NICTA

COMP 4161

NICTA Advanced Course

Advanced Topics in Software Verification

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$$\{P\} \ldots \{Q\}$$

Last Time

- Syntax of a simple imperative language
- Operational semantics
- Program proof on operational semantics
- Hoare logic rules
- Soundness of Hoare logic

Content

➜ Intro & motivation, getting started [1]

➜ Foundations & Principles

- Lambda Calculus, natural deduction [1,2]
- Higher Order Logic [3^a]
- Term rewriting [4]

➜ Proof & Specification Techniques

- Isar [5]
- Inductively defined sets, rule induction [6^b]
- Datatypes, recursion, induction [7^c, 8]
- Calculational reasoning, code generation [9]
- Hoare logic, proofs about programs [10^d,11,12]

^{a}a1 due; ^{b}a2 due; ^{c}session break; ^{d}a3 due

Automation?

Last time: Hoare rule application is nicer than using operational semantic.

BUT:

- ➜ it's still kind of tedious
- ➜ it seems boring & mechanical

Automation?

Invariant

Problem: While – need creativity to find right (invariant) P

Solution:

- ➜ annotate program with invariants
- ➜ then, Hoare rules can be applied automatically

Example:

$\{M = 0 \wedge N = 0\}$

WHILE $M \neq a$ INV $\{N = M * b\}$ DO $N := N + b; M := M + 1$ OD

$\{N = a * b\}$

Weakest Preconditions

pre $c\ Q$ **= weakest** P **such that** $\{P\}\ c\ \{Q\}$

With annotated invariants, easy to get:

$$
\begin{array}{lcl}
\text{pre SKIP } Q & = & Q \\
\text{pre } (x := a)\ Q & = & \lambda\sigma.\ Q(\sigma(x := a\sigma)) \\
\text{pre } (c_1; c_2)\ Q & = & \text{pre } c_1 \text{ (pre } c_2\ Q) \\
\text{pre } (\text{IF } b \text{ THEN } c_1 \text{ ELSE } c_2)\ Q & = & \lambda\sigma.\ (b \longrightarrow \text{pre } c_1\ Q\ \sigma) \wedge \\
 & & \qquad (\neg b \longrightarrow \text{pre } c_2\ Q\ \sigma) \\
\text{pre } (\text{WHILE } b \text{ INV } I \text{ DO } c \text{ OD})\ Q & = & I
\end{array}
$$

Verification Conditions

$\{\text{pre } c\ Q\}\ c\ \{Q\}$ **only true under certain conditions**

These are called **verification conditions** vc $c\ Q$:

$$
\begin{aligned}
\text{vc SKIP } Q &= \text{True} \\
\text{vc } (x := a)\ Q &= \text{True} \\
\text{vc } (c_1; c_2)\ Q &= \text{vc } c_2\ Q \wedge (\text{vc } c_1\ (\text{pre } c_2\ Q)) \\
\text{vc } (\text{IF } b \text{ THEN } c_1 \text{ ELSE } c_2)\ Q &= \text{vc } c_1\ Q \wedge \text{vc } c_2\ Q \\
\text{vc } (\text{WHILE } b \text{ INV } I \text{ DO } c \text{ OD})\ Q &= (\forall \sigma.\ I\sigma \wedge b\sigma \longrightarrow \text{pre } c\ I\ \sigma) \wedge \\
&\quad\ (\forall \sigma.\ I\sigma \wedge \neg b\sigma \longrightarrow Q\ \sigma) \wedge \\
&\quad\ \text{vc } c\ I
\end{aligned}
$$

$$\text{vc } c\ Q \wedge (P \Longrightarrow \text{pre } c\ Q) \Longrightarrow \{P\}\ c\ \{Q\}$$

Syntax Tricks

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- $x := \lambda\sigma.\ 1$ instead of $x := 1$ sucks
- $\{\lambda\sigma.\ \sigma\ x = n\}$ instead of $\{x = n\}$ sucks as well

Problem: program variables are functions, not values

Solution: distinguish program variables syntactically

Choices:

- declare program variables with each Hoare triple
  - nice, usual syntax
  - works well if you state full program and only use vcg
- separate program variables from Hoare triple (use extensible records), indicate usage as function syntactically
  - more syntactic overhead
  - program pieces compose nicely

Records in Isabelle

Records are a tuples with named components

Example:

record A = a :: nat
b :: int

- Selectors: a :: A $\Rightarrow$ nat, b :: A $\Rightarrow$ int, a $r = \text{Suc}\ 0$
- Constructors: $(\!|\ \text{a} = \text{Suc}\ 0,\ \text{b} = -1\ |\!)$
- Update: $r(\!|\ \text{a} := \text{Suc}\ 0\ |\!)$

Records are extensible:

record B = A +
c :: nat list

$$(\!|\ \text{a} = \text{Suc}\ 0,\ \text{b} = -1,\ \text{c} = [0, 0]\ |\!)$$

Arrays

Depending on language, model arrays as functions:

- ➜ Array access = function application:

  a[i] $=$ a i

- ➜ Array update = function update:

  a[i] :== v $=$ a :== a(i:= v)

Use lists to express length:

- ➜ Array access = nth:

  a[i] $=$ a ! i

- ➜ Array update = list update:

  a[i] :== v $=$ a :== a[i:= v]

- ➜ Array length = list length:

  a.length $=$ length a

Pointers

Choice 1

datatype ref = Ref int | Null

types heap = int $\Rightarrow$ val

datatype val = Int int | Bool bool | Struct_x int int bool | . . .

- hp :: heap, p :: ref
- Pointer access: *p $=$ the_Int (hp (the_addr p))
- Pointer update: *p :== v $=$ hp :== hp ((the_addr p) := v)

- a bit klunky
- gets even worse with structs
- lots of value extraction (the_Int) in spec and program

Pointers

Choice 2 (Burstall '72, Bornat '00)

struct with next pointer and element

datatype	ref	= Ref int | Null
types	next_hp	= int $\Rightarrow$ ref
types	elem_hp	= int $\Rightarrow$ int

- ➜ next :: next_hp, elem :: elem_hp, p :: ref
- ➜ Pointer access: p$\rightarrow$next $=$ next (the_addr p)
- ➜ Pointer update: p$\rightarrow$next :== v $=$ next :== next ((the_addr p) := v)

- ➜ a separate heap for each struct field
- ➜ buys you p$\rightarrow$next $\neq$ p$\rightarrow$elem automatically (aliasing)
- ➜ still assumes type safe language

DEMO

We have seen today ...

- ➜ Weakest precondition
- ➜ Verification conditions
- ➜ Example program proofs
- ➜ Arrays, pointers