



COMP4161 Advanced Topics in Software Verification

C

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Last Time

- → Deep and shallow embeddings
- → Isabelle records
- → Nondeterministic State Monad with Failure
- → Monadic Weakest Precondition Rules

Content

→ Foundations & Principles Intro. Lambda calculus, natural deduction [1,2]• Higher Order Logic, Isar (part 1) $[2,3^{a}]$ Term rewriting [3,4] → Proof & Specification Techniques Inductively defined sets, rule induction [4,5] Datatype induction, primitive recursion [5,7] General recursive functions, termination proofs [7] Proof automation, Isar (part 2) [8^b] Hoare logic, proofs about programs, invariants [8,9] C verification [9,10] Practice, questions, exam prep $[10^{c}]$

^aa1 due: ^ba2 due: ^ca3 due

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Today we will learn about AutoCorres and C verification.

Demo

Introduction to AutoCorres and wp

A Brief Overview of C and Simpl

Main new problems in verifying C programs:

- → expressions with side effects
- → more control flow (do/while, for, break, continue, return)
- → local variables and blocks
- → functions & procedures
- → concrete C data types
- → C memory model and C pointers

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C is not a nice language for reasoning.

Things are going to get ugly.

AutoCorres will help.

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C Parser: parses C, produces Simpl definitions in Isabelle

- → written by Michael Norrish, NICTA and ANU
- → Handles a non-trivial subset of C
- → Originally written to verify seL4's C implementation
- → AutoCorres is built on top of the C Parser

Commands in Simpl

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a = a * b; x = f(h); i = ++i - i++; x = f(h) + g(x);
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Alternative:

Explicitly model nondeterministic order of execution in expressions.

Control flow

```
do { c } while (condition);
automatically translates into:
                  c; while (condition) { c }
Similarly:
            for (init; condition; increment) { c }
becomes
           init; while (condition) { c; increment; }
```

```
while (condition) {
   foo;
   if (Q) continue;
   bar;
   if (P) break;
}
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Non-local control flow: **continue** goes to condition, **break** goes to end.

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→ throw exception 'continue', catch at end of body.

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Non-local control flow: **continue** goes to condition, **break** goes to end. Can be modelled with exceptions:

- → throw exception 'continue', catch at end of body.
- → throw exception 'break', catch after loop.

Break/continue

Break/continue example becomes:

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try {
    while (condition) {
        try {
            foo;
            if (Q) { exception = 'continue'; throw; }
            bar;
            if (P) { exception = 'break'; throw; }
            } catch { if (exception == 'continue') SKIP else throw; }
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Need to be careful that only the translation has access to exception state.

Return

```
if (P) return x;
foo;
return y;
```

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Similar non-local control flow. Similar solution: use throw/try/catch

```
try {
    if (P) { return_val = x; exception = 'return'; throw; }
    foo;
    return_val = y; exception = 'return'; throw;
} catch {
    SKIP
}
```

AutoCorres

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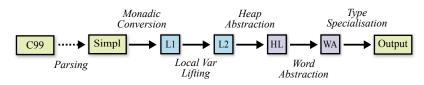
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For each Simpl definition C and its generated shallow embedding A:

- → AutoCorres proves an Isabelle theorem stating that *C* refines *A*
- \rightarrow Every behaviour of C has a corresponding behaviour of A
- → Refinement guarantees that properties proved about A will also hold for C.
- → (Provided that A never fails. c.f. Total Correctness)

AutoCorres Process



L1: initial monadic shallow embedding

L2: local variables introduced by λ -bindings

HL: heap state abstracted into a set of **typed heaps**

WA: machine words abstracted to idealised integers or nats

Output: human-readable output with type strengthening, polish

On-the-fly proof:

Simpl refines L1 refines L2 refines HL refines WA refines Output

Example: C99

We will use the following example program to illustrate each of the phases.

```
unsigned some_func(unsigned *a, unsigned *b, unsigned c) {
  unsigned *p = NULL;

if (c > 10u){
   p = a;
} else {
   p = b;
}

return *p;
}
```

Example: Simpl

Example: L1 (monadic shallow embedding)

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State type is the same as Simpl, namely a record with fields:

- → globals: heap and type information
- \rightarrow a_', b_', c_', p_' (parameters and local variables)
- → ret_unsigned_', global_exn_var_' (return value, exception type)

Example: L2 (local variables lifted)

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State is a record with just the **globals** field

- → function now takes its parameters as arguments
- \rightarrow local variable **p** now passed via λ -binding
- → L2_gets annotated with local variable names
- → This ensures preservation by later AutoCorres phases

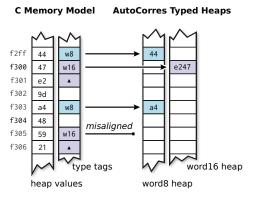
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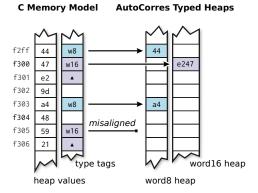
State is a record with a set of **is_valid_** and **heap_** fields:

- → These store **pointer validity** and **heap contents** respectively, per type
- → above example has only 32-bit word pointers

Heap Abstraction



Heap Abstraction



C Memory Model: by Harvey Tuch

- → **Heap** is a mapping from 32-bit addresses to bytes: 32 word \Rightarrow 8 word
- → Heap Type Description stores type information for each heap location

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In the example, the unsigned argument c is now of type nat

- → The function also returns a nat result
- → The heap is not abstracted, hence the call to unat

Example: Output (type strengthening and polish)

```
some_func' a b c \equiv DO p \leftarrow oreturn (if 10 < c then a else b); oguard (\lambdas. is_valid_w32 s p); ogets (\lambdas. unat (heap_w32 s p)) OD
```

Example: Output (type strengthening and polish)

Type Strengthening:

- → Tries to convert output to a more restricted monad
- → The above is in the option monad because it doesn't modify the state, but might fail
- → The **type** of the option monad implies it cannot modify state

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Polish:

- → Simplify output as much as possible
- ightharpoonup The condition has been rewritten to a return because the condition 10 < c doesn't depend on the state

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Can be controlled by the ts_force option of AutoCorres

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returnOk x \equiv \text{return (Inr } x) throwError e \equiv \text{return (Inl } e)
lift b \equiv (\lambda x. \text{ case } x \text{ of Inl } e \Rightarrow \text{throwError } e \mid \text{Inr } r \Rightarrow b r)
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returnOk x \equiv return (lnr x) throwError e \equiv return (lnl e) lift b \equiv (\lambda x. case x of lnl e \Rightarrow throwError e \mid \text{lnr } r \Rightarrow b r) bindE: a \gg = E b \equiv a \gg = (\text{lift b})
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bindE: $a \gg = E$ $b \equiv a \gg = (lift b)$ **Do notation:** doE ... odE

New kind of Hoare triples to model normal and exceptional cases:

$${P} f {Q}, {E}$$

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Weakest Precondition Rules:

$${P \times \text{returnOk} \times \{P\}, \{E\}}$$
 ${E \in \text{throwError } e \in \{P\}, \{E\}\}$

New kind of Hoare triples to model normal and exceptional cases:

Weakest Precondition Rules:

Today we have seen

- → The automated proof method wp
- → The C Parser and translating C into Simpl
- → AutoCorres and translating Simpl into monadic form
- → The option and exception monads