

Tree Transducers and their Applications to XML

Tarragona Lectures
22-26.3.2004

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Overview

- 1st Day: History of Tree Transducers, Finite-State Models
- 2nd Day: Context-Free Models
- TODAY: Properties of Macro Tree Transducers**
- 4th Day: XML Type Checking using MTTs
- 5th Day: Complexity of MTTs

Today

1. Expressive Power of Macro Tree Transducers
2. Closure under regular look ahead
3. Inverses of MTTs preserve REGT

Macro Tree Transducer

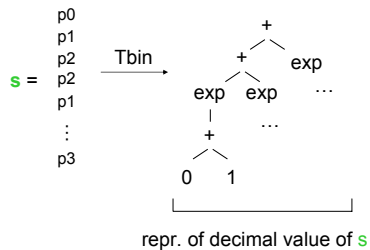
Notation For ranked alphabet Σ and a set A
 $\langle \Sigma, S \rangle := \{ \langle \sigma, a \rangle^{(k)} \mid \sigma \in \Sigma^{(k)}, a \in A \}$

MTT $M = (Q, \Sigma, \Delta, q_0, R)$
 $R: \langle q, \sigma(x_1, \dots, x_k) \rangle (y_1, \dots, y_m) \rightarrow t \in T_{\langle q, x_k \rangle \cup \Delta}(Y_m)$
 \uparrow
 $\in \Sigma^{(k)}$
 $\in Q^{(m)}$

Sentential forms: $\xi, \xi' \in T_{\langle Q, \Sigma \rangle \cup \Delta}$

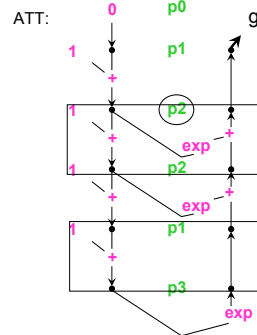
$\xi \Rightarrow_M \xi'$ iff \exists node $u: \xi/u = \langle q, \sigma(s_1, \dots, s_k) \rangle (\xi_1, \dots, \xi_m)$ and
 $\xi' = \xi [u \leftarrow t [x_i \leftarrow s_i] [y_j \leftarrow \xi_j]]$.

Macro Tree Transducer

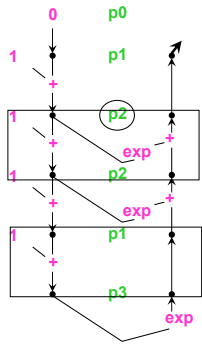


Can NOT be done by TR , but by ATT. Can it be done by an MTT?

Macro Tree Transducer

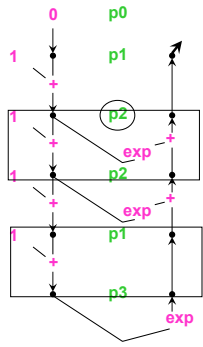


Macro Tree Transducer

ATT: 

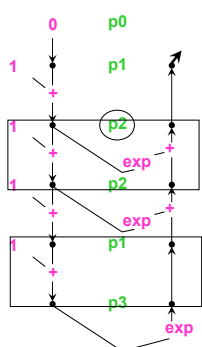
MTT: $\langle q_0, p0(x) \rangle \rightarrow \langle q, x \rangle(0)$
 $\langle q, p1(x) \rangle(y) \rightarrow \langle q, x \rangle(+ (1, y))$

Macro Tree Transducer


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 $\langle q, p1(x) \rangle(y) \rightarrow \langle q, x \rangle(+ (1, y))$
 $\langle q, p2(x) \rangle(y) \rightarrow +(exp(y), \langle q, x \rangle)$

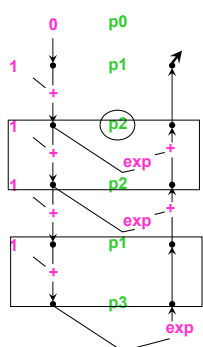
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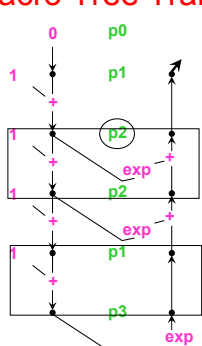
NO! 

Macro Tree Transducer

ATT: 

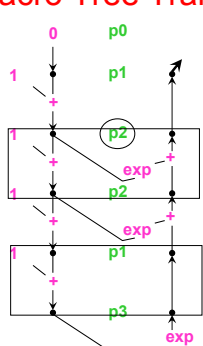
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 $\langle q, p3(x) \rangle(y) \rightarrow exp(y)$

Macro Tree Transducer

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MTT: $\langle q_0, p0(x) \rangle \rightarrow \langle q, x \rangle(0)$
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 DETERMINISTIC, can be made TOTAL.

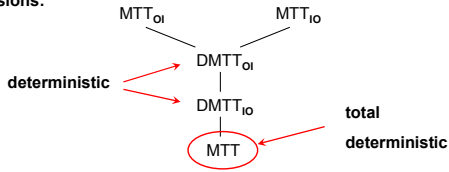
OI vs. IO

For the **partial nondet** case (like for CFT grammar):

- unrestricted = OI, and
- MTT_{OI} and MTT_{IO} are incomparable

(to show this, fix an input tree and consider the MTT as a CFT grammar)

Inclusions:



1. Expressive Power of MTTs

Theorem: $ATT \subseteq MTT$.

1. Expressive Power of MTTs

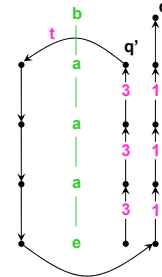
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↑ total, det.
Noncircular (total, det.)

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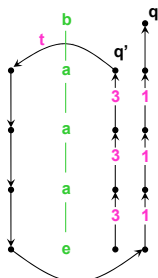
Proof idea: "Don't go back, but JUMP back."



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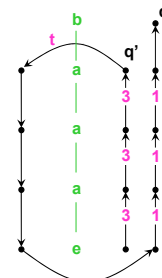


$$\begin{aligned}
 & \langle q, ba^3e \rangle \\
 \Rightarrow_M & \langle q, a^3e \rangle (t \langle q', a^3e \rangle) \\
 \Rightarrow_M & 1 \langle q, a^2e \rangle (t \langle q', a^3e \rangle) \\
 \Rightarrow_M^2 & 1^3 \langle q, e \rangle (t \langle q', a^3e \rangle)
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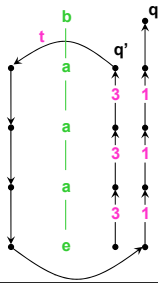
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"push" into parameter what we need later!



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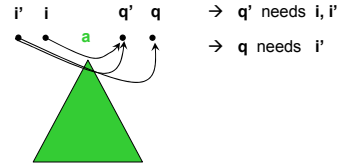
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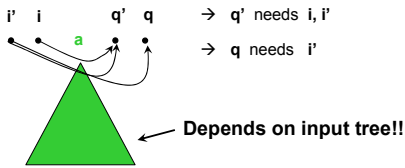
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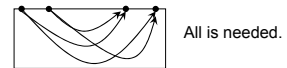
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Solution 2: Assume worst case (all "needs" and stop at circularities.



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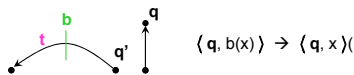
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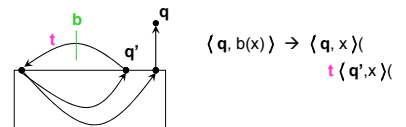
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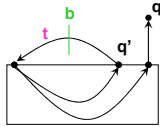
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$$\langle q, b(x) \rangle \rightarrow \langle q, x \rangle (\langle q', x \rangle (\langle q', x \rangle (\dots)))$$

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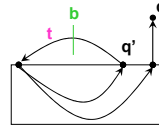
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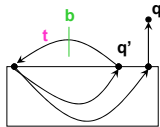
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$$\langle q, b(x) \rangle \rightarrow \langle q, x \rangle (\langle q', x \rangle (\langle q', x \rangle (\dots \text{dummy} \dots)))$$

1. Expressive Power of MTTs

Do ATT and MTT have the **same power??**

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$$\begin{aligned} \langle q_0, a(x_1) \rangle &\rightarrow \langle q, x_1 \rangle (\langle q, x_1 \rangle (e)) \\ \langle q, a(x_1) \rangle (y_1) &\rightarrow \langle q, x_1 \rangle (\langle q, x_1 \rangle (y_1)) \\ \langle q, e \rangle (y_1) &\rightarrow a(y_1) \end{aligned}$$

$$\langle q_0, a^n(e) \rangle \Rightarrow_M \langle q, a^{n-1}(e) \rangle (\langle q, a^{n-1}(e) \rangle (e))$$

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Do ATT and MTT have the **same power??**

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$$\langle q_0, a^n(e) \rangle \Rightarrow_M \langle q, a^{n-1}(e) \rangle (\langle q, a^{n-1}(e) \rangle (e))$$

$$\Rightarrow_{M^2} \langle q, a^{n-2}(e) \rangle (\langle q, a^{n-2}(e) \rangle (\langle q, a^{n-2}(e) \rangle (e)))$$

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1. Expressive Power of MTTs

Size-to-Height increase of MTTs can be EXPONENTIAL!!

$$\begin{aligned} \langle q_0, a(x_1) \rangle &\rightarrow \langle q, x_1 \rangle (\langle q, x_1 \rangle (e)) \\ \langle q, a(x_1) \rangle (y_1) &\rightarrow \langle q, x_1 \rangle (\langle q, x_1 \rangle (y_1)) \\ \langle q, e \rangle (y_1) &\rightarrow a(y_1) \end{aligned}$$

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1. Expressive Power of MTTs

Size-to-Height increase of MTTs can be EXPONENTIAL!!

Theorem: $ATT \subsetneq MTT$.

(size-to-height inc. of ATTs is LINEAR)

$$\begin{aligned} \langle q_0, a^n(e) \rangle &\Rightarrow_M \langle q, a^{n-1}(e) \rangle (\langle q, a^{n-1}(e) \rangle (e)) \\ &\Rightarrow_{M^2} \langle q, a^{n-2}(e) \rangle (\langle q, a^{n-2}(e) \rangle (\langle q, a^{n-2}(e) \rangle (\langle q, a^{n-2}(e) \rangle (e)))) \\ &\Rightarrow_{M^n} \underbrace{\langle q, e \rangle (\langle q, e \rangle (\dots \langle q, e \rangle (e) \dots))}_{2^n \text{ times}} \Rightarrow_{M^n} a^{2^n}(e) \end{aligned}$$

1. Expressive Power of MTTs

Size increase of MTTs?

→ At most DOUBLE EXP.

EXERCISE:

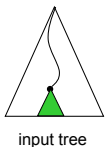
Can you give an example of an MTT with DEXP size inc.?

(hint: try to generalize the previous example to output a full k-ary tree, instead of a monadic one)

2. Closure under Reg. Look-Ah.

Let $A = (P, \Sigma, \delta)$ be a (deterministic) BU finite tree automaton.

Regular look-ahead = ability to determine A's state for any node of the input tree.



What is $\delta(\triangle)$??

2. Closure under Reg. Look-Ah.

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$MTT^R = MTT$ w. LA = B-REL ; MTT

Rules:

$$\langle q, \sigma(x_1, \dots, x_k) \rangle (y_1, \dots, y_m) \rightarrow t \langle p_1, \dots, p_k \rangle$$

↑ A's state for x_1 ↑ A's state for x_k

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↑ ↑
A's state for x_1 A's state for x_k

$\text{rhs}(q, \sigma, \langle p_1, \dots, p_k \rangle) := t$

2. Closure under Reg. Look-Ah.

Theorem: $MTT^R \subseteq MTT$.

Proof. Let $M = (Q, \Sigma, \Delta, q_0, R, A)$ an MTT^R with $P = \{p_1, \dots, p_n\}$.

$MTT M' := (Q \cup \{\tau^{(n)}\}, \Sigma, \Delta, q_0, K)$

K:

$\langle q, \sigma(x_1, \dots, x_k) \rangle (y_1, \dots, y_m) \rightarrow$

$\text{rhs}(q, \sigma, \langle p_1, \dots, p_1 \rangle) \dots \text{rhs}(q, \sigma, \langle p_n, \dots, p_n \rangle)$

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K:

$\langle \tau, \sigma(x_1, \dots, x_k) \rangle (y_1, \dots, y_m) \rightarrow$

$\delta(\sigma, p_1, \dots, p_1) = p_j \quad \delta(\sigma, p_n, \dots, p_n) = p_d$

Example:

$\Sigma = \Delta = \{a^{(1)}, b^{(1)}, e^{(0)}\}$

Nondeterministic TOP:

$\begin{matrix} a \\ b \\ b \\ a \\ b \\ a \\ a \\ e \end{matrix} \xrightarrow{T} \begin{matrix} a \\ a \\ e \end{matrix}$
 largest subtree without b

$q0(e) \rightarrow e$
 $q0(a/b(x)) \rightarrow q0(x)$
 $q0(a(x)) \rightarrow a(q(x))$
 $q(a(x)) \rightarrow a(q(x))$
 $q(e) \rightarrow e$

Example:

$\Sigma = \Delta = \{a^{(1)}, b^{(1)}, e^{(0)}\}$

$\begin{matrix} a \\ b \\ b \\ a \\ b \\ a \\ a \\ e \end{matrix} \xrightarrow{T} \begin{matrix} a \\ a \\ e \end{matrix}$
 largest subtree without b

$TOP^R M$ for T :

Look-ahead Automaton A:

$\delta(e) = p_1$
 $\delta(a, p_1) = p_1$
 $\delta(b, p_1) = p_2$
 $\delta(a/b, p_2) = p_2$

Example:

$\Sigma = \Delta = \{a^{(1)}, b^{(1)}, e^{(0)}\}$

$\begin{matrix} p_2 & a \\ p_2 & b \\ p_2 & b \\ p_2 & a \\ p_2 & b \\ p_1 & a \\ p_1 & a \\ p_1 & e \end{matrix} \xrightarrow{T} \begin{matrix} a \\ a \\ e \end{matrix}$
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Example:

$\Sigma = \Delta = \{ a^{(1)}, b^{(1)}, e^{(0)} \}$

$$\begin{array}{c}
 p2 \ a \\
 p2 \ b \\
 p2 \ b \\
 p2 \ a \\
 p2 \ b \\
 p1 \ a \\
 p1 \ e
 \end{array}
 \xrightarrow{T}
 \begin{array}{c}
 a \\
 a \\
 e
 \end{array}$$

largest subtree without b

TOP^R M for T:

Look-ahead Automaton A:

$\delta(e) = p1$
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 $\delta(b, p1) = p2$
 $\delta(a/b, p2) = p2$

$\langle q0, a/b(x_i) \rangle \rightarrow \langle id, x_i \rangle \quad \langle p1 \rangle$
 $\langle q0, a/b(x_i) \rangle \rightarrow \langle q0, x_i \rangle \quad \langle p2 \rangle$
 $\langle q0, e \rangle \rightarrow e \quad \langle p1/p2 \rangle$
 $\langle id, a/b(x_i) \rangle \xrightarrow[e]{a/b} \langle id, x_i \rangle \quad \langle p1/p2 \rangle$

TOP^R M for T:

Look-ahead Automaton A:

$\delta(e) = p1$
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 $\langle id, a/b(x_i) \rangle \xrightarrow[e]{a/b} \langle id, x_i \rangle \quad \langle p1/p2 \rangle$

$\langle q0, a/b(x_i) \rangle \rightarrow \langle \tau, x_i \rangle (\langle id, x_i \rangle, \langle q0, x_i \rangle)$
 $\langle id, a/b(x_i) \rangle \rightarrow a/b(\langle id, x_i \rangle)$
 $\langle q0/id, e \rangle \rightarrow e$
 $\langle \tau, a(x_i) \rangle (y_1, y_2) \rightarrow \langle \tau, x_i \rangle$

TOP^R M for T:

Look-ahead Automaton A:

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 $\delta(b, p1) = p2$
 $\delta(a/b, p2) = p2$

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 $\langle q0, a/b(x_i) \rangle \rightarrow \langle q0, x_i \rangle \quad \langle p2 \rangle$
 $\langle q0, e \rangle \rightarrow e \quad \langle p1/p2 \rangle$
 $\langle id, a/b(x_i) \rangle \xrightarrow[e]{a/b} \langle id, x_i \rangle \quad \langle p1/p2 \rangle$

$\langle q0, a/b(x_i) \rangle \rightarrow \langle \tau, x_i \rangle (\langle id, x_i \rangle, \langle q0, x_i \rangle)$
 $\langle id, a/b(x_i) \rangle \rightarrow a/b(\langle id, x_i \rangle)$
 $\langle q0/id, e \rangle \rightarrow e$
 $\langle \tau, a(x_i) \rangle (y_1, y_2) \rightarrow \langle \tau, x_i \rangle$

TOP^R M for T:

Look-ahead Automaton A:

$\delta(e) = p1$
 $\delta(a, p1) = p1$
 $\delta(b, p1) = p2$
 $\delta(a/b, p2) = p2$

$\langle q0, a/b(x_i) \rangle \rightarrow \langle id, x_i \rangle \quad \langle p1 \rangle$
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 $\langle \tau, e \rangle (y_1, y_2) \rightarrow y_1$

MTT N for T.

$$\begin{array}{c}
 a \\
 \bullet b \\
 b \\
 a \\
 b \\
 a \\
 a \\
 e
 \end{array}
 \xrightarrow{T}
 \begin{array}{c}
 a \\
 a \\
 e
 \end{array}$$

$\langle q0, a(\bullet) \rangle \Rightarrow_N \langle \tau, \bullet \rangle (\langle id, \bullet \rangle, \langle q0, \bullet \rangle)$

$\langle q0, a/b(x_i) \rangle \rightarrow \langle \tau, x_i \rangle (\langle id, x_i \rangle, \langle q0, x_i \rangle)$
 $\langle id, a/b(x_i) \rangle \rightarrow a/b(\langle id, x_i \rangle)$
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 $\langle \tau, b(x_i) \rangle (y_1, y_2) \rightarrow \langle \tau, x_i \rangle (y_2, y_2)$
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MTT N for T.

<pre> a b • b a b a a e </pre> <p>\xrightarrow{T}</p> <pre> a a e </pre> <p>$\langle q0, ab.. \rangle \Rightarrow_N^* \langle q0, \bullet \rangle$</p>	$\langle q0, a/b(x_1) \rangle \rightarrow \langle \tau, x_1 \rangle (\langle id, x_1 \rangle, \langle q0, x_1 \rangle)$ $\langle id, a/b(x_1) \rangle \rightarrow a/b(\langle id, x_1 \rangle)$ $\langle q0/id, e \rangle \rightarrow e$ $\langle \tau, a(x_1) \rangle (Y_1, Y_2) \rightarrow \langle \tau, x_1 \rangle (Y_1, Y_2)$ $\langle \tau, b(x_1) \rangle (Y_1, Y_2) \rightarrow \langle \tau, x_1 \rangle (Y_2, Y_2)$ $\langle \tau, e \rangle (Y_1, Y_2) \rightarrow Y_1$ <p>MTT N for T.</p>
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<pre> a b b • a b a a e </pre> <p>\xrightarrow{T}</p> <pre> a a e </pre> <p>$\langle q0, ab.. \rangle \Rightarrow_N^* \langle q0, \bullet \rangle$</p>	$\langle q0, a/b(x_1) \rangle \rightarrow \langle \tau, x_1 \rangle (\langle id, x_1 \rangle, \langle q0, x_1 \rangle)$ $\langle id, a/b(x_1) \rangle \rightarrow a/b(\langle id, x_1 \rangle)$ $\langle q0/id, e \rangle \rightarrow e$ $\langle \tau, a(x_1) \rangle (Y_1, Y_2) \rightarrow \langle \tau, x_1 \rangle (Y_1, Y_2)$ $\langle \tau, b(x_1) \rangle (Y_1, Y_2) \rightarrow \langle \tau, x_1 \rangle (Y_2, Y_2)$ $\langle \tau, e \rangle (Y_1, Y_2) \rightarrow Y_1$ <p>MTT N for T.</p>
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2. Closure under Reg. Look-Ah.

Theorem: $MTT^R \subseteq MTT$.

How many times is each node visited??

- for B-REL ; MTT
- for the corresponding MTT (without rLA)

EXERCISE

Why is this construction useful??

→ (top-down) READ ONLY access to **s**

```

match s => {
  case a -> ..
  case b -> ..
  .. }

```

E.g. in Functional Languages:

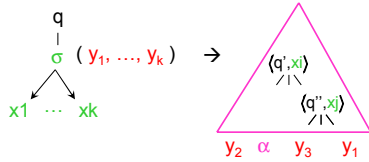
3. Inverses of MTTs preserve REGT

Theorem: If $M \in \text{MTT}$ and $K \in \text{REGT}$, then $M^{-1}(K) \in \text{REGT}$.

Proof. Let $M = (Q, \Sigma, \Delta, q_0, R)$ and

$A = (P, \Delta, \delta, F)$ be a det. bu TA with $L(A) = K$.

Idea: Run A on the rhs's of the rules of M.



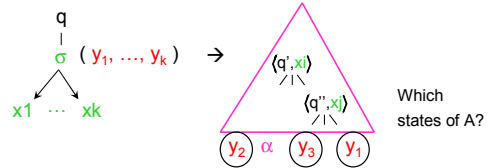
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Define $B = (D, \Sigma, \beta, G)$

$D =$ all mappings d s.t. $\forall q \in Q^{(m)}, d(q): P^m \rightarrow P$

$\forall \sigma \in \Sigma^{(k)}$ and $d_1, \dots, d_k \in D$ let $\beta(\sigma, d_1, \dots, d_k) := d$
where $\forall q \in Q^{(m)}, p_1, \dots, p_m \in P:$

$$d(q)(p_1, \dots, p_m) = \delta'(\text{rhs}(q, \sigma) [y_j \leftarrow p_j])$$

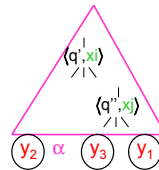
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E.g. $d(q)(p_1, p_1, \dots, p_1) = ?$



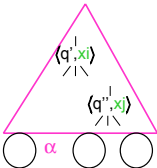
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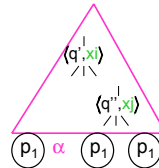
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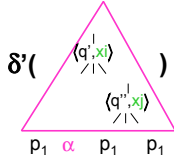
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E.g. $d(q) (p_1, p_1, \dots, p_1) = ?$



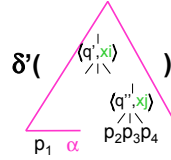
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E.g. $d(q) (p_1, p_1, \dots, p_1) = ?$



$$\delta'((q'', x_j), p_2, p_3, p_4) = d_j(q'') (p_2, p_3, p_4)$$

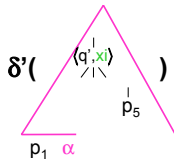
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E.g. $d(q) (p_1, p_1, \dots, p_1) = ?$



$$\delta'((q'', x_j), p_2, p_3, p_4) = d_j(q'') (p_2, p_3, p_4) = p_5$$

3. Inverses of MTTs preserve REGT

Theorem: If $M \in \text{MTT}$ and $K \in \text{REGT}$, then $M^{-1}(K) \in \text{REGT}$.

EXERCISE:

→ What is the complexity of this construction?

(hint: take as measure the number of states of the new automaton.)