

## **COMP 4161**

NICTA Advanced Course

## **Advanced Topics in Software Verification**

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$$\{P\}\,\ldots\{Q\}$$

## Slide 1

## Last Time



- → Syntax of a simple imperative language
- → Operational semantics
- → Program proof on operational semantics
- → Hoare logic rules
- → Soundness of Hoare logic

Slide 2

Content

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→	Intro	Ŏ.	motivation,	getting	started	

[1]

→ Foundations & Principles

Lambda Calculus, natural deduction	[1,2]
Higher Order Logic	[3]
Term rewriting	[4 <sup>a</sup> ]

→ Proof & Specification Techniques

Inductively defined sets, rule induction	[5]
Datatypes, recursion, induction	[6, 7]
Automated proof and disproof	[7]
Hoare logic, proofs about programs, refinement	[8 <sup>b</sup> ,9 <sup>c</sup> ,10]
Isar, locales	[11 <sup>d</sup> ,12]

<sup>&</sup>lt;sup>a</sup> a1 due; <sup>b</sup> a2 due; <sup>c</sup> session break; <sup>d</sup> a3 due

## Slide 3

Automation?



INI

Last time: Hoare rule application is nicer than using operational semantic.

## BUT:

- → it's still kind of tedious
- → it seems boring & mechanical

## Automation?

Slide 4

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#### Invariant



**Problem:** While – need creativity to find right (invariant) P

#### Solution:

- → annotate program with invariants
- → then, Hoare rules can be applied automatically

#### Example:

$$\{M=0 \land N=0\}$$
 WHILE  $M \neq a$  INV  $\{N=M*b\}$  DO  $N:=N+b; M:=M+1$  OD  $\{N=a*b\}$ 

#### Slide 5

#### Weakest Preconditions



pre 
$$c$$
  $Q$  = weakest  $P$  such that  $\{P\}$   $c$   $\{Q\}$ 

With annotated invariants, easy to get:

$$\begin{array}{llll} \operatorname{pre} \operatorname{SKIP} Q & = & Q \\ \operatorname{pre} \left( x := a \right) Q & = & \lambda \sigma. \ Q (\sigma (x := a \sigma)) \\ \operatorname{pre} \left( c_1 ; c_2 \right) Q & = & \operatorname{pre} c_1 \left( \operatorname{pre} c_2 Q \right) \\ \operatorname{pre} \left( \operatorname{IF} b \operatorname{THEN} c_1 \operatorname{ELSE} c_2 \right) Q & = & \lambda \sigma. \left( b \longrightarrow \operatorname{pre} c_1 Q \sigma \right) \wedge \\ & & (\neg b \longrightarrow \operatorname{pre} c_2 Q \sigma) \\ \operatorname{pre} \left( \operatorname{WHILE} b \operatorname{INV} I \operatorname{DO} c \operatorname{OD} \right) Q & = & I \end{array}$$

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## **Verification Conditions**



#### $\{pre\ c\ Q\}\ c\ \{Q\}$ only true under certain conditions

These are called **verification conditions** vc c Q:

$$\begin{array}{lll} \operatorname{vc} \operatorname{SKIP} Q & = & \operatorname{True} \\ \operatorname{vc} \left( x := a \right) Q & = & \operatorname{True} \\ \operatorname{vc} \left( c_1 ; c_2 \right) Q & = & \operatorname{vc} c_2 \ Q \wedge \left( \operatorname{vc} c_1 \left( \operatorname{pre} c_2 \ Q \right) \right) \\ \operatorname{vc} \left( \operatorname{IF} b \operatorname{THEN} c_1 \operatorname{ELSE} c_2 \right) Q & = & \operatorname{vc} c_1 \ Q \wedge \operatorname{vc} c_2 \ Q \\ \operatorname{vc} \left( \operatorname{WHILE} b \operatorname{INV} I \operatorname{DO} c \operatorname{OD} \right) Q & = & \left( \forall \sigma. \ I \sigma \wedge b \sigma \longrightarrow \operatorname{pre} c I \ \sigma \right) \wedge \\ & \qquad \qquad \qquad \left( \forall \sigma. \ I \sigma \wedge \neg b \sigma \longrightarrow Q \ \sigma \right) \wedge \\ & \qquad \qquad \operatorname{vc} c \ Q \wedge \left( P \Longrightarrow \operatorname{pre} c \ Q \right) \Longrightarrow \left\{ P \right\} c \left\{ Q \right\} \end{array}$$

#### Slide 7

## Syntax Tricks



- $\Rightarrow x := \lambda \sigma. \ 1$  instead of x := 1 sucks
- $\rightarrow$   $\{\lambda\sigma.\ \sigma\ x=n\}$  instead of  $\{x=n\}$  sucks as well

Problem: program variables are functions, not values

Solution: distinguish program variables syntactically

#### Choices:

- → declare program variables with each Hoare triple
  - · nice, usual syntax
  - · works well if you state full program and only use vcg
- → separate program variables from Hoare triple (use extensible records), indicate usage as function syntactically
  - · more syntactic overhead
  - · program pieces compose nicely

#### Slide 8



## **D**EMO

## Slide 9

## Arrays

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## Depending on language, model arrays as functions:

→ Array access = function application:

→ Array update = function update:

## Use lists to express length:

- → Array access = nth:
  - a[i] = a!i
- → Array update = list update:

→ Array length = list length:

#### Slide 10

## Pointers



#### Choice 1

 datatype
 ref
 = Ref int | Null

 types
 heap
 = int ⇒ val

 datatype
 val
 = Int int | Bool bool | Struct\_x int int bool | . . .

- → hp :: heap, p :: ref
- → Pointer access: \*p = the\_Int (hp (the\_addr p))
- → Pointer update: \*p :== v = hp :== hp ((the\_addr p) := v)
- → a bit klunky
- → gets even worse with structs
- → lots of value extraction (the\_Int) in spec and program

#### Slide 11

## Pointers



## Choice 2 (Burstall '72, Bornat '00)

struct with next pointer and element

 $\begin{array}{lll} \textbf{datatype} & \text{ref} & = \text{Ref int} \mid \text{Null} \\ \textbf{types} & \text{next\_hp} & = \text{int} \Rightarrow \text{ref} \\ \textbf{types} & \text{elem\_hp} & = \text{int} \Rightarrow \text{int} \\ \end{array}$ 

- → next :: next\_hp, elem :: elem\_hp, p :: ref
- → Pointer access: p→next = next (the\_addr p)
- → Pointer update:  $p\rightarrow next :== v$  = next :== next ((the\_addr p) := v)
- → a separate heap for each struct field
- $\Rightarrow \text{ buys you } p {\rightarrow} next \neq p {\rightarrow} elem \text{ automatically (aliasing)}$
- → still assumes type safe language

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## Slide 13

# We have seen today ...



- → Weakest precondition
- → Verification conditions
- → Example program proofs
- → Arrays, pointers

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