



COMP4161

Advanced Topics in Software Verification



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Content

→ Foundations & Principles

- Intro, Lambda calculus, natural deduction [1,2]
- Higher Order Logic, Isar (part 1) [2,3^a]
- Term rewriting [3,4]

→ Proof & Specification Techniques

- Inductively defined sets, rule induction [4,5]
- Datatype induction, primitive recursion [5,7]
- General recursive functions, termination proofs [7]
- Proof automation, Isar (part 2) [8^b]
- Hoare logic, proofs about programs, invariants [8,9]
- C verification [9,10]
- Practice, questions, exam prep [10^c]

^aa1 due; ^ba2 due; ^ca3 due

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Disadvantages:

→ Semantically equivalent programs are not obviously equal.

→ e.g. "IF True THEN SKIP ELSE SKIP = SKIP" is not a true theorem.

→ Many concepts already present in the logic must be reinvented.

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Today: a shallow embedding for (interesting parts of) C semantics

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AutoCorres: verified translation from deeply embedded C to monadic representation

- Specifically designed for humans to do proofs over.

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modify – applies its argument to modify the state; returns ():

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Monads, Laws

Formally: a monad \mathbf{M} is a type constructor with two operations.

$\text{return} :: \alpha \Rightarrow \mathbf{M} \alpha$ $\text{bind} :: \mathbf{M} \alpha \Rightarrow (\alpha \Rightarrow \mathbf{M} \beta) \Rightarrow \mathbf{M} \beta$

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bind-assoc: $((a \gg= b) \gg= c) = (a \gg= (\lambda x. b x \gg= c))$

State Monad: Example

A fragment of C:

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void f(int *p) {  
    int x = *p;  
    if (x < 10) {  
        *p = x+1;  
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record state =

hp :: int ptr \Rightarrow int

f :: “int ptr \Rightarrow (state \Rightarrow (unit,state))”

f p \equiv

do {

x \leftarrow gets (λ s. hp s p);

if x < 10 **then**

 modify (hp_update (λ h. (h(p := x + 1))))

else

 return ()

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guard – fails when given condition applied to the state is False:

$\text{guard } P \equiv \text{get } \gg= (\lambda s. \text{assert } (P \ s))$

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f p ≡  
do {  
  y ← guard (λs. valid s p);  
  x ← gets (λs. hp s p);  
  if x < 10 then  
    modify (hp_update (λh. (h(p := x + 1))))  
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select – nondeterministic selection from a set:

$$\text{select } A \equiv \lambda s. ((A \times \{s\}), \text{False})$$

Demo

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Monadic while loop, defined **inductively**.

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$\text{whileLoop } C B$

- **condition** C : takes **loop parameter** and **state** as arguments, returns **bool**
- **monadic body** B : takes **loop parameter** as argument, return-value is the **updated** loop parameter
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Example: $\text{whileLoop } (\lambda p s. \text{hp } s \ p = 0) (\lambda p. \text{return } (\text{ptrAdd } p \ 1)) \ p$

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$$\frac{\neg C r s}{(\text{Some } (r,s), \text{Some } (r,s)) \in \text{while_results } C B} \text{ (terminate)}$$

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 $((('a \times 's) \text{ option}) \times ((('a \times 's) \text{ option})) \text{ set}$

$$\frac{\neg C r s}{(\text{Some } (r,s), \text{Some } (r,s)) \in \text{while_results } C B} \text{ (terminate)}$$

$$\frac{C r s \quad \text{snd } (B r s)}{(\text{Some } (r,s), \text{None}) \in \text{while_results } C B} \text{ (fail)}$$

Defining While Loops Inductively

Two-part definition: results and termination

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$$\frac{C r s \quad (r',s') \in \text{fst } (B r s) \quad (\text{Some } (r', s'), z) \in \text{while_results } C B}{(\text{Some } (r,s), z) \in \text{while_results } C B} \text{ (loop)}$$

Defining While Loops Inductively

Termination:

$$\begin{aligned} \text{while_terminates} &:: ('a \Rightarrow 's \Rightarrow \text{bool}) \Rightarrow \\ &('a \Rightarrow ('s \Rightarrow ('a \times 's) \text{ set} \times \text{bool})) \Rightarrow \\ &'a \Rightarrow 's \Rightarrow \text{bool} \end{aligned}$$

Defining While Loops Inductively

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$$\frac{\neg C r s}{\text{while_terminates } C B r s} \text{ (terminate)}$$

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Defining While Loops Inductively

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$\text{whileLoop } C B \equiv$

$(\lambda r s. (\{(r',s'). (\text{Some } (r, s), \text{Some } (r', s')) \in \text{while_results } C B\},$
 $(\text{Some } (r, s), \text{None}) \in \text{while_results} \vee$
 $\neg \text{while_terminates } C B r s))$

Hoare Logic over Nondeterministic State Monads

Partial correctness:

$$\{P\} m \{Q\} \equiv \forall s. P s \longrightarrow \forall (r,s') \in \text{fst } (m s). Q r s'$$

→ Post-condition Q is a predicate of return-value and result state.

Weakest Precondition Rules

$$\begin{array}{l} \{ \quad \} \text{ return } x \{ \lambda r s. P r s \} \quad \{ \quad \} \text{ get } \{P\} \quad \{ \quad \} \text{ put } x \{P\} \\ \{ \quad \} \text{ gets } f \{P\} \quad \{ \quad \} \text{ modify } f \{P\} \\ \{ \quad \} \text{ assert } P \{Q\} \quad \{ \quad \} \text{ fail } \{Q\} \end{array}$$

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$$\{\lambda s. P \times s\} \text{ return } x \{\lambda r s. P r s\} \quad \{ \quad \} \text{ get } \{P\} \quad \{ \quad \} \text{ put } x \{P\}$$

$$\{ \quad \} \text{ gets } f \{P\} \quad \{ \quad \} \text{ modify } f \{P\}$$

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Weakest Precondition Rules

$$\{\lambda s. P x s\} \text{ return } x \quad \{\lambda r s. P r s\} \quad \{\lambda s. P s s\} \text{ get } \{P\} \quad \{\lambda s. P () x\} \text{ put } x \{P\}$$

$$\{ \quad \} \text{ gets } f \{P\} \quad \{ \quad \} \text{ modify } f \{P\}$$

$$\{ \quad \} \text{ assert } P \{Q\} \quad \{ \quad \} \text{ fail } \{Q\}$$

Hoare Logic over Nondeterministic State Monads

Partial correctness:

$$\{P\} m \{Q\} \equiv \forall s. P s \longrightarrow \forall (r,s') \in \text{fst } (m s). Q r s'$$

→ Post-condition Q is a predicate of return-value and result state.

Weakest Precondition Rules

$$\{\lambda s. P \ x \ s\} \text{ return } x \ \{\lambda r \ s. P \ r \ s\} \quad \{\lambda s. P \ s \ s\} \text{ get } \{P\} \quad \{\lambda s. P \ () \ x\} \text{ put } x \ \{P\}$$

$$\{\lambda s. P \ (f \ s) \ s\} \text{ gets } f \ \{P\} \quad \{ \} \text{ modify } f \ \{P\}$$

$$\{ \} \text{ assert } P \ \{Q\} \quad \{ \} \text{ fail } \{Q\}$$

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$$\{\lambda s. P \ x \ s\} \text{ return } x \ \{\lambda r \ s. P \ r \ s\} \quad \{\lambda s. P \ s \ s\} \text{ get } \{P\} \quad \{\lambda s. P \ () \ x\} \text{ put } x \ \{P\}$$

$$\{\lambda s. P \ (f \ s) \ s\} \text{ gets } f \ \{P\} \quad \{\lambda s. P \ () \ (f \ s)\} \text{ modify } f \ \{P\}$$

$$\{ \quad \quad \quad \} \text{ assert } P \ \{Q\} \quad \{ \quad \quad \} \text{ fail } \{Q\}$$

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$$\{\{P\}\} m \{\{Q\}\} \equiv \forall s. P s \longrightarrow \forall (r,s') \in \text{fst } (m s). Q r s'$$

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Weakest Precondition Rules

$$\{\{\lambda s. P \ x \ s\}\} \text{return } x \{\{\lambda r \ s. P \ r \ s\}\} \quad \{\{\lambda s. P \ s \ s\}\} \text{get } \{\{P\}\} \quad \{\{\lambda s. P \ () \ x\}\} \text{put } x \{\{P\}\}$$

$$\{\{\lambda s. P \ (f \ s) \ s\}\} \text{gets } f \{\{P\}\} \quad \{\{\lambda s. P \ () \ (f \ s)\}\} \text{modify } f \{\{P\}\}$$

$$\{\{\lambda s. P \ \longrightarrow Q \ () \ s\}\} \text{assert } P \ \{\{Q\}\} \quad \{\{\} \} \text{fail } \{\{Q\}\}$$

Hoare Logic over Nondeterministic State Monads

Partial correctness:

$$\{\{P\}\} m \{\{Q\}\} \equiv \forall s. P s \longrightarrow \forall (r,s') \in \text{fst } (m s). Q r s'$$

→ Post-condition Q is a predicate of return-value and result state.

Weakest Precondition Rules

$$\{\{\lambda s. P \ x \ s\}\} \text{return } x \{\{\lambda r \ s. P \ r \ s\}\} \quad \{\{\lambda s. P \ s \ s\}\} \text{get } \{\{P\}\} \quad \{\{\lambda s. P \ () \ x\}\} \text{put } x \{\{P\}\}$$

$$\{\{\lambda s. P \ (f \ s) \ s\}\} \text{gets } f \{\{P\}\} \quad \{\{\lambda s. P \ () \ (f \ s)\}\} \text{modify } f \{\{P\}\}$$

$$\{\{\lambda s. P \ \longrightarrow Q \ () \ s\}\} \text{assert } P \{\{Q\}\} \quad \{\{\lambda .. \text{True}\}\} \text{fail } \{\{Q\}\}$$

More Hoare Logic Rules

$\{ \} \quad \} \text{ if } P \text{ then } f \text{ else } g \{ S \}$

More Hoare Logic Rules

$$\frac{P \implies \{Q\} f \{S} \quad \neg P \implies \{R\} g \{S}}{\{\lambda s.(P \longrightarrow Q s) \wedge (\neg P \longrightarrow R s)\} \text{ if } P \text{ then } f \text{ else } g \{S\}}$$

More Hoare Logic Rules

$$\frac{P \implies \{Q\} f \{S\} \quad \neg P \implies \{R\} g \{S\}}{\{\lambda s. (P \longrightarrow Q s) \wedge (\neg P \longrightarrow R s)\} \text{ if } P \text{ then } f \text{ else } g \{S\}}$$

$$\frac{\bigwedge x. \{B x\} g x \{C\} \quad \{A\} f \{B\}}{\{A\} \text{ do}\{ x \leftarrow f; g x \} \{C\}}$$

More Hoare Logic Rules

$$\frac{P \implies \{Q\} f \{S\} \quad \neg P \implies \{R\} g \{S\}}{\{\lambda s. (P \longrightarrow Q s) \wedge (\neg P \longrightarrow R s)\} \text{ if } P \text{ then } f \text{ else } g \{S\}}$$

$$\frac{\bigwedge x. \{B x\} g x \{C\} \quad \{A\} f \{B\}}{\{A\} \text{ do}\{ x \leftarrow f; g x \} \{C\}}$$

$$\frac{\{R\} m \{Q\} \quad \bigwedge s. P s \implies R s}{\{P\} m \{Q\}}$$

More Hoare Logic Rules

$$\frac{P \implies \{Q\} f \{S\} \quad \neg P \implies \{R\} g \{S\}}{\{\lambda s. (P \longrightarrow Q s) \wedge (\neg P \longrightarrow R s)\} \text{ if } P \text{ then } f \text{ else } g \{S\}}$$

$$\frac{\bigwedge x. \{B x\} g x \{C\} \quad \{A\} f \{B\}}{\{A\} \text{ do}\{ x \leftarrow f; g x \} \{C\}}$$

$$\frac{\{R\} m \{Q\} \quad \bigwedge s. P s \implies R s}{\{P\} m \{Q\}}$$

$$\frac{\bigwedge r. \{\lambda s. I r s \wedge C r s\} B \{I\} \quad \bigwedge r s. \llbracket I r s; \neg C r s \rrbracket \implies Q r s}{\{I r\} \text{ whileLoop } C B r \{Q\}}$$

Demo

We have seen today

- Deep and shallow embeddings
- Isabelle records
- Nondeterministic State Monad with Failure
- Monadic Weakest Precondition Rules