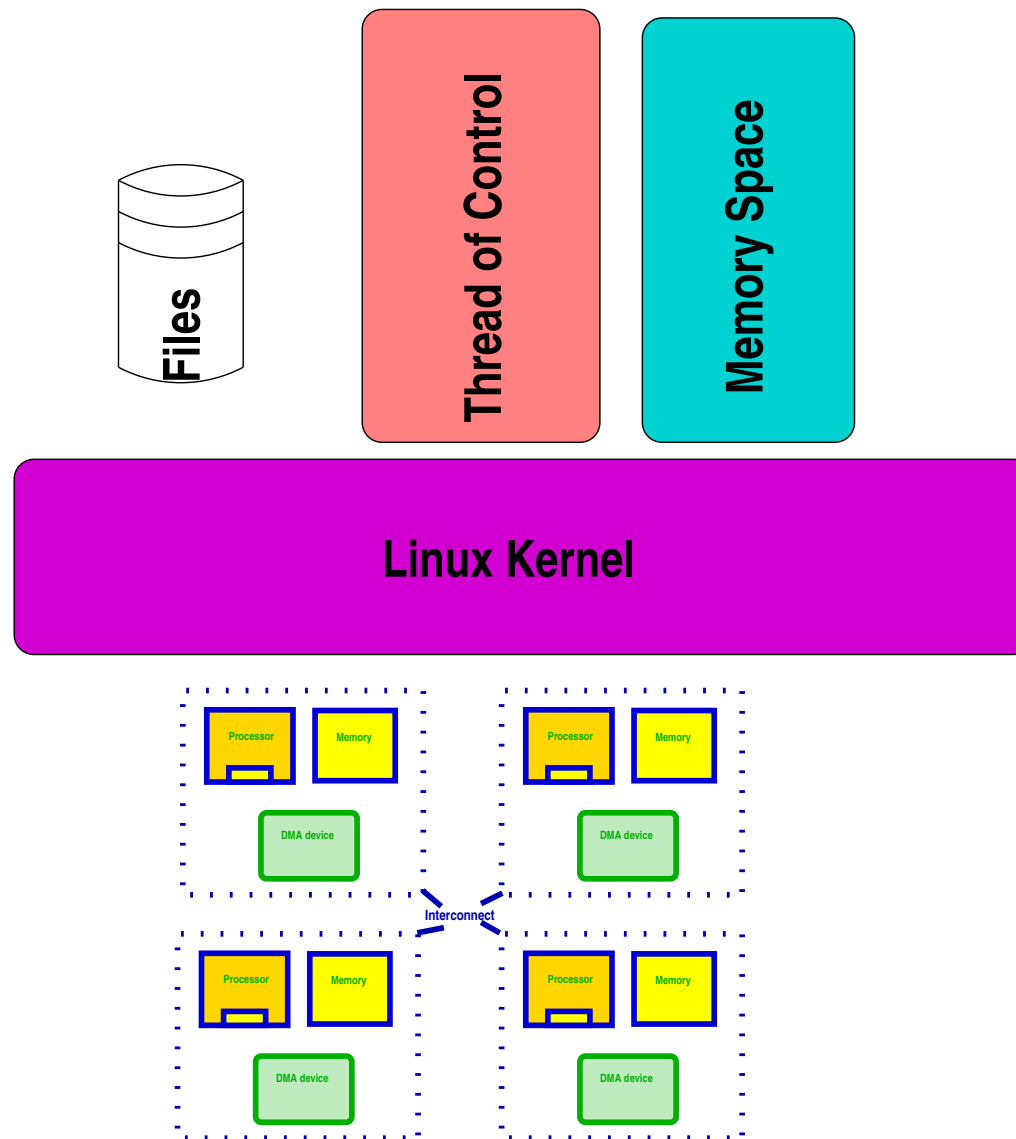
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 - Process model
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 - IPC
- Additions:
 - Paged virtual memory (3BSD, 1979)
 - TCP/IP Networking (BSD 4.1, 1983)
 - Multiprocessing (Vendor Unices such as Sequent's 'Balance', 1984)

Abstractions



Process model

- Root process (`init`)
- `fork()` creates (almost) exact copy
 - Much is shared with parent — Copy-On-Write avoids overmuch copying
- `exec()` overwrites memory image from a file

Process model

- Root process (`init`)
- `fork()` creates (almost) exact copy
 - Much is shared with parent — Copy-On-Write avoids overmuch copying
- `exec()` overwrites memory image from a file
- Allows a process to control what is shared

fork () and exec ()

- A process can clone itself by calling `fork ()`.
- Most attributes *copied*:
 - Address space (actually shared, marked copy-on-write)
 - current directory, current root
 - File descriptors
 - permissions, etc.
- Some attributes *shared*:
 - Memory segments marked **MAP_SHARED**
 - Open files

fork () and exec ()

Files and Processes:

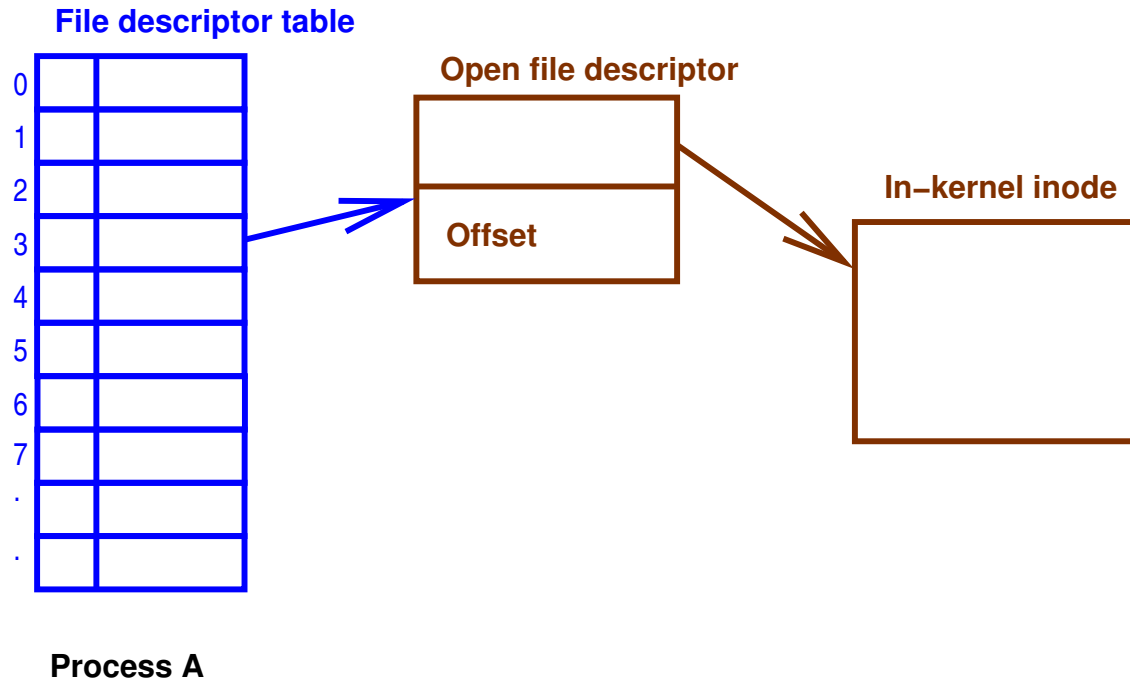
File descriptor table

0	
1	
2	
3	
4	
5	
6	
7	
·	
·	

Process A

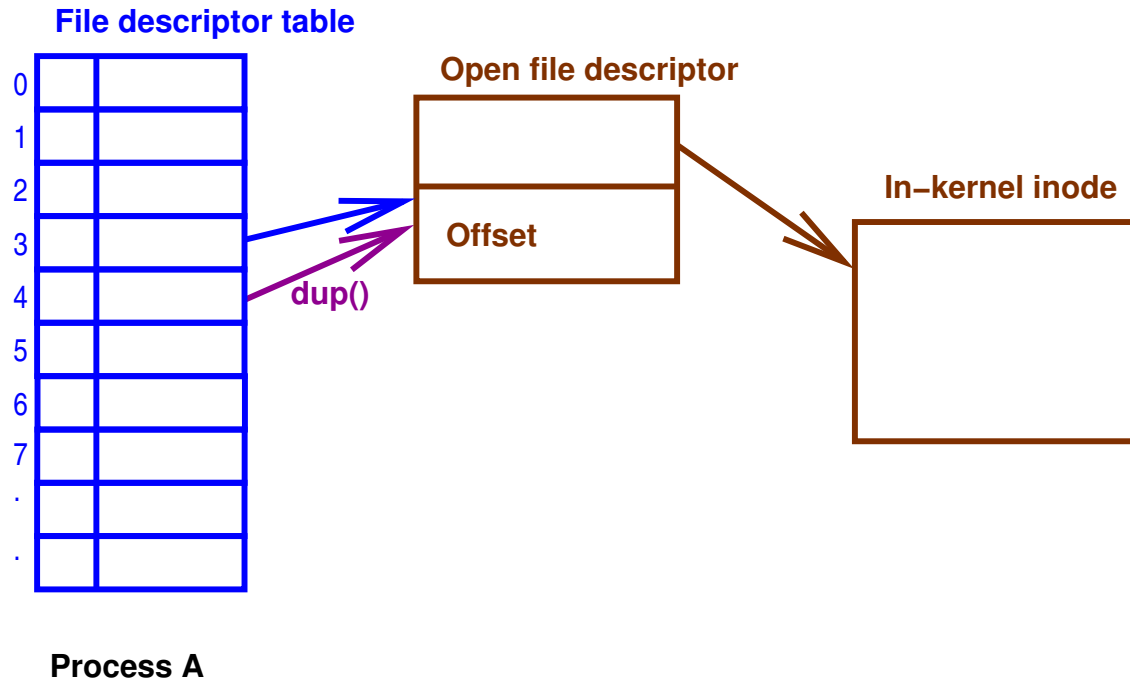
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Files and Processes:



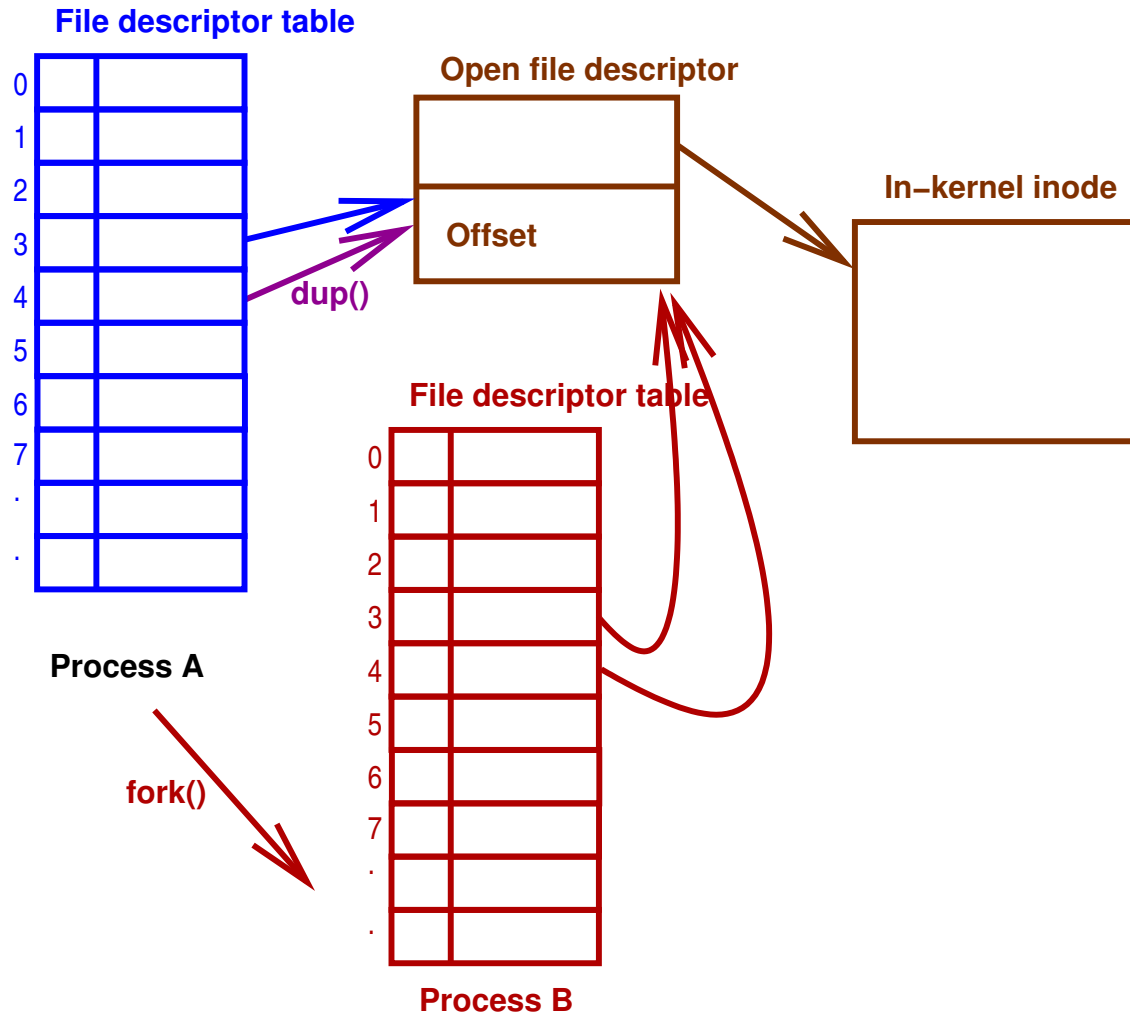
fork () and exec ()

Files and Processes:



fork () and exec ()

Files and Processes:



fork () and exec ()

```
switch (kidpid = fork()) {
case 0: /* child */
    close(0); close(1); close(2);
    dup(infd); dup(outfd); dup(outfd);
    execve("path/to/prog", argv, envp);
    _exit(EXIT_FAILURE);
case -1:
    /* handle error */
default:
    waitpid(kidpid, &status, 0);
}
```

Standard File Descriptors

0 Standard Input

1 Standard Output

2 Standard Error

→ Inherited from parent

→ On login, all are set to *controlling tty*

The problem with `fork()`

- Almost perfect in original system
 - Implemented in a few lines of assembly
 - Allowed re-use of system calls for changing state
 - Fast for segment-style (not paged) MMU

The problem with `fork()`

- Almost perfect in original system
- But:
 - Address spaces now bigger and managed with pages
 - * Slow to copy page tables
 - Multi-threading breaks semantics
 - * Child no longer an exact copy — only one thread `fork()` ed
 - * Much more per-process state, not all inheritable

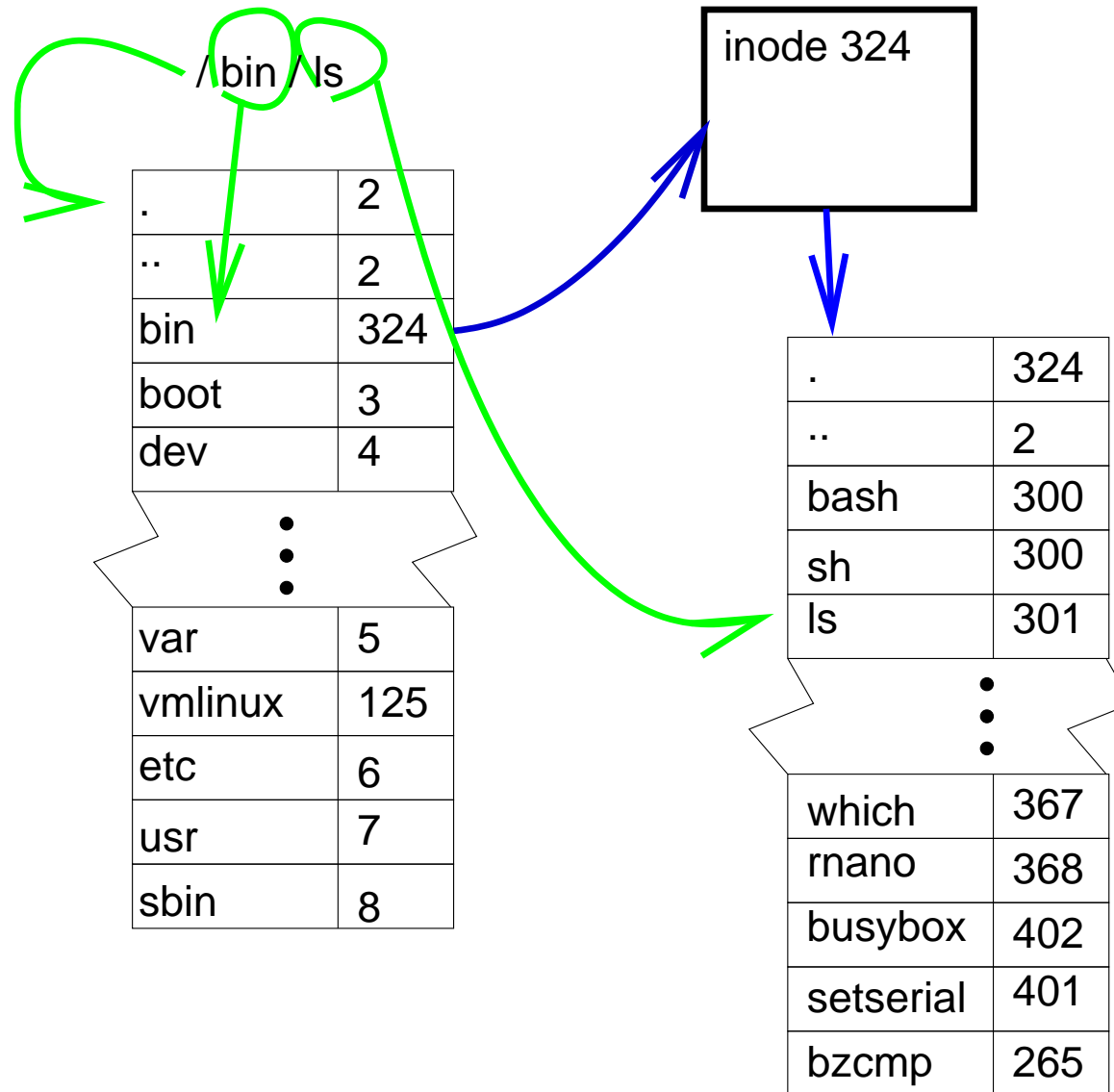
Permissions Model

- Based on logged-in-users
- UID, GID, Other — rwx
- Mainly for File access.

File model

- Separation of names from content.
- ‘regular’ files ‘just bytes’ → structure/meaning supplied by userspace
- Devices represented by files.
- Directories map names to index node indices (`inums`)
- Simple permissions model based on who you are.

File model



namei

- translate name → inode
- abstracted per filesystem in VFS layer
- Can be slow: extensive use of caches to speed it up *dentry cache*
- hide filesystem and device boundaries
- walks pathname, translating symbolic links

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- abstracted per filesystem in VFS layer
- Can be slow: extensive use of caches to speed it up *dentry cache* — becomes SMP bottleneck
- hide filesystem and device boundaries
- walks pathname, translating symbolic links

Evolution

KISS:

→ Simplest possible algorithm used at first

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KISS:

- Simplest possible algorithm used at first
 - Easy to show correctness
 - Fast to implement
- As drawbacks and bottlenecks are found, replace with faster/more scalable alternatives

Linux C Dialect

- Extra keywords:
 - Section IDs: `__init`, `__exit`, `__percpu` **etc**
 - Info Taint annotation `__user`, `__rcu`, `__kernel`, `__iomem`
 - Locking annotations `__acquires(X)`, `__releases(x)`
 - extra typechecking (endian portability) `__bitwise`

Linux C Dialect

- Extra iterators
 - `type_name_foreach()`
- Extra O-O accessors
 - `container_of()`
- Macros to register Object initialisers

Linux C Dialect

- Massive use of inline functions
- Quite a big use of CPP macros
- Little `#ifdef` use in code: rely on optimiser to elide dead code.

Internal Abstractions

- MMU
- Memory consistency model
- Device model

Scheduling

Goals:

- dispatch $O(1)$ in number of runnable processes, number of processors
 - good uniprocessor performance
- 'fair'
- Good interactive response
- topology-aware
- $O(\log n)$ for scheduling in number of runnable processes.

Scheduling

Implementation:

- Changes from time to time.
- Currently 'CFS' by Ingo Molnar.

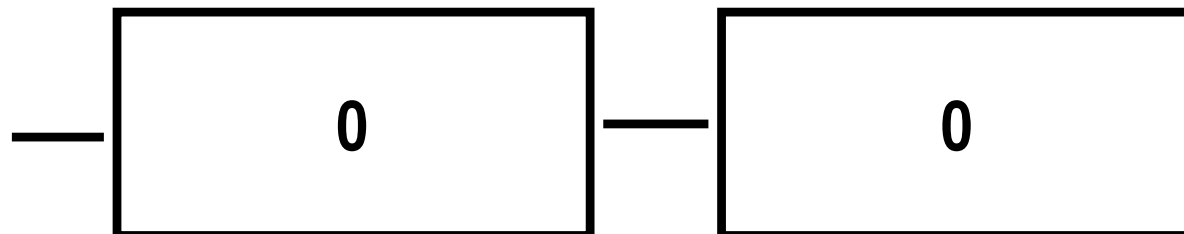
Scheduling

Dual Entitlement Scheduler

Running



Expired



Scheduling

CFS:

1. Keep tasks ordered by effective CPU runtime weighted by nice in red-black tree
2. Always run left-most task.

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Devil's in the details:

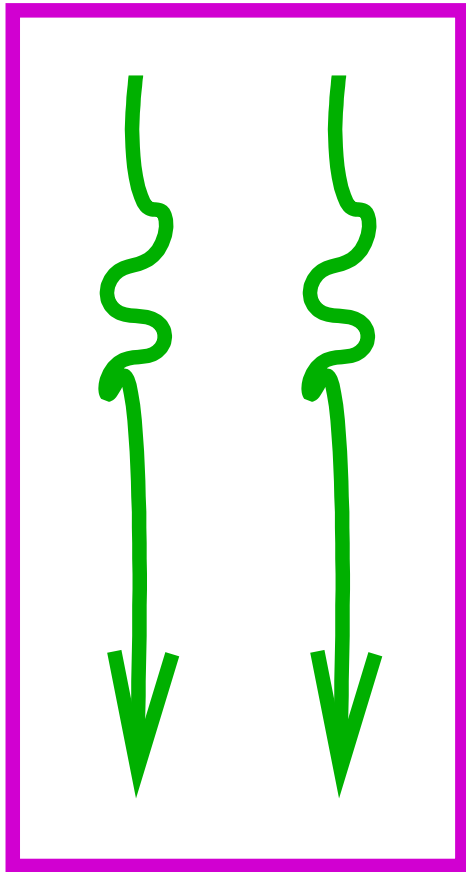
- Avoiding overflow
- Keeping recent history
- multiprocessor locality
- handling too-many threads
- Sleeping tasks
- Group hierarchy

Scheduling



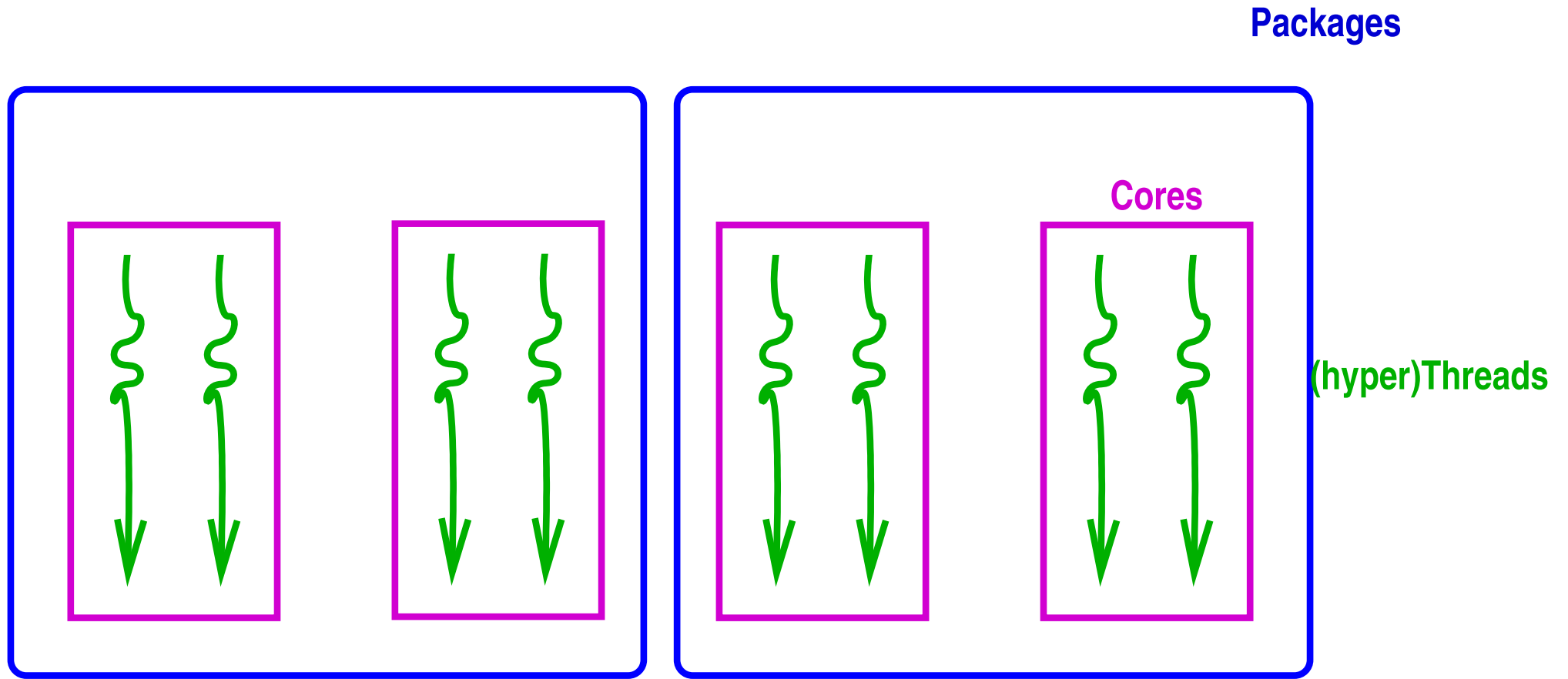
(hyper)Thread

Scheduling

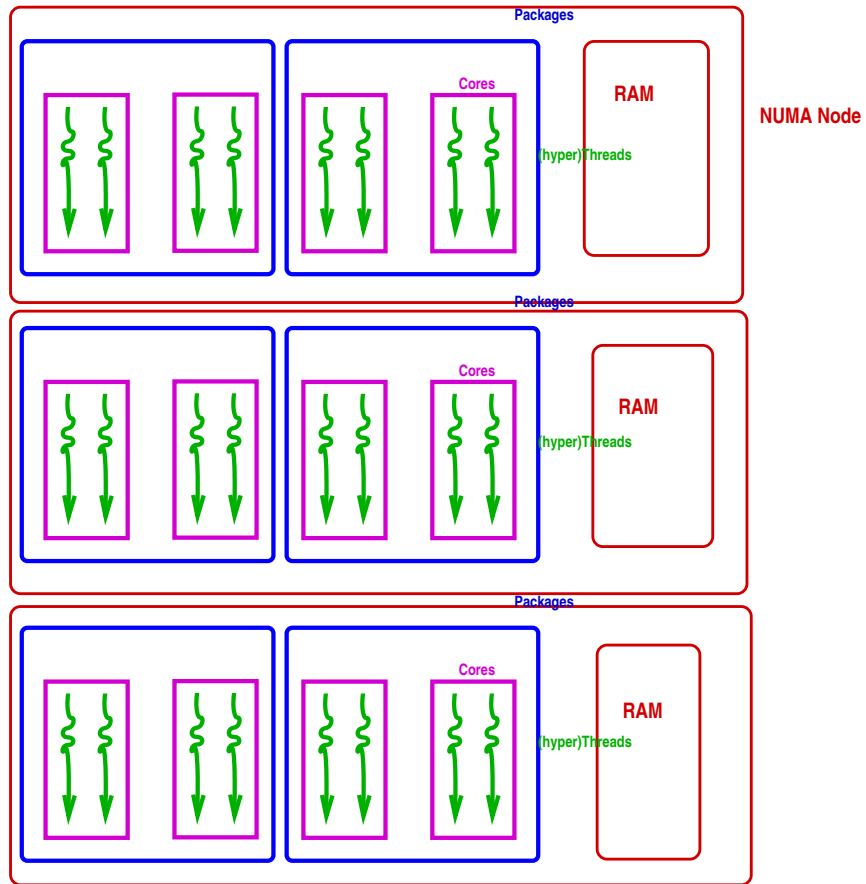


Core

Scheduling



Scheduling



Scheduling

Locality Issues:

- Best to reschedule on same processor (don't move cache footprint, keep memory close)

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Scheduling

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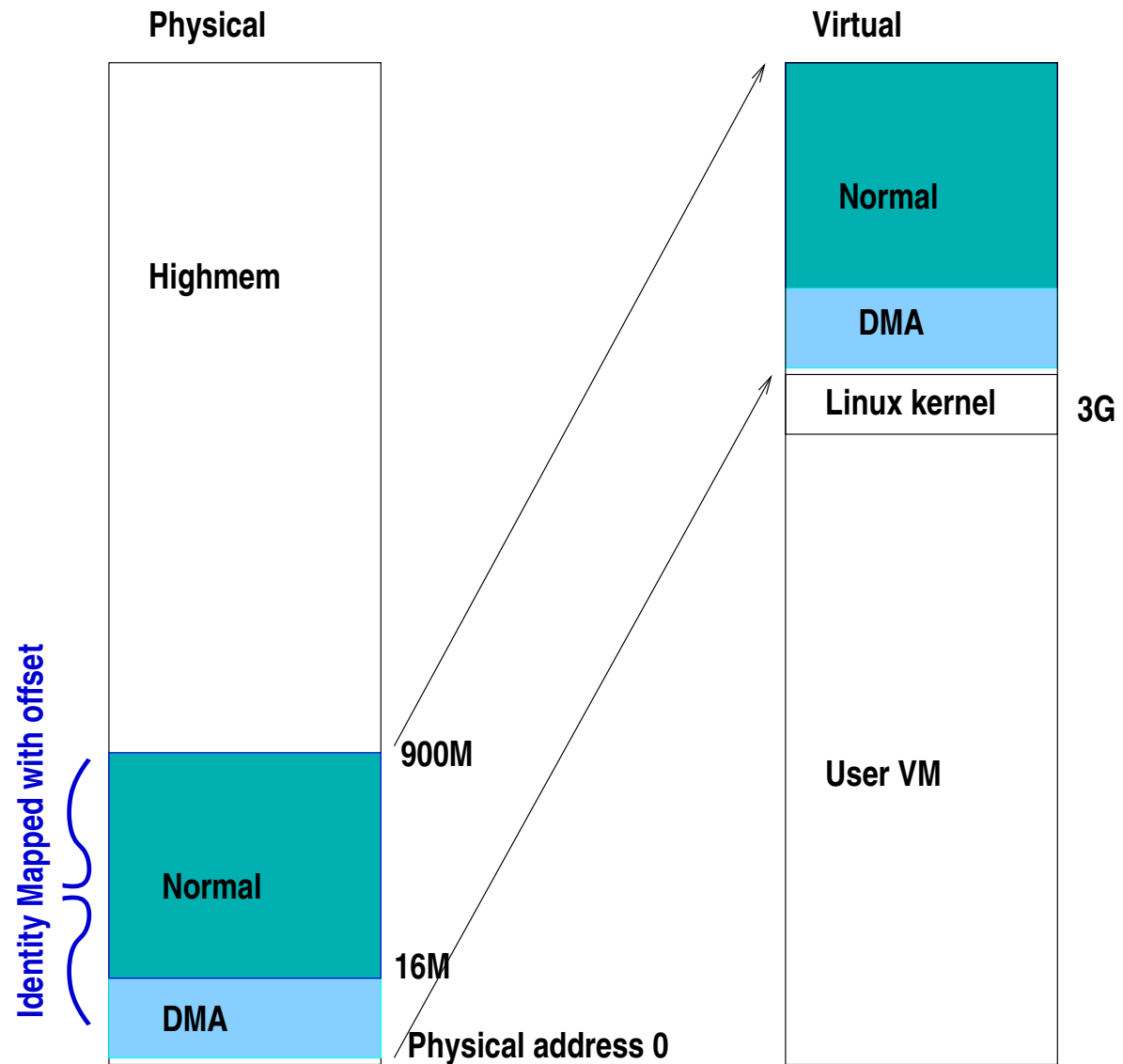
- Best to reschedule on same processor (don't move cache footprint, keep memory close)
 - Otherwise schedule on a 'nearby' processor
- Try to keep whole sockets idle (can power them off)
- Somehow identify cooperating threads, co-schedule 'close by'?

Scheduling

- One queue per processor (or hyperthread)
- Processors in hierarchical 'domains'
- Load balancing per-domain, bottom up
- Aims to keep whole domains idle if possible (power savings)

Memory Management

Memory in *zones*



Memory Management

- Direct mapped pages become *logical addresses*
 - `__pa()` and `__va()` convert physical to virtual for these

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Memory Management

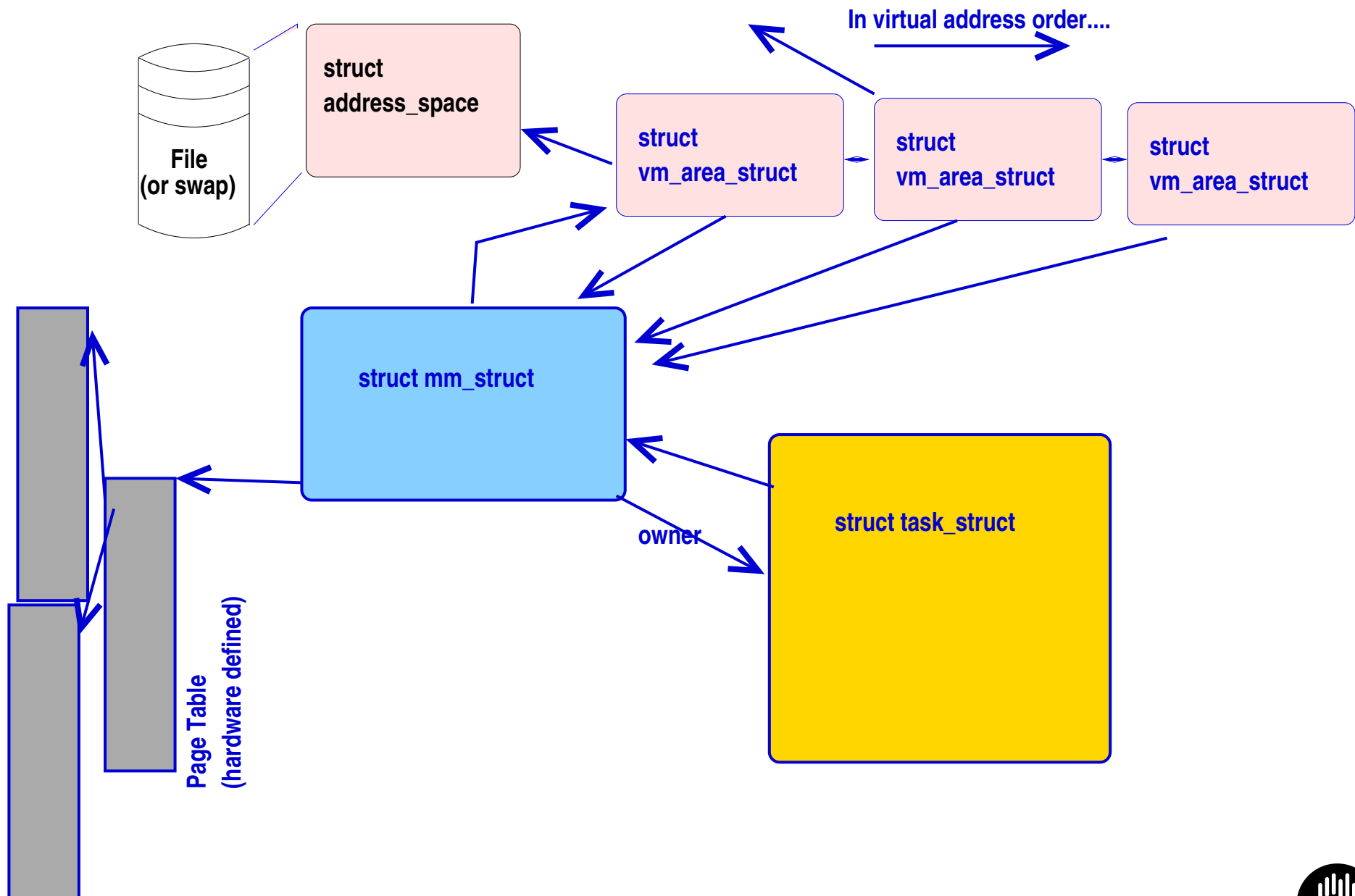
- Direct mapped pages become *logical addresses*
 - `__pa()` and `__va()` convert physical to virtual for these
- small memory systems have all memory as logical
- More memory \rightarrow Δ kernel refer to memory by `struct page`

Memory Management

`struct page:`

- Every frame has a `struct page` (up to 10 words)
- Track:
 - flags
 - backing address space
 - offset within mapping *or* freelist pointer
 - Reference counts
 - Kernel virtual address (if mapped)

Memory Management



Memory Management

Address Space:

- Misnamed: means collection of pages mapped from the same object
- Tracks inode mapped from, radix tree of pages in mapping
- Has ops (from file system or swap manager) to:
 - dirty** mark a page as dirty
 - readpages** populate frames from backing store
 - writepages** Clean pages — make backing store the same as in-memory copy
 - migratepage** Move pages between NUMA nodes
 - Others...** And other housekeeping

Page fault time

- Special case in-kernel faults
- Find the VMA for the address
 - segfault if not found (unmapped area)
- If it's a stack, extend it.
- Otherwise:
 1. Check permissions, SIG_SEGV if bad
 2. Call `handle_mm_fault()`:
 - walk page table to find entry (populate higher levels if nec. until leaf found)
 - call `handle_pte_fault()`

Page fault time

`handle_pte_fault()`: Depending on PTE status, can

- provide an anonymous page
- do copy-on-write processing
- reinstantiate PTE from page cache
- initiate a read from backing store.

and if necessary flushes the TLB.

Driver Interface

Three kinds of device:

1. Platform device
2. enumerable-bus device
3. Non-enumerable-bus device

Driver Interface

Enumerable buses:

```
static DEFINE_PCI_DEVICE_TABLE(cp_pci_tbl) = {
    { PCI_DEVICE(PCI_VENDOR_ID_REALTEK,
                 PCI_DEVICE_ID_REALTEK_8139), },
    { PCI_DEVICE(PCI_VENDOR_ID_TTTECH,
                 PCI_DEVICE_ID_TTTECH_MC322), },
    { },
};

MODULE_DEVICE_TABLE(pci, cp_pci_tbl);
```

Driver Interface

Driver interface:

init called to register driver

exit called to deregister driver, at module unload time

probe () called when bus-id matches; returns 0 if driver claims device

open, close, etc as necessary for driver class

Driver Interface

Platform Devices (old way):

```
static struct platform_device nslu2_uart = {  
    .name = "serial8250",  
    .id = PLAT8250_DEV_PLATFORM,  
    .dev.platform_data = nslu2_uart_data,  
    .num_resources = 2,  
    .resource = nslu2_uart_resources,  
};
```

Driver Interface

non-enumerable buses: Treat like platform devices

Device Tree

- Describe board+peripherals

Device Tree

- Describe board+peripherals
 - replaces ACPI on embedded systems

Device Tree

- Describe board+peripherals
 - replaces ACPI on embedded systems
- Names in device tree trigger driver instantiation

Device Tree

```
uart_A: serial@84c0 {  
    compatible = "amlogic,meson6-uart", "amlogic,meson6-uart";  
    reg = <0x84c0 0x18>;  
    interrupts = <GIC_SPI 26 IRQ_TYPE_EDGE_RISING>;  
    status = "ok";  
};
```

Containers

- *Namespace* isolation

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- Plus Memory and CPU isolation

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- Plus other resources

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In hierarchy of control groups

Containers

- *Namespace* isolation
- Plus Memory and CPU isolation
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In hierarchy of control groups

Used to implement, e.g., **Docker**

Summary

- I've told you status today

Summary

- I've told you status today
 - Next week it may be different

Summary

- I've told you status today
 - Next week it may be different
- I've simplified a lot. There are many hairy details

Scalability

The Multiprocessor Effect:

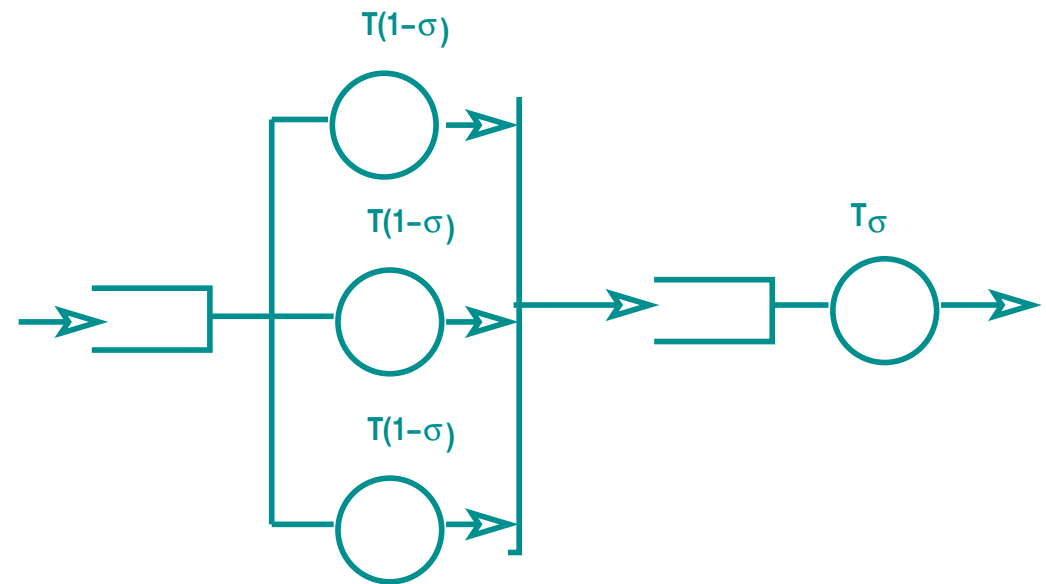
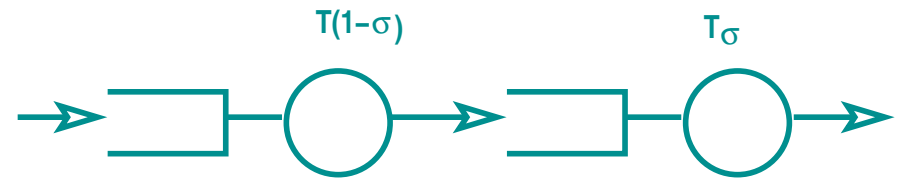
- Some fraction of the system's cycles are not available for application work:
 - Operating System Code Paths
 - Inter-Cache Coherency traffic
 - Memory Bus contention
 - Lock synchronisation
 - I/O serialisation

Scalability

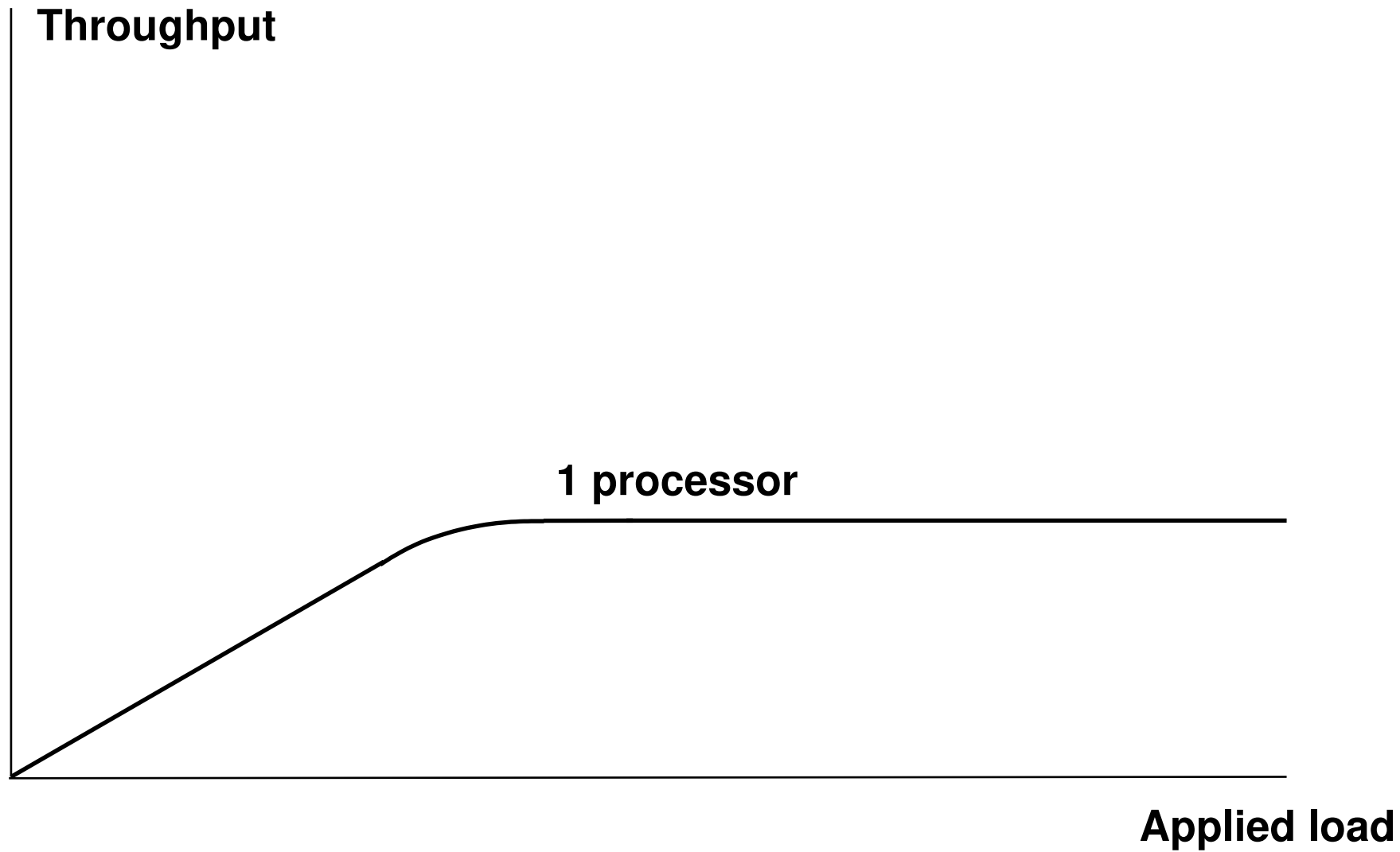
Amdahl's law:

If a process can be split such that σ of the running time cannot be sped up, but the rest is sped up by running on p processors, then overall speedup is

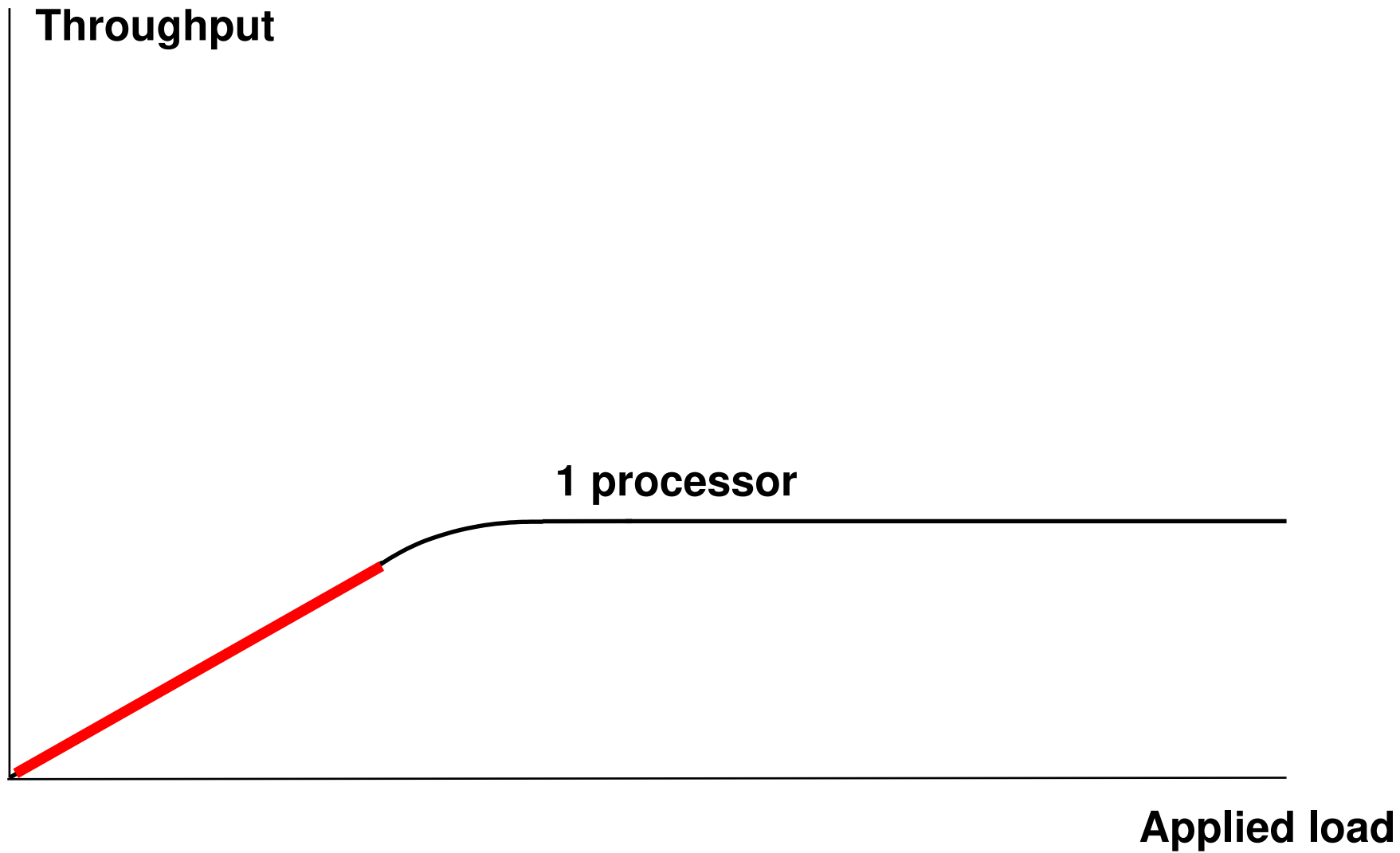
$$\frac{p}{1 + \sigma(p - 1)}$$



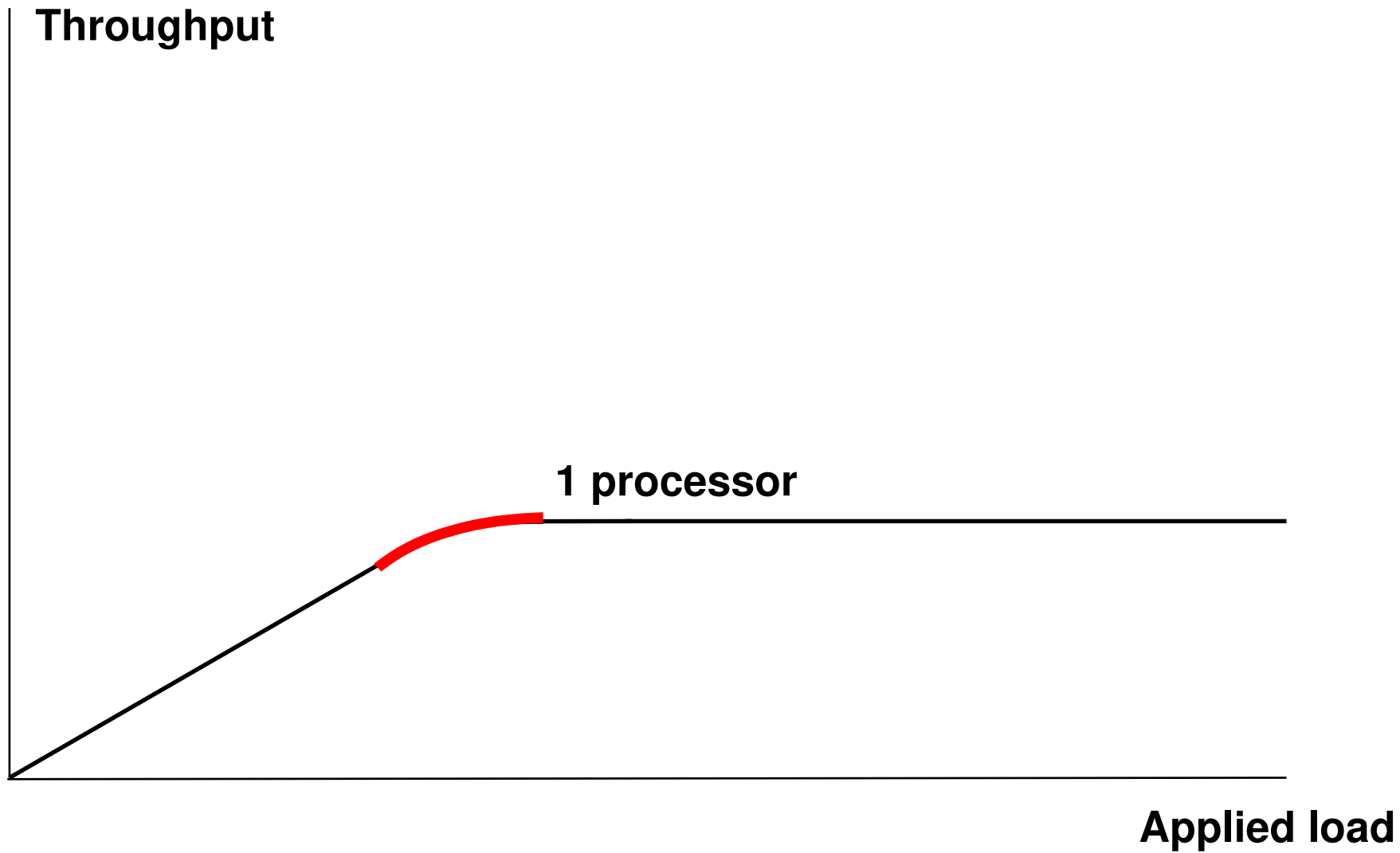
Scalability



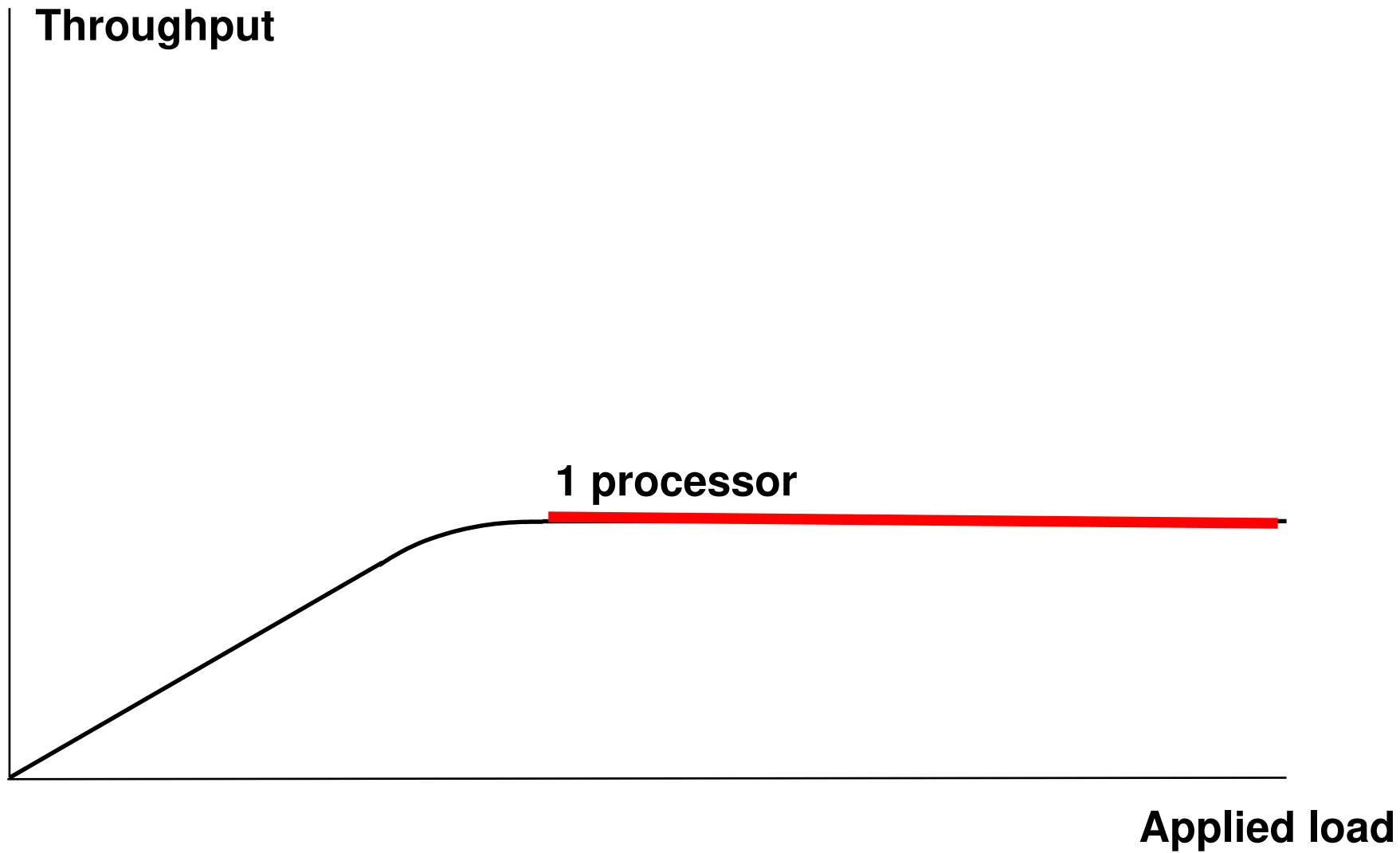
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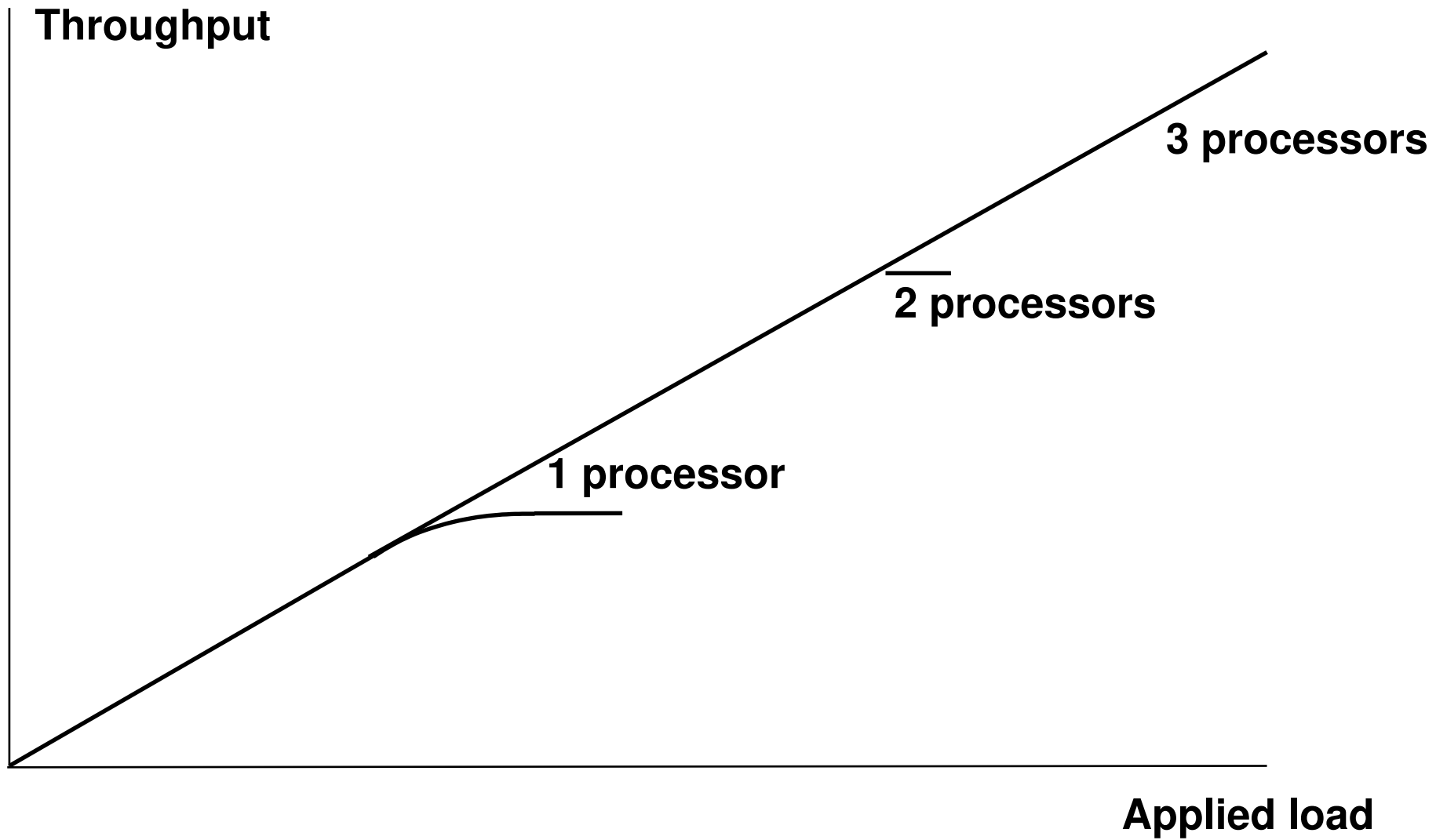
Scalability



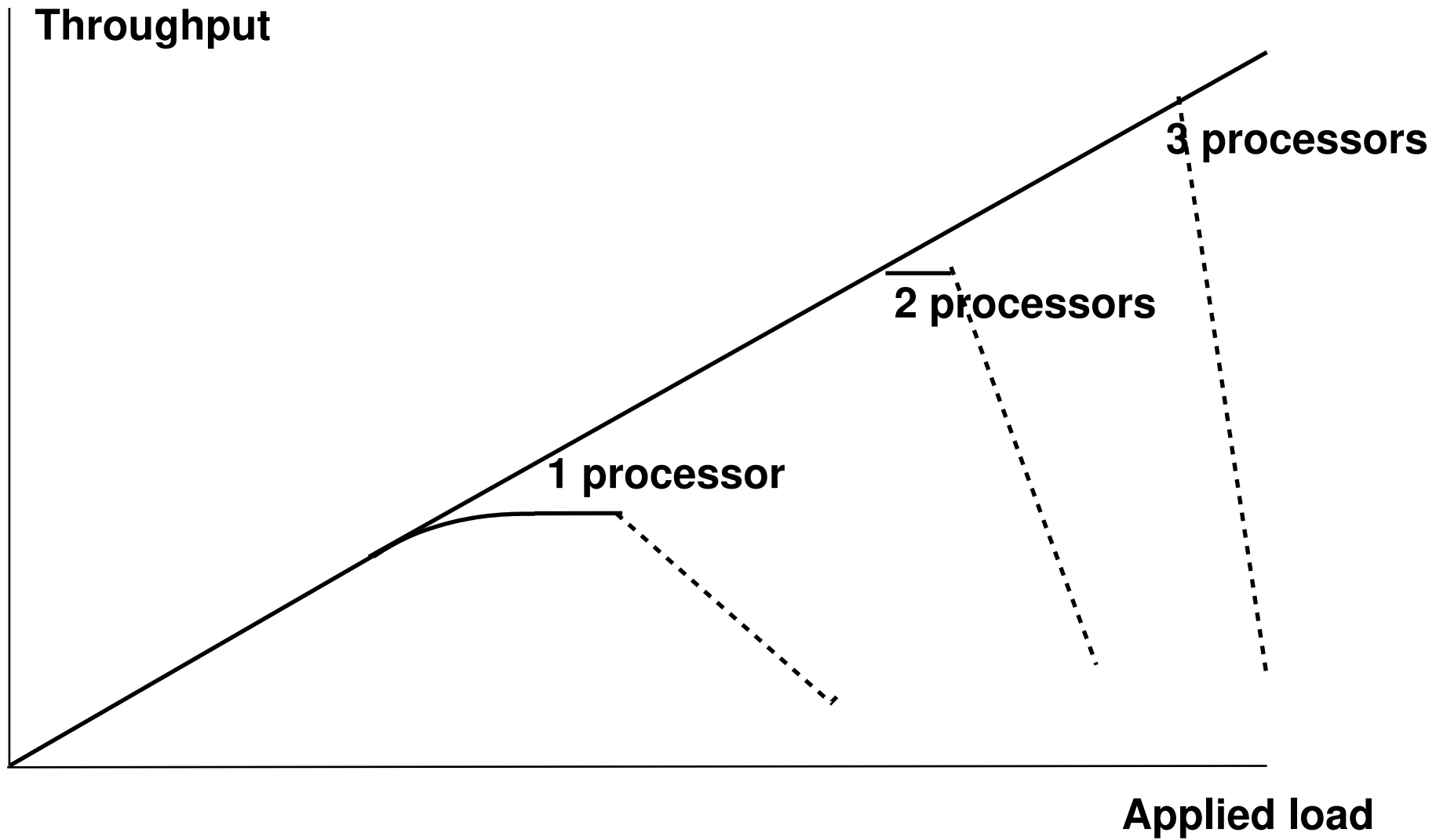
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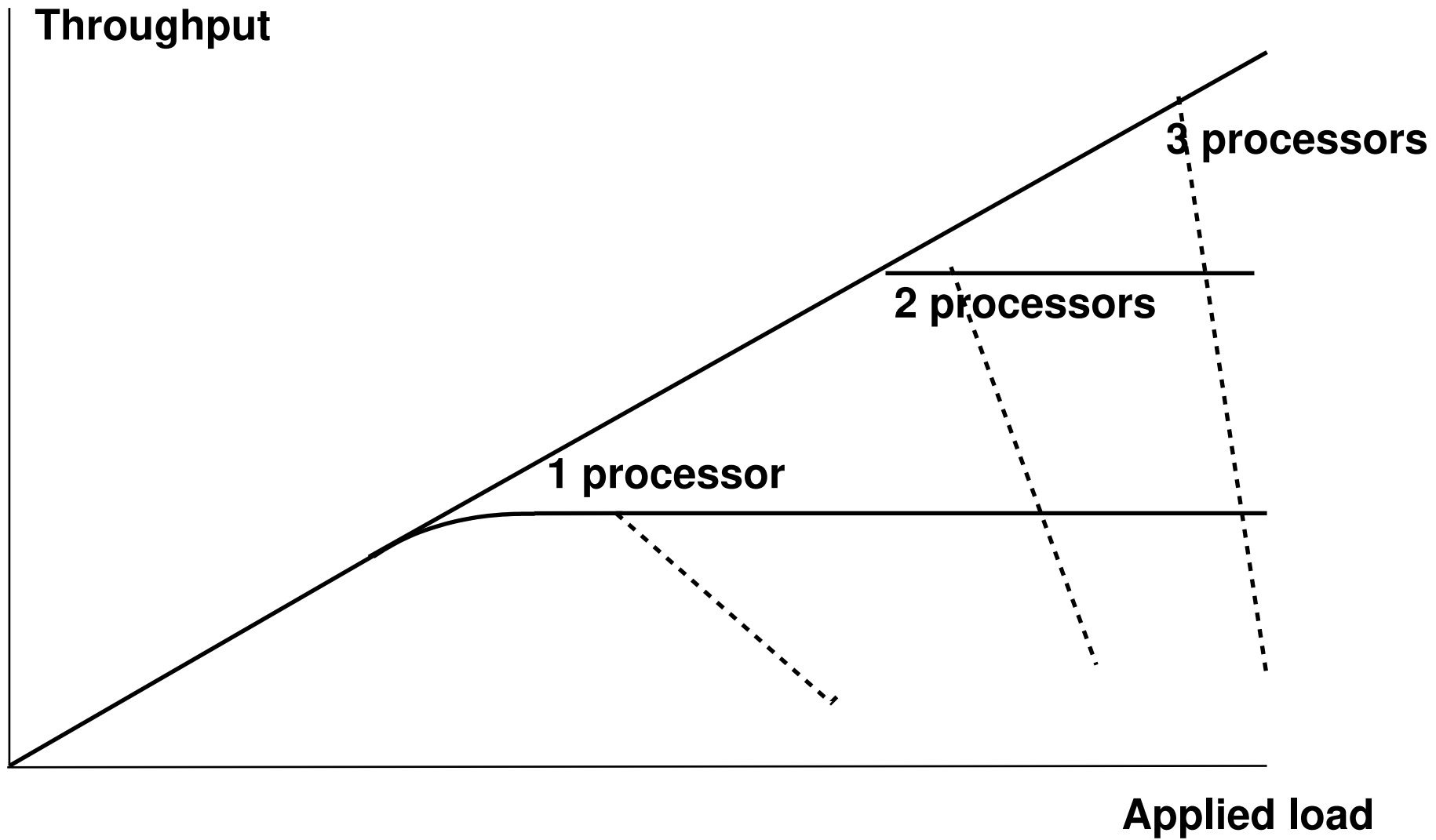
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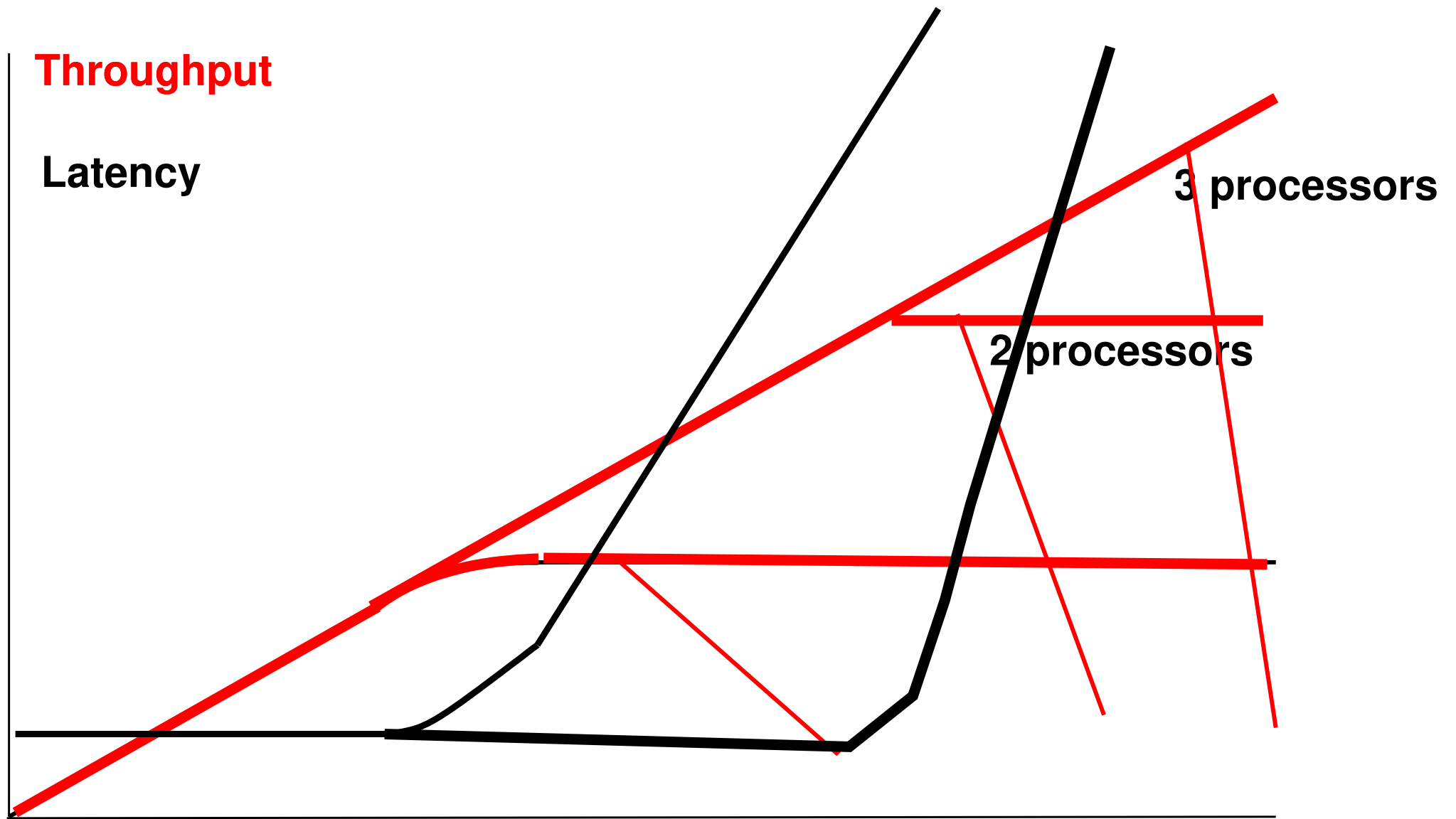
Scalability



Scalability



Scalability



Applied load



Scalability

Gunther's law:

$$C(N) = \frac{N}{1 + \alpha(N - 1) + \beta N(N - 1)}$$

where:

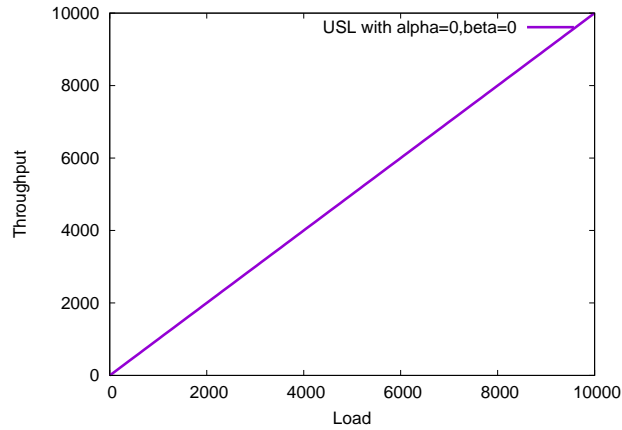
N is demand

α is the amount of serialisation: represents Amdahl's law

β is the coherency delay in the system.

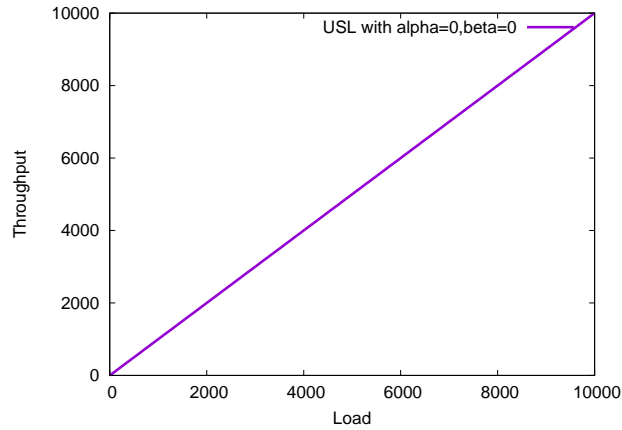
C is Capacity or Throughput

Scalability

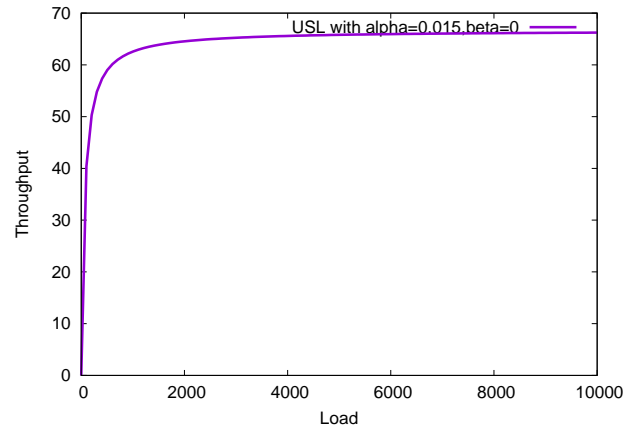


$$\alpha = 0, \beta = 0$$

Scalability

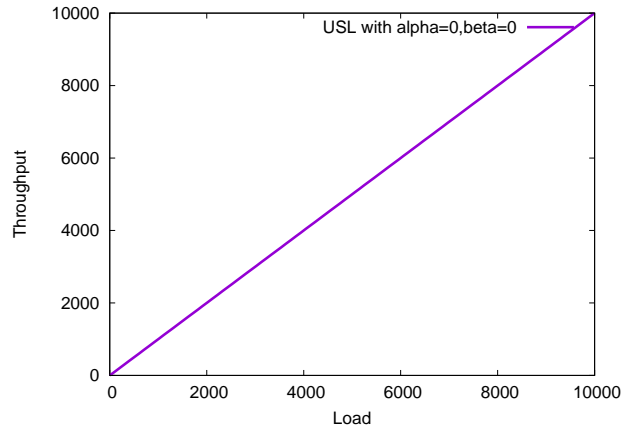


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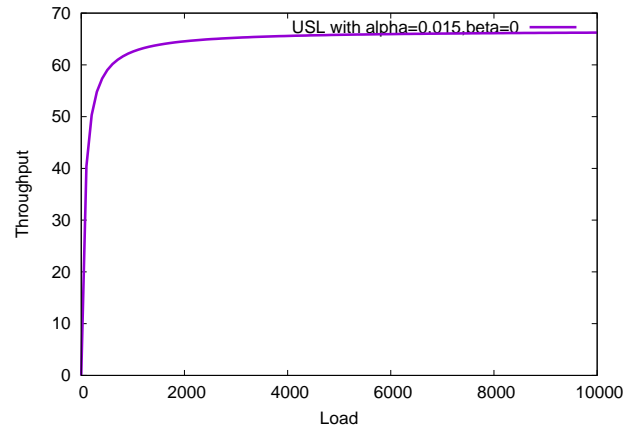


$$\alpha > 0, \beta = 0$$

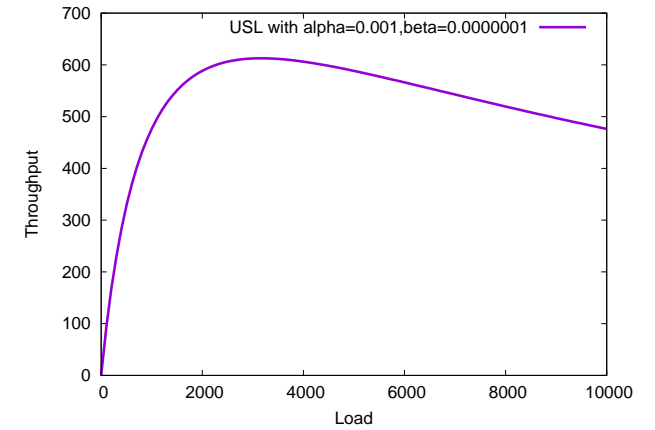
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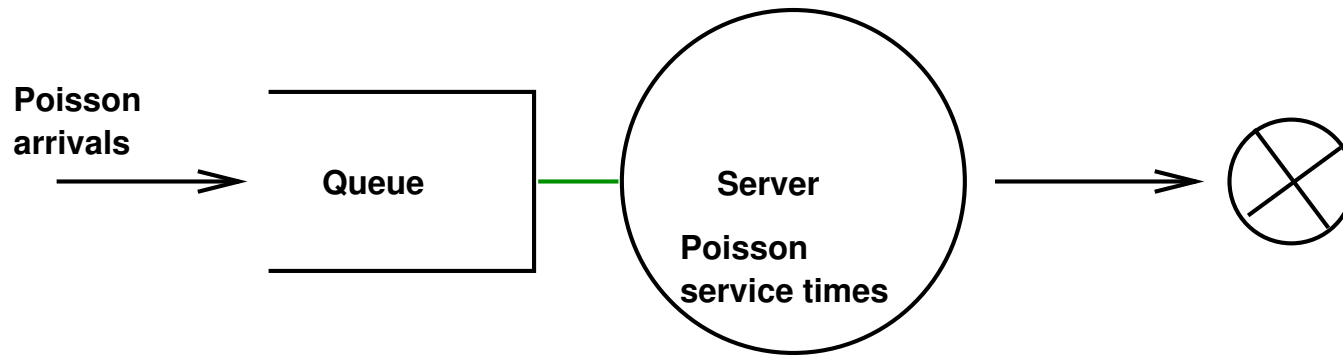
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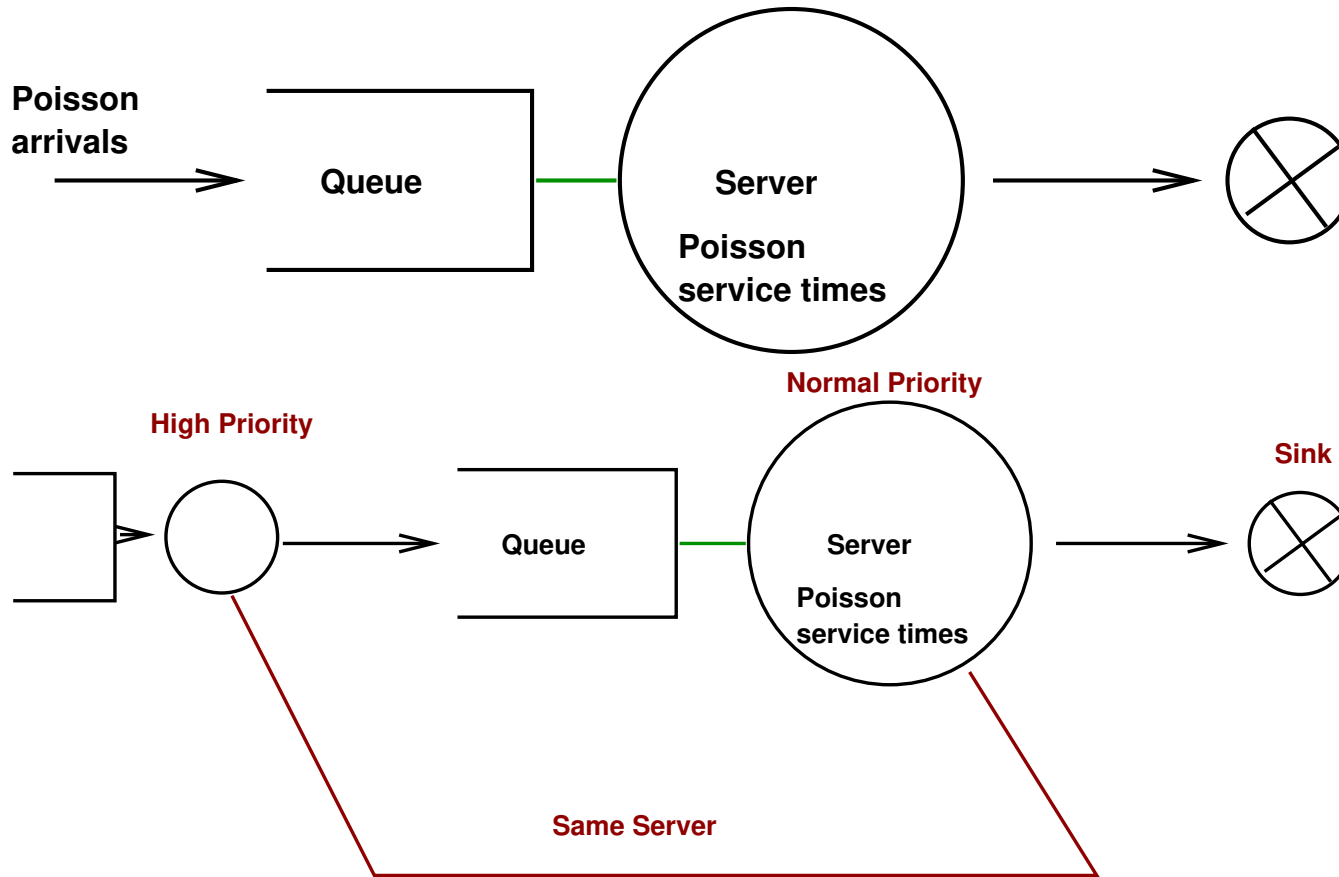
Scalability

Queueing Models:



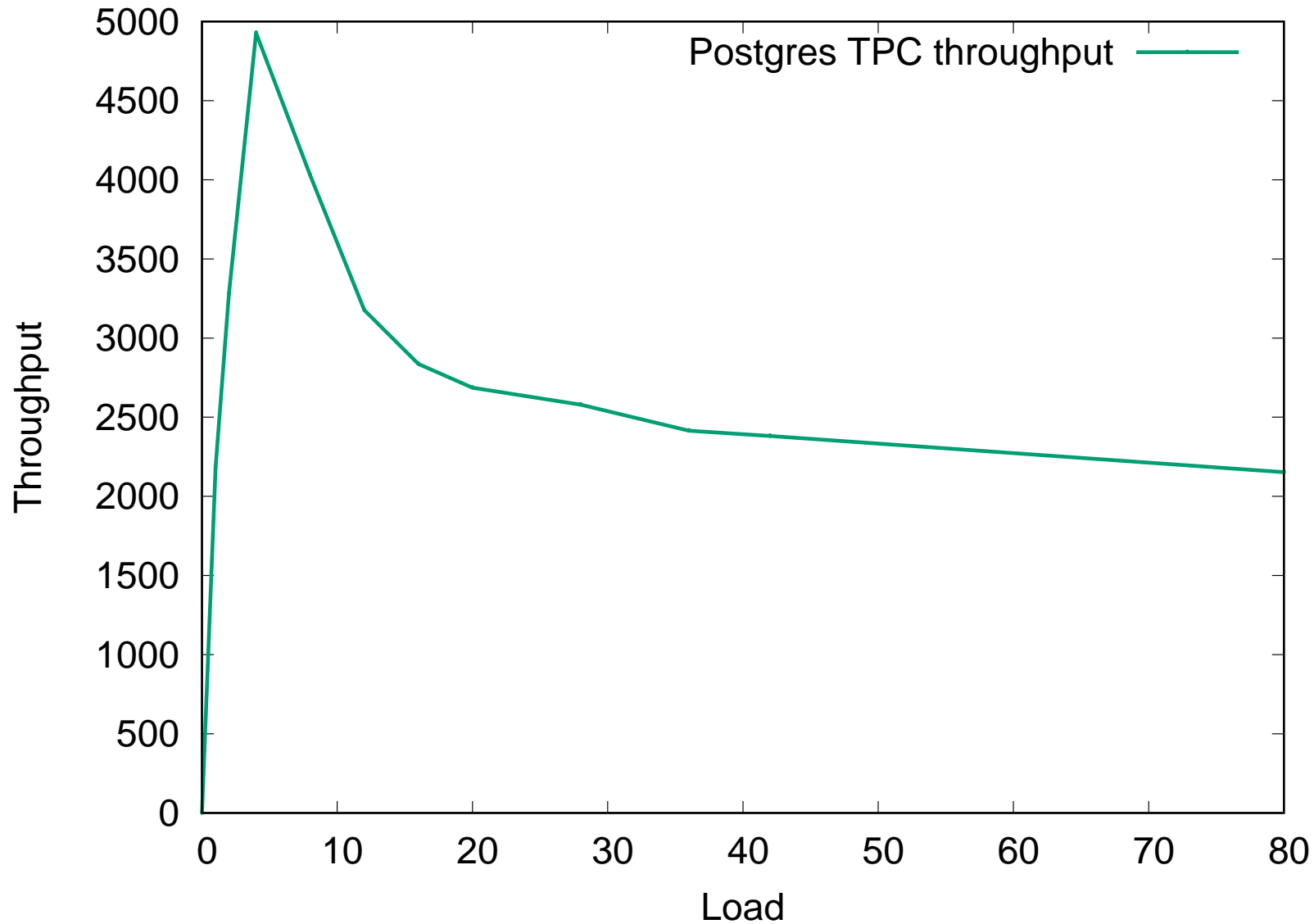
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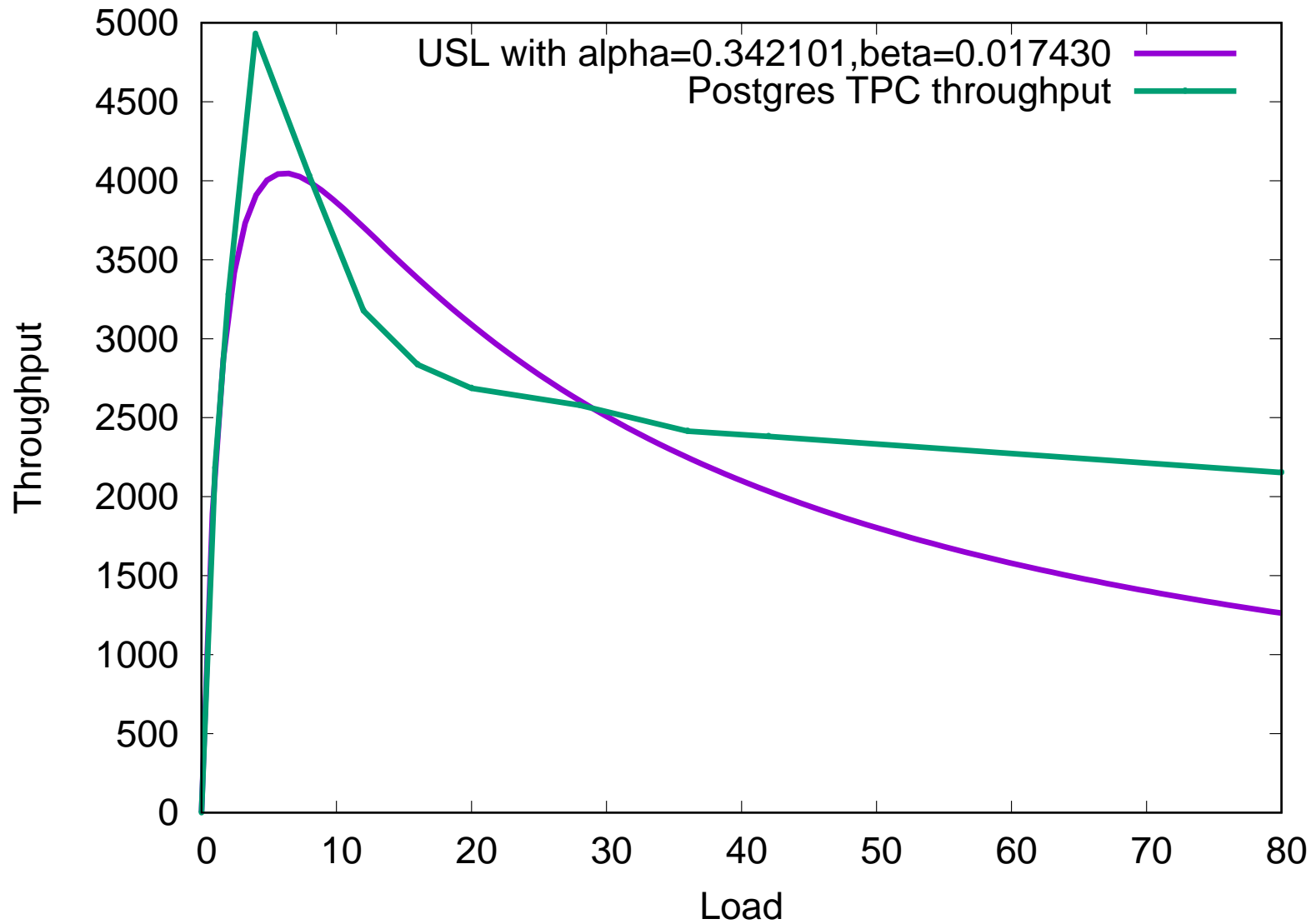


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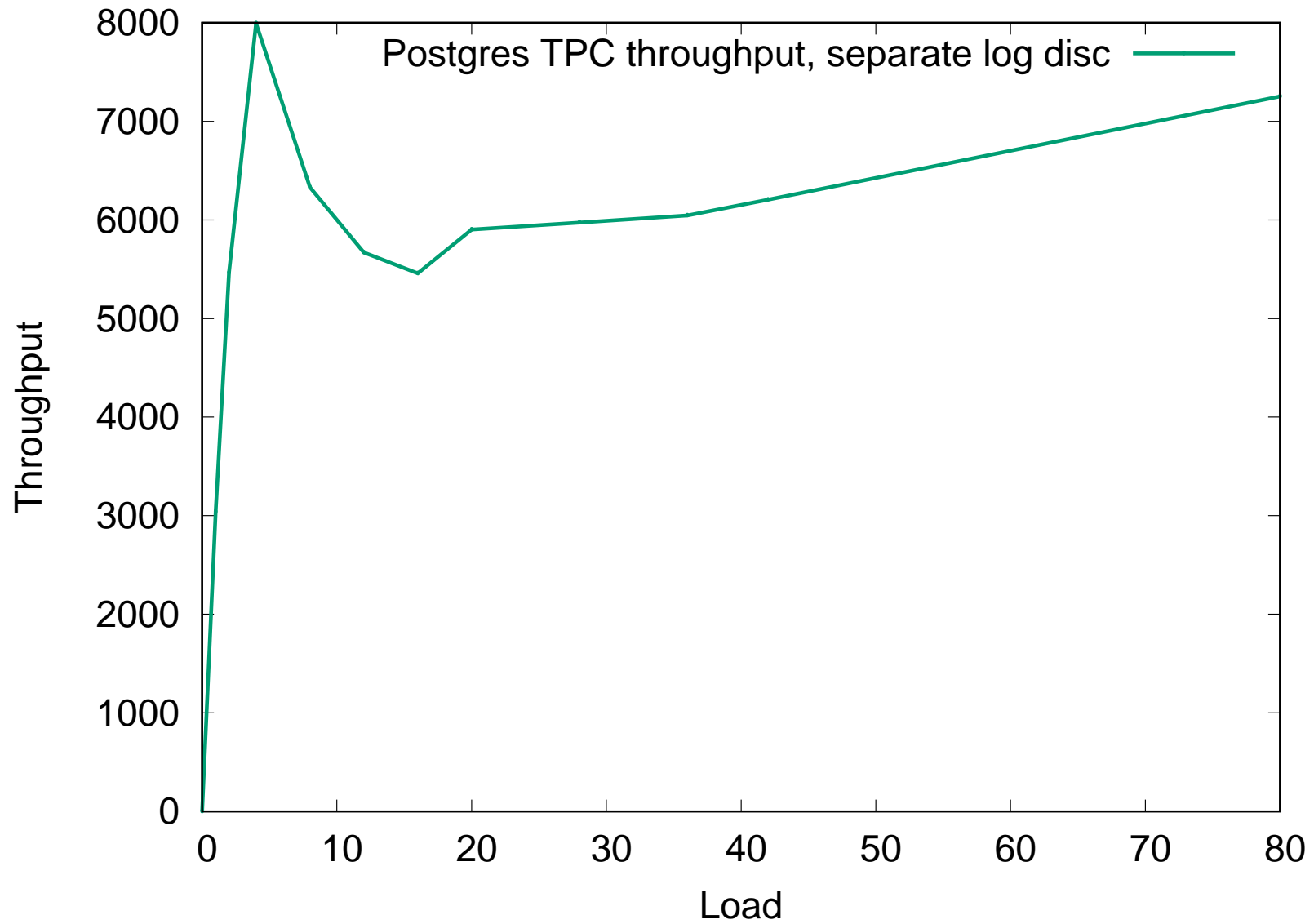
Real examples:



Scalability

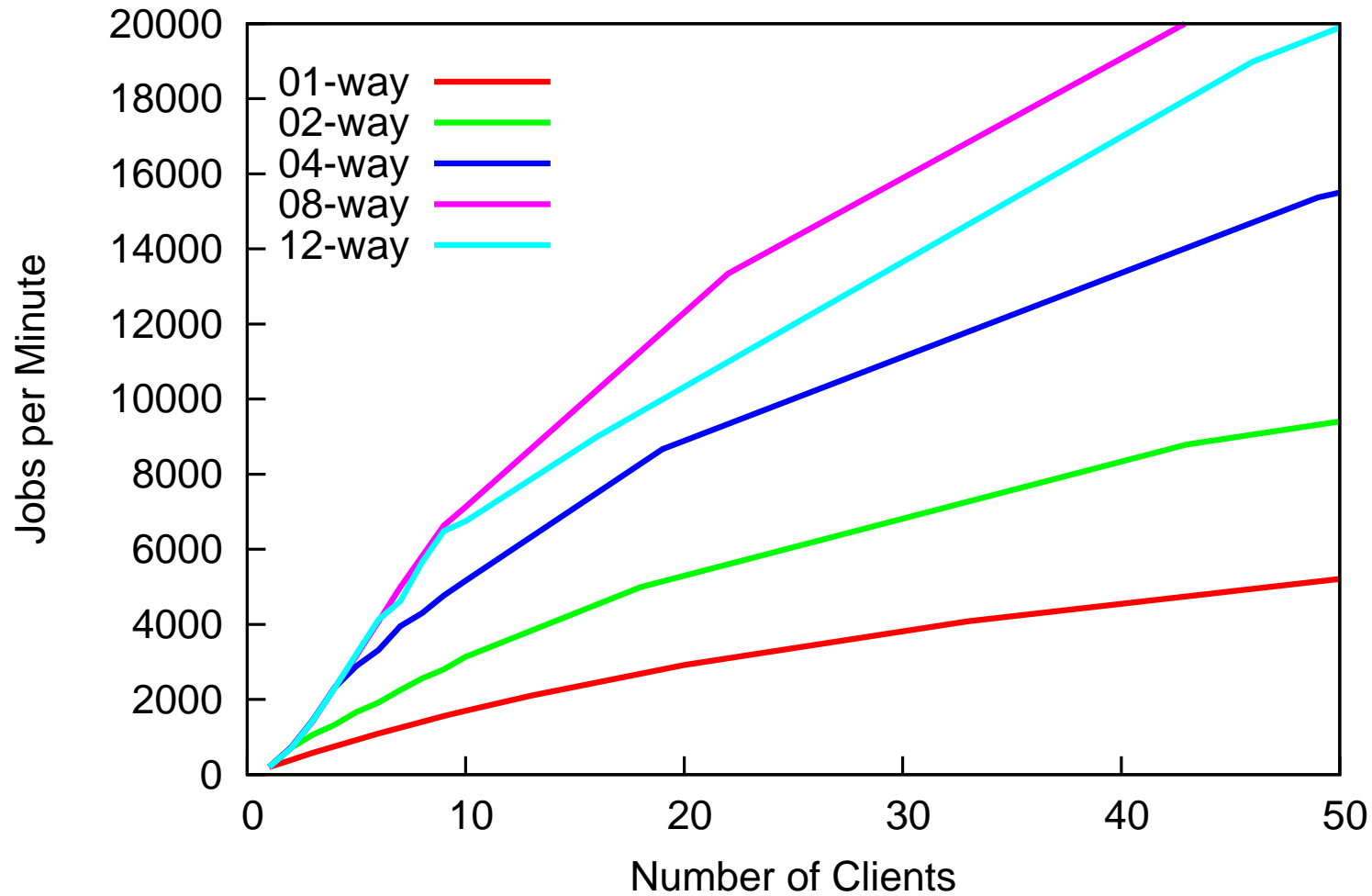


Scalability



Scalability

Another example:



Scalability

SPINLOCKS		HOLD		WAIT					
UTIL	CON	MEAN (MAX)	MEAN (MAX) (% CPU)	TOTAL	NOWAIT	SPIN	RJECT	NAME	
72.3%	13.1%	0.5us (9.5us)	29us (20ms) (42.5%)	50542055	86.9%	13.1%	0%	find_lock_page+0x30	
0.01%	85.3%	1.7us (6.2us)	46us (4016us) (0.01%)	1113	14.7%	85.3%	0%	find_lock_page+0x130	

Scalability

```
struct page *find_lock_page(struct address_space *mapping,
                            unsigned long offset)
{
    struct page *page;

    spin_lock_irq(&mapping->tree_lock);

repeat:
    page = radix_tree_lookup(&mapping->page_tree, offset);

    if (page) {
        page_cache_get(page);

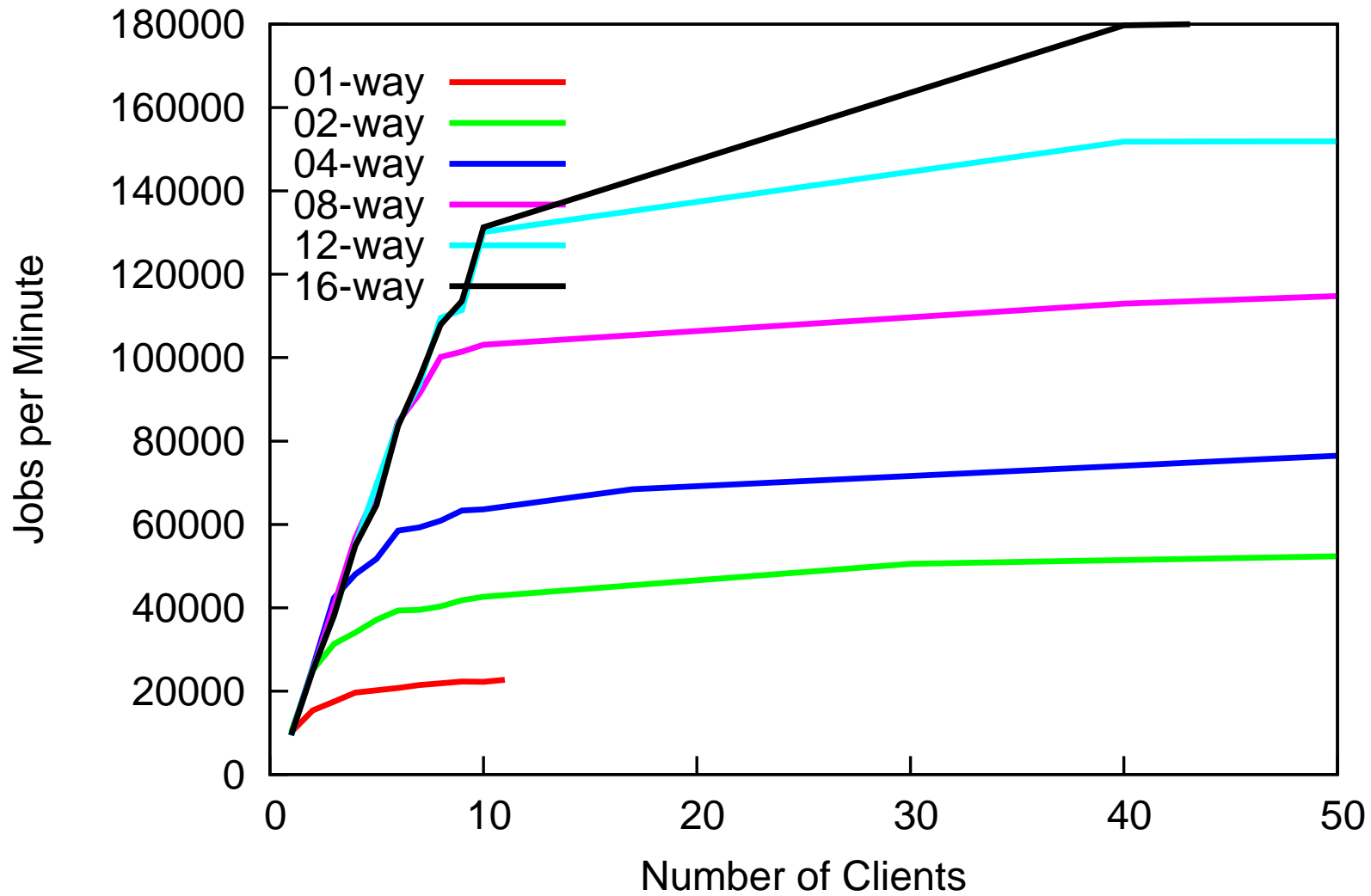
        if (TestSetPageLocked(page)) {
            spin_unlock_irq(&mapping->tree_lock);

            lock_page(page);

            spin_lock_irq(&mapping->tree_lock);

            . . .
        }
    }
}
```

Scalability



Tackling scalability problems

- Find the bottleneck

Tackling scalability problems

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 - not always easy

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Tackling scalability problems

- Find the bottleneck
- fix or work around it
- check performance doesn't suffer too much on the low end.
- Experiment with different algorithms, parameters

Tackling scalability problems



- Each solved problem uncovers another
- Fixing performance for one workload can worsen another

Tackling scalability problems



- Each solved problem uncovers another
- Fixing performance for one workload can worsen another
- Performance problems can make you cry

Doing without locks

Avoiding Serialisation:

- *Lock-free* algorithms
- Allow safe concurrent access *without excessive serialisation*

Doing without locks

Avoiding Serialisation:

- *Lock-free* algorithms
- Allow safe concurrent access *without excessive serialisation*
- Many techniques. We cover:
 - Sequence locks
 - Read-Copy-Update (RCU)

Doing without locks

Sequence locks:

- Readers don't lock
- Writers serialised.

Doing without locks

Reader:

```
volatile seq;
do {
    do {
        lastseq = seq;
    } while (lastseq & 1);
    rmb();
    reader body .....
} while (lastseq != seq);
```

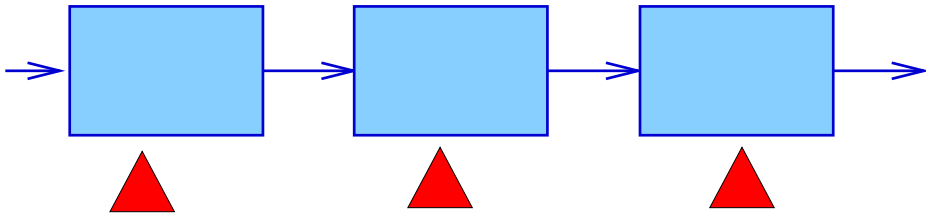
Writer:

```
spinlock(&lck);
seq++; wmb();
writer body ...
wmb(); seq++;
spinunlock(&lck);
```

Doing without locks

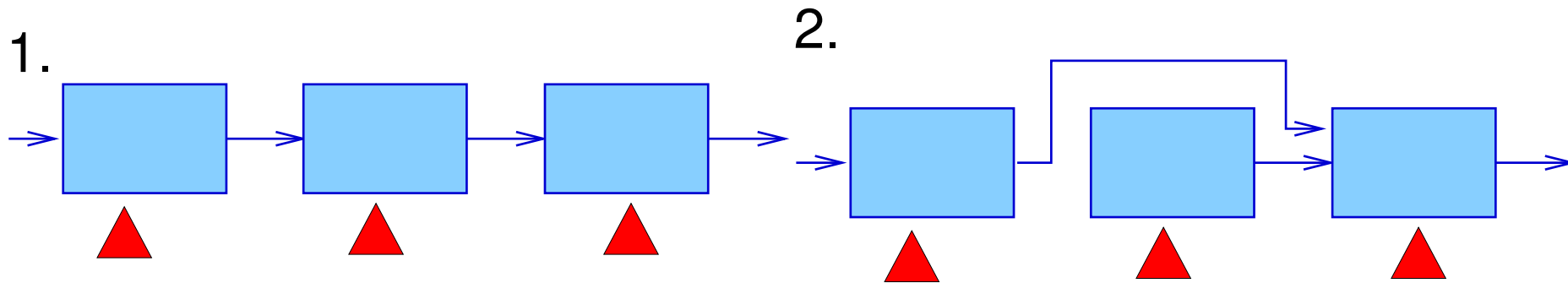
RCU: McKenney (2004), McKenney et al. (2002)

1.



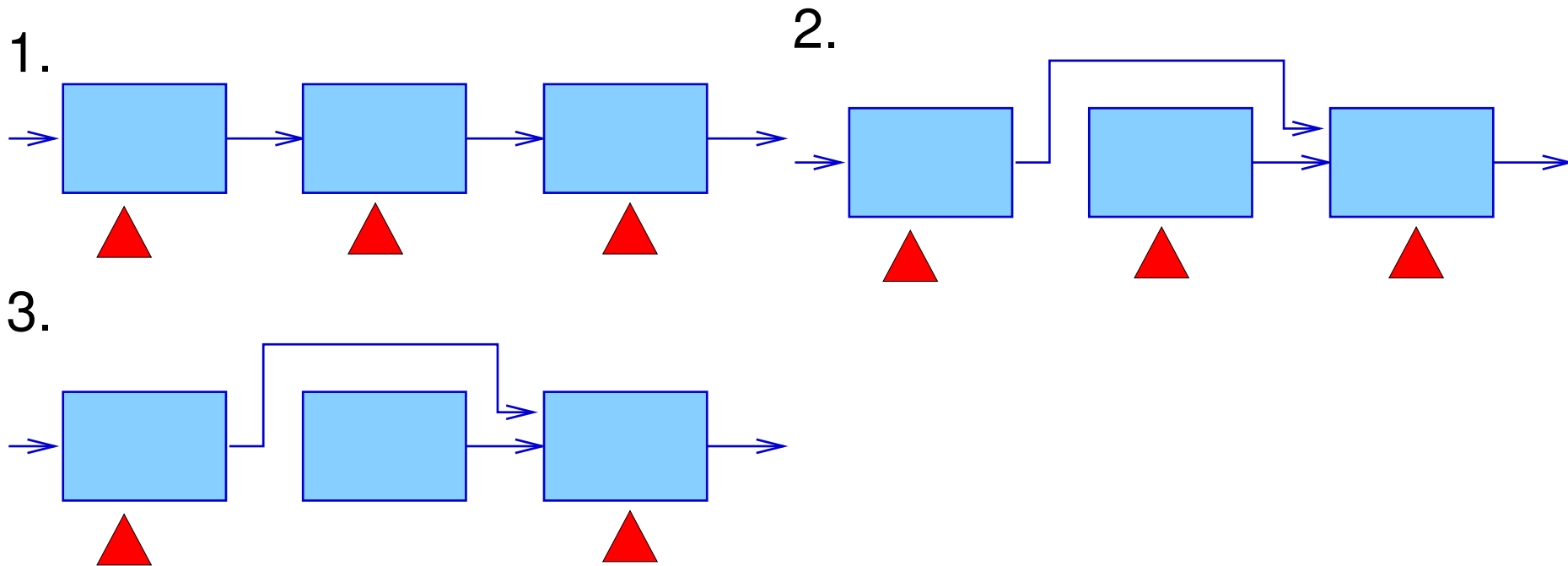
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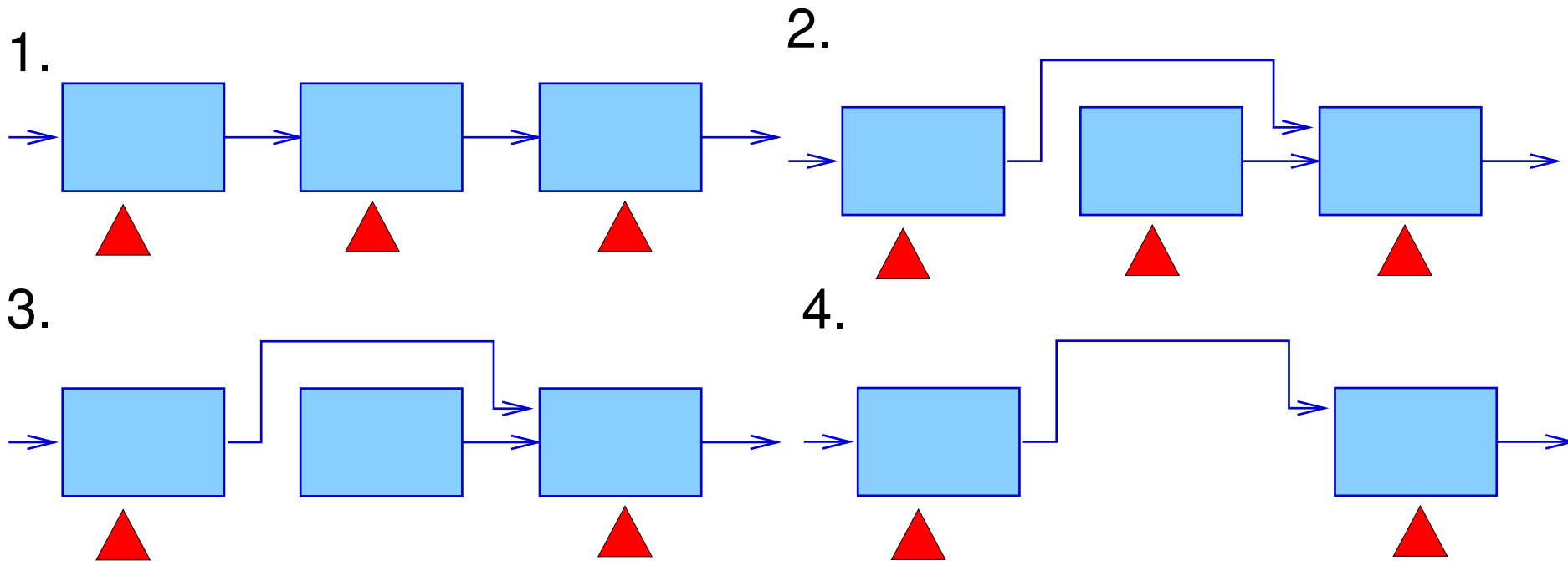
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Doing without locks

References

McKenney, P. E. (2004), Exploiting Deferred Destruction: An Analysis of Read-Copy-Update Techniques in Operating System Kernels, PhD thesis, OGI School of Science and Engineering at Oregon Health and Sciences University.

URL:

<http://www.rdrop.com/users/paulmck/RCU/RCUdissertation>

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