

Events, Co-routines, Continuations and Threads OS (and application) Execution Models

System Building

General purpose systems need to deal with

- Many activities
 - potentially overlapping
 - may be interdependent
 - » need to resume after something else happens
- Activities that depend on external phenomena
 - may requiring waiting for completion (e.g. disk read)
 - reacting to external triggers (e.g. interrupts)
- OS defines its execution model
 - low-level language
 - minimal runtime

Need a systematic approach to execution structure



Execution Models

- Events
- Coroutines
- Threads
- Continuations

Note: Focus is on uni-processor for now, multiprocessors come later in the course.



Events

External entities generate (post) events.

keyboard presses, mouse clicks, system calls

Event loop waits for events and calls an appropriate event handler.

Event handler is a function that runs until completion and returns to the event loop.

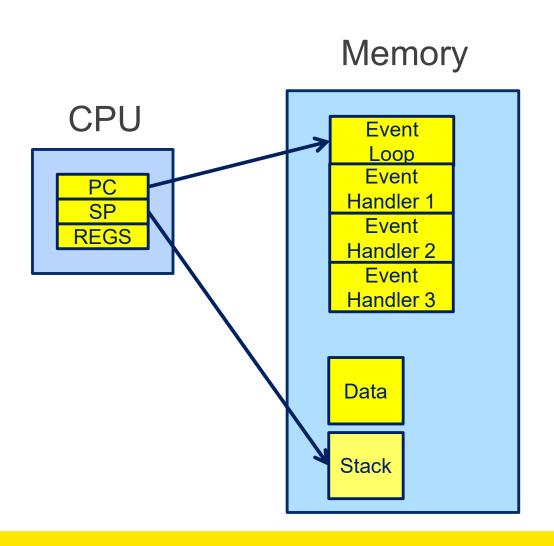


Some Definitions

- Block
 - Execution state is preserved
 - Marks current execution as blocked
 - It is no longer considered Ready
 - Removed from a Ready Queue
 - Requires an unblock to mark ready and rejoin the ready queue
 - Resumes from where it blocked
- Yield
 - Execution state is preserved
 - The thread relinquishes execution
 - Immediately placed in the ready queue
 - Resumes from where it yielded



Event Model



The event model only requires a single stack

- All event handlers must return to the event loop
 - No blocking
 - No yielding

No preemption of handlers

Handlers generally short lived

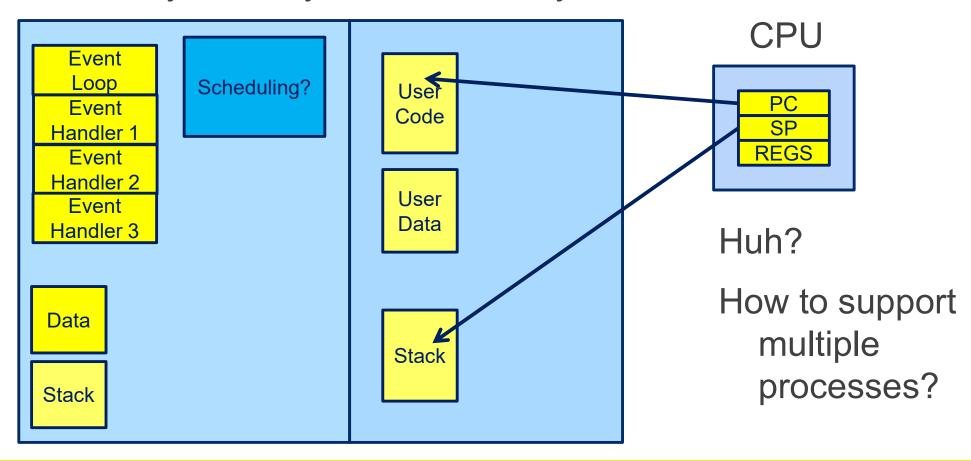


What is 'a'?

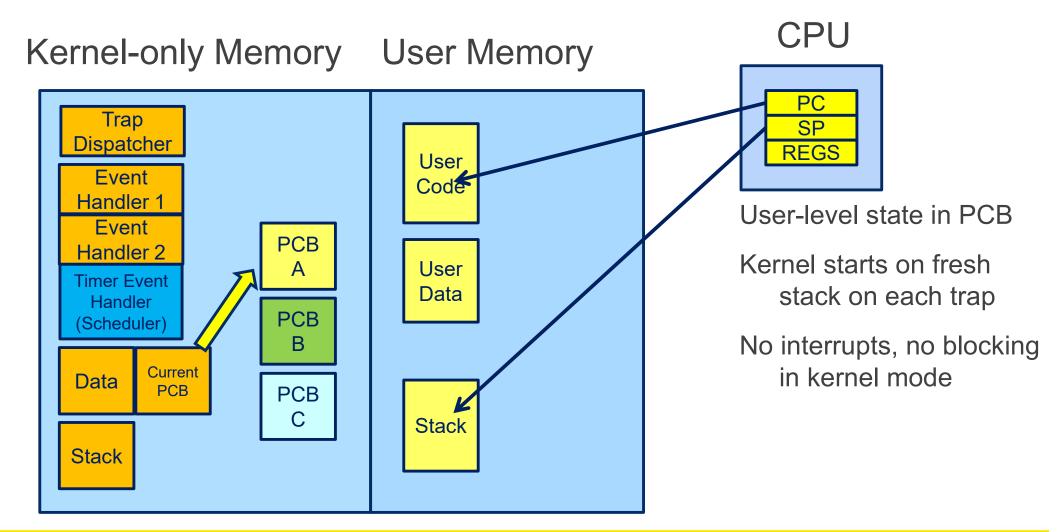
```
int a; /* global */
int func()
    a = 1;
    if (a == 1) {
        a = 2;
                    No concurrency issues within a
                    handler
    return a;
```

Event-based kernel on CPU with protection

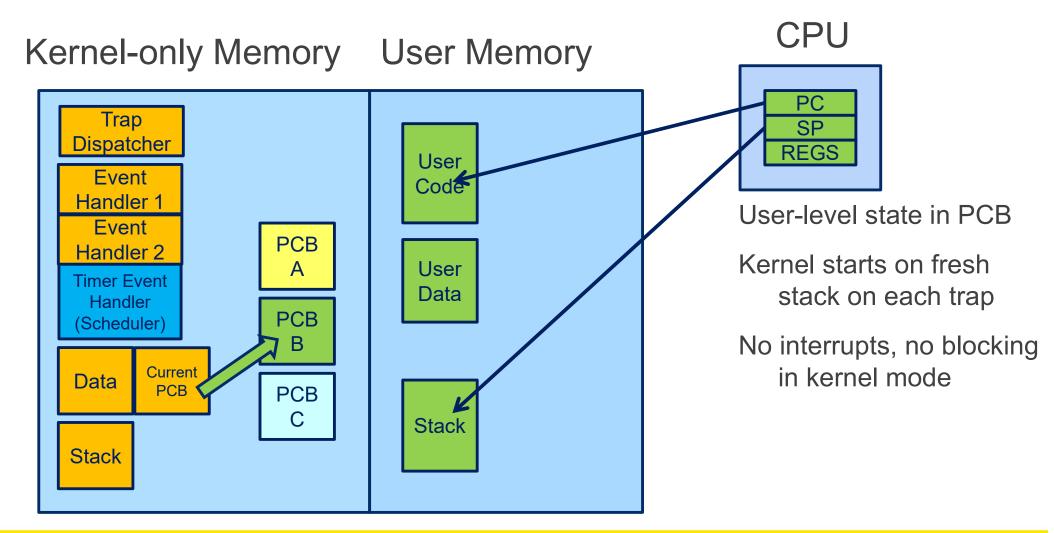
Kernel-only Memory User Memory



Event-based kernel on CPU with protection



Event-based kernel on CPU with protection



Co-routines

Originally described in:

Melvin E. Conway. 1963. Design of a separable transition-diagram compiler. Commun. ACM 6, 7 (July 1963), 396-408. DOI=http://dx.doi.org/10.1145/366663.366704

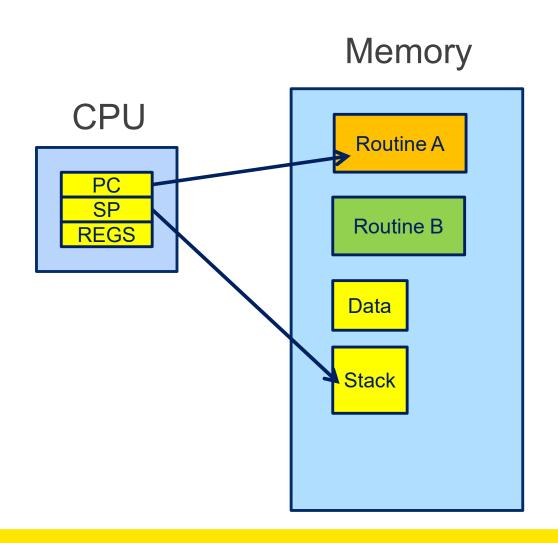
Analogous to a "subroutine" with extra entry and exit points.

Via yield()

- Supports long running subroutines
- Can implement sync primitives that wait for a condition to be true
 - while (condition != true) yield();



Co-routines



yield() saves state of routine A and starts routine B

 or resumes B's state from its previous yield() point.

No pre-emption, any switching is explicit via yield() in code

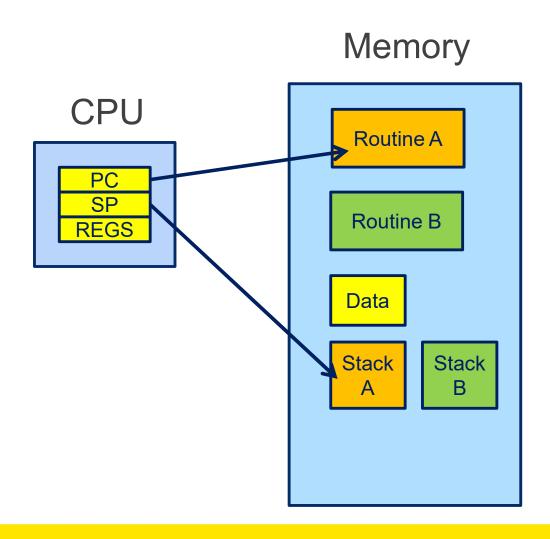
What is 'a'?

```
int a; /* global */
int func()
    a = 1;
    yield();
    if (a == 1) {
       a = 2;
    return a;
```

What is 'a'?

```
int a; /* global */
int func() {
    a = 1;
    if (a == 1) {
       yield();
       a = 2;
                       Limited concurrency
                       issues/races as globals are
    return a;
                       exclusive between yields()
```

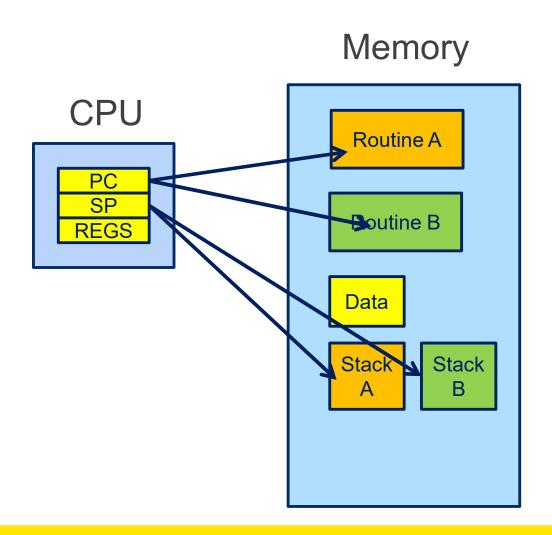
Co-routines Implementation strategy?



Usually implemented with a stack per routine

Preserves current state of execution of the routine

Co-routines



Routine A state currently loaded
Routine B state stored on stack
Routine switch from A → B

- saving state of A a
 - regs, sp, pc
- restoring the state of B
 - regs, sp, pc

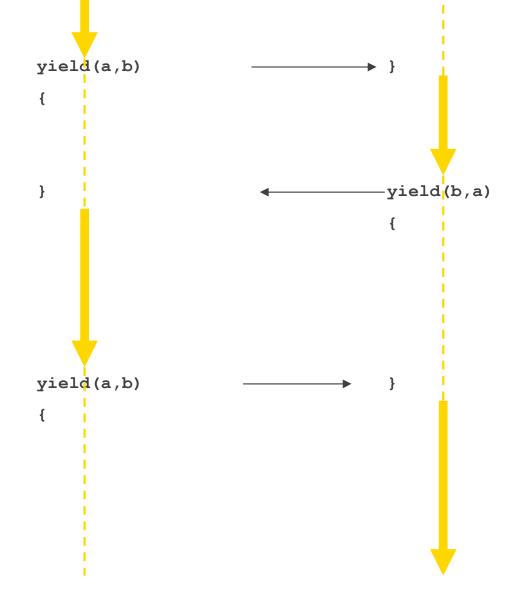
A hypothetical yield()

```
yield:
   /*
    * a0 contains a pointer to the previous routine's struct.
    * al contains a pointer to the new routine's struct.
    *
      The registers get saved on the stack, namely:
    *
           s0-s8
    *
           gp, ra
    *
    *
    */
   /* Allocate stack space for saving 11 registers. 11*4 = 44 */
   addi sp, sp, -44
```

```
/* Save the registers */
     ra, 40(sp)
  SW
  sw qp, 36(sp)
  sw s8, 32(sp)
                                  Save the registers
  sw s7, 28(sp)
                                  that the 'C'
     s6, 24(sp)
  SW
  sw s5, 20(sp)
                                  procedure calling
  sw s4, 16(sp)
                                  convention
  sw s3, 12(sp)
                                  expects
  sw s2, 8(sp)
  sw s1, 4(sp)
                                  preserved
  sw s0, 0(sp)
  /* Store the old stack pointer */
  sw sp, 0(a0)
```

```
/* Get the new stack pointer from the new pcb */
  lw sp, 0(a1)
               /* delay slot for load */
  nop
/* Now, restore the registers */
  lw s0, 0(sp)
  lw s1, 4(sp)
  lw s2, 8(sp)
  lw s3, 12(sp)
  lw s4, 16(sp)
  lw s5, 20(sp)
  lw s6, 24(sp)
      s7, 28(sp)
  lw
  lw s8, 32(sp)
  lw gp, 36(sp)
  lw ra, 40(sp)
                     /* delay slot for load */
  nop
/* and return. */
  j ra
  addi sp, sp, 44 /* in delay slot */
```

Yield



What is 'a'?

```
int a; /* global */
int func() {
    a = 1;
    func2();
    if (a == 1) {
        a = 2;
    return a;
```

Coroutines

What about subroutines combined with coroutines

i.e. what is the issue with calling subroutines?

Subroutine calling might involve an implicit yield()

- potentially creates a race on globals
 - either understand where all yields lie, or
 - cooperative multithreading



Cooperative Multithreading

Also called *green threads*

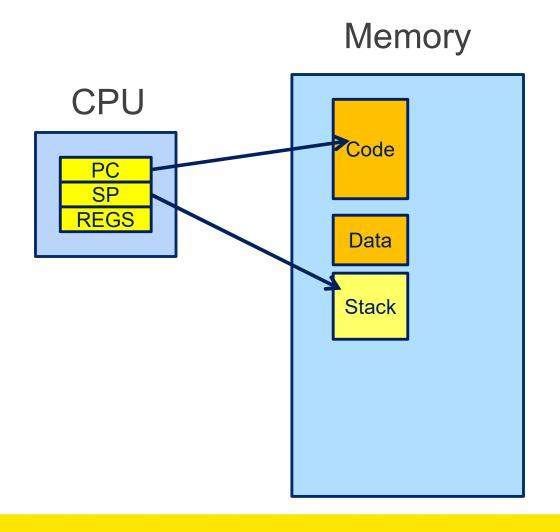
Conservatively assumes a multithreading model

- i.e. uses synchronisation (locks) to avoid races,
- and makes no assumption about subroutine behaviour
 - Everything thing can potentially yield()



```
int a; /* global */
lock_t a_lock;
int func() {
    int t;
    lock_acquire(a_lock)
    a = 1;
    func2();
    if (a == 1) {
        a = 2;
    t = a;
    lock_release(a_lock);
    return t;
```

A Thread

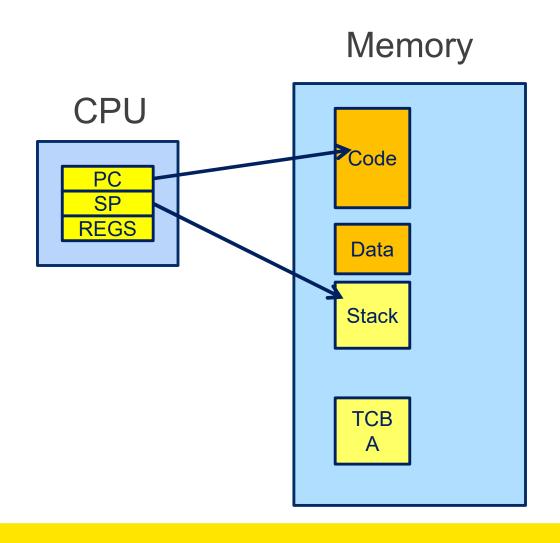


Thread attributes

- processor related
 - memory
 - program counter
 - stack pointer
 - registers (and status)
- OS/package related
 - state (running/blocked)
 - identity
 - scheduler (queues, priority)
 - etc...



Thread Control Block

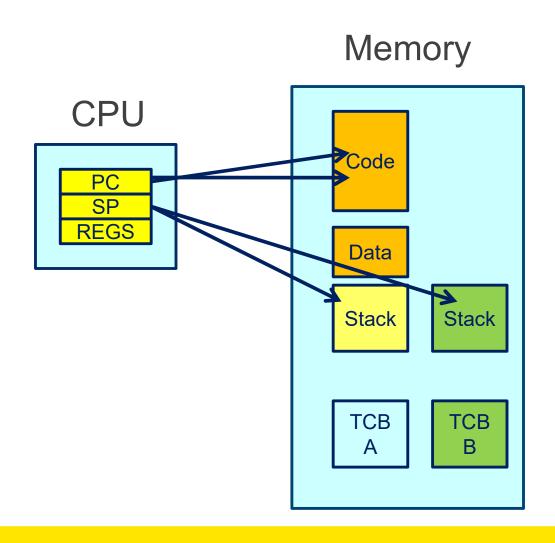


To support more than a single thread we to need store thread state and attributes

Stored in per-thread thread control block

also indirectly in stack

Thread A and Thread B



Thread A state currently loaded
Thread B state stored in TCB B

- · saving state of thread a
 - regs, sp, pc
- restoring the state of thread B

Thread switch from $A \rightarrow B$

regs, sp, pc

Note: registers and PC can be stored on the stack, and only SP stored in TCB



Approximate OS

```
mi_switch()
  struct thread *cur, *next;
  next = scheduler();
/* update curthread */
                                              Note: global
  cur = curthread;
                                              variable curthread
  curthread = next;
 * Call the machine-dependent code that actually does the
 * context switch.
 */
 md_switch(&cur->t_sp, &next->t_sp);
/* back running in same thread */
```

UNSW SYDNEY

OS/161 mips_switch

```
mips switch:
   /*
    * a0 contains a pointer to the old thread's struct tcb.
    * al contains a pointer to the new thread's struct tcb.
    *
    * The only thing we touch in the tcb is the first word, which
    * we save the stack pointer in. The other registers get saved
    * on the stack, namely:
    *
           s0-s8
           gp, ra
    *
    */
   /* Allocate stack space for saving 11 registers. 11*4 = 44 */
   addi sp, sp, -44
```

OS/161 mips_switch

```
/* Save the registers */
      ra, 40(sp)
  SW
     gp, 36(sp)
  SW
                                   Save the registers
  sw s8, 32(sp)
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  sw s7, 28(sp)
      s6, 24(sp)
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      s4, 16(sp)
  SW
                                   expects
      s3, 12(sp)
  SW
  sw s2, 8(sp)
                                   preserved
     s1, 4(sp)
  SW
      s0, 0(sp)
  SW
  /* Store the old stack pointer in the old tcb */
       sp, 0(a0)
  SW
```

OS/161 mips switch /* Get the new stack pointer from the new tcb */ sp, 0(a1) lw /* delay slot for load */ nop /* Now, restore the registers */ lw s0, 0(sp) lw s1, 4(sp) lw s2, 8(sp) lw s3, 12(sp) lw s4, 16(sp) lw s5, 20(sp) lw s6, 24(sp) lw s7, 28(sp) lw s8, 32(sp) lw gp, 36(sp) ra, 40(sp) lw /* delay slot for load */ nop /* and return. */ j ra addi sp, sp, 44 /* in delay slot */ .end mips_switch

Thread b

Thread Switch

```
mips switch(a,b)
                                  mips switch(b,a)
mips switch(a,b)
```

Preemptive Multithreading

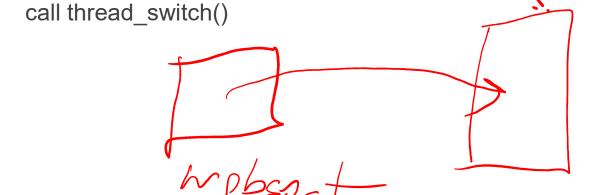
Switch can be triggered by asynchronous external event

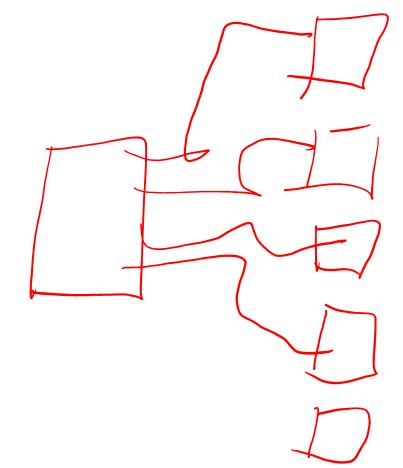
timer interrupt

Asynchronous interrupt triggers saving current state

on current stack, if in kernel (nesting)

on kernel stack or in TCB if coming from user-level

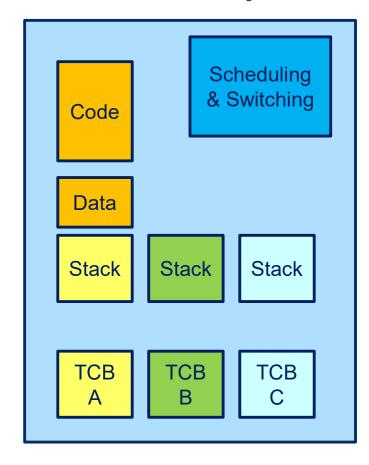






Threads on simple CPU

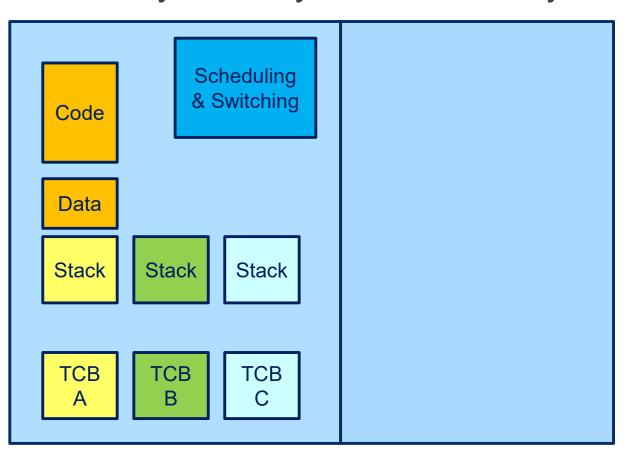
Memory

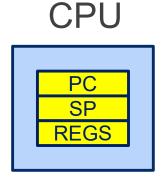


Threads on CPU with protection

Kernel-only Memory User Memory

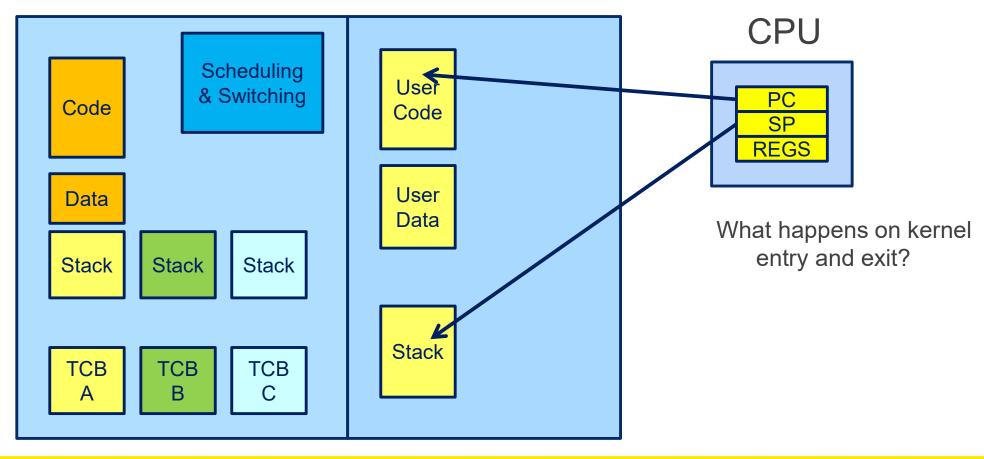
What is missing?



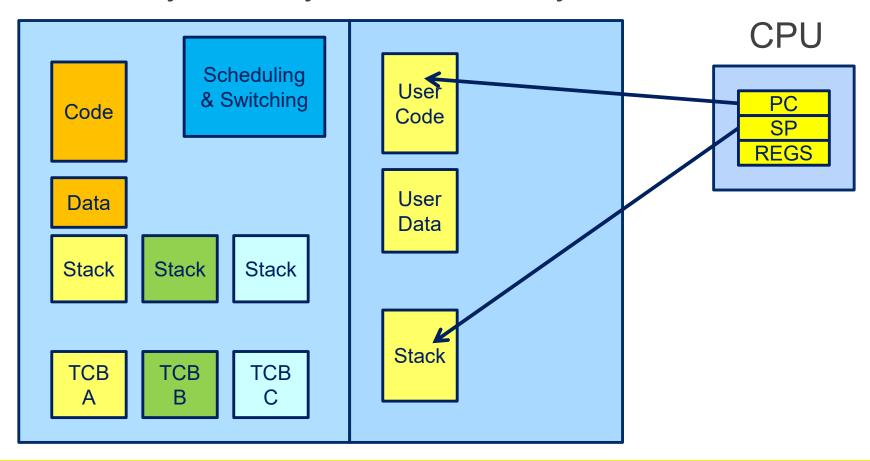


Threads on CPU with protection

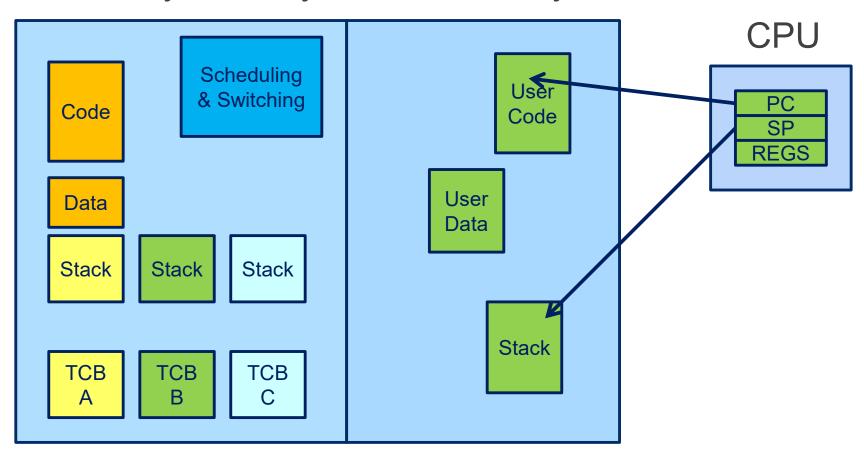
Kernel-only Memory User Memory



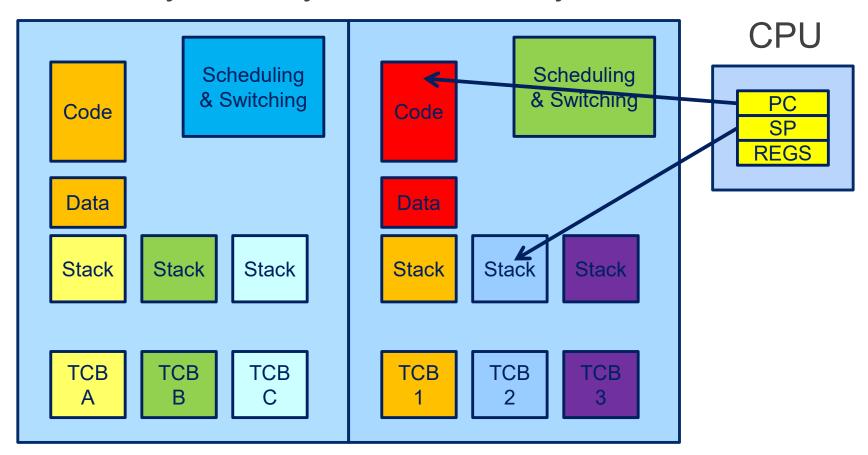
Switching Address Spaces on Thread Switch = Processes



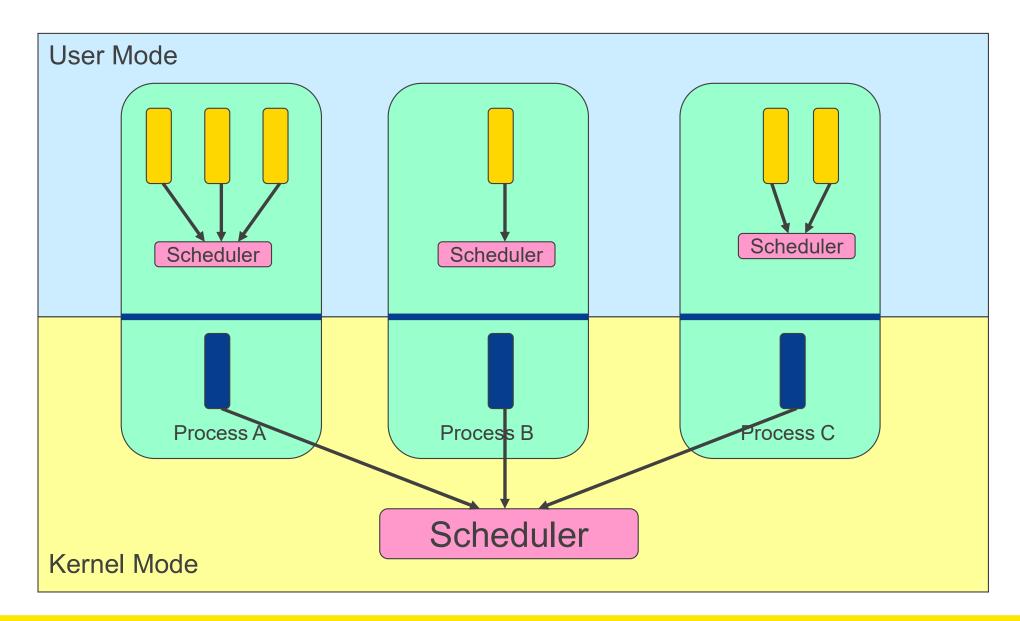
Switching Address Spaces on Thread Switch = Processes



What is this?



User-level Threads



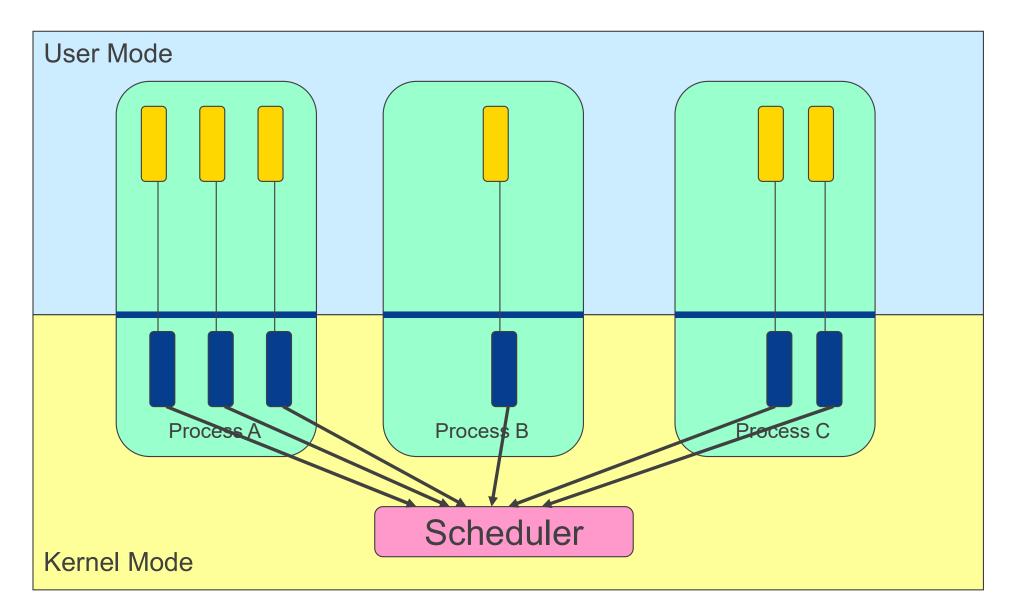


User-level Threads

- ✓ Fast thread management (creation, deletion, switching, synchronisation...)
- Blocking blocks all threads in a process
- Syscalls
- Page faults
- No thread-level parallelism on multiprocessor



Kernel-Level Threads





Kernel-level Threads

- Slow thread management (creation, deletion, switching, synchronisation...)
- System calls
- ✓ Blocking blocks only the appropriate thread in a process
- ✓ Thread-level parallelism on multiprocessor



Continuations

Definition of a Continuation

- representation of an instance of a computation at a point in time
- the state and code where to continue from

Warm-up using python

Traditional function that returns

```
def func(x):
    return x+1
```

- Function with a continuation indicating where to continue
 - The continuation is invoked with the function's result.

```
def func_cps(x,c):
    c(x+1)
```

Continuation Passing Style

Continuation Passing Style

```
def add(a,b):
                                def add_cps(a,b,cont):
   return a + b
                                    cont(a+b)
                                def mul_cps(a,b,cont):
def mul(a,b):
   return a * b
                                    cont(a*b)
def func(a,b):
                                def func_cps(a,b,c):
                                    mul(2,a,lambda r, y=b, c=c: add(r,y,c))
   return add(mult(2,a),b)
                                func_cps(3,4,print)
print(func(3,4))
=> 10
                                => 10
```

call/cc in Scheme (a functional language)

call/cc = call-with-current-continuation

A function

- takes a function (f) to call as an argument
- calls that function with a reference to current continuation (cont) as an argument
- when cont is later called, the continuation is restored.
 - The argument to cont is returned from to the caller of call/cc

```
(call-with-current-continuation f)
(f(x)
  (x return_value)
```

Note

For C-programmers, call/cc is effectively saving stack, and PC



Simple Example

```
(define (f arg)
  (arg 2)
  3)
(display (f (lambda (x) x))); displays 3
(display (call-with-current-continuation f))
; displays 2
```

Derived from http://en.wikipedia.org/wiki/Call-with-current-continuation

Another Simple Example

```
(define the-continuation #f)
(define (test)
 (let ((i 0))
   ; call/cc calls its first function argument, passing
    a continuation variable representing this point in
   ; the program as the argument to that function.
    In this case, the function argument assigns that
    continuation to the variable the-continuation.
   (call/cc (lambda (k) (set! the-continuation k)))
    The next time the-continuation is called, we start here.
   (set! i (+ i 1))
  i))
```



Another Simple Example

```
> (test)
> (the-continuation)
> (the-continuation)
> ; stores the current continuation (which will print 4 next) away
> (define another-continuation the-continuation)
> (test); resets the-continuation
> (the-continuation)
> (another-continuation); uses the previously stored continuation
 4
```

Coroutine Example

```
;;; This starts a new routine running (proc).
(define (fork proc)
  (call/cc (lambda (k)
   (enqueue k)
   (proc))))
;;; This yields the processor to another routine, if there is one.
 (define (yield)
   (call/cc
    (lambda (k)
     (enqueue k)
     ((dequeue)))))
```

Continuations

The concept of capturing current (stack) state to continue the computation in the future In the general case, as many times as we like

Variations and language environments (e.g. in C) result in less general continuations

e.g. one shot continuations, setjmp()/longjump()



What should be a kernel's execution model?

Note that the same question can be asked of applications



The two alternatives

No one correct answer

From the view of the designer there are two alternatives.

Single Kernel Stack

Only one stack is used all the time to support all user threads.

Per-Thread Kernel Stack

Every user thread has a kernel stack.



Per-Thread Kernel Stack Processes Model

- A thread's kernel state is implicitly encoded in the kernel activation stack
- If the thread must block inkernel, we can simply switch from the current stack, to another threads stack until thread is resumed
- Resuming is simply switching back to the original stack
- Preemption is easy

```
example(arg1, arg2) {
  P1(arg1, arg2);
  if (need to block) {
        thread block();
       P2(arg2);
  } else {
       P3();
   /* return control to user */
  return SUCCESS;
```



Single Kernel Stack "Event" or "Interrupt" Model

How do we use a single kernel stack to support many threads?

Issue: How are system calls that block handled?

⇒ either continuations

 Using Continuations to Implement Thread Management and Communication in Operating Systems. [Draves et al., 1991]

⇒ or *stateless kernel* (event model)

- Interface and Execution Models in the Fluke Kernel. [Ford et al., 1999]
- Also seL4



Continuations

State required to resume a blocked thread is explicitly saved in a TCB

- A function pointer
- Variables

Stack can be discarded and reused to support new thread

Resuming involves discarding current stack, restoring the continuation, and continuing

```
example(arg1, arg2) {
   P1(arg1, arg2);
   if (need_to_block) {
        save arg in TCB;
        thread block(example continue);
        /* NOT REACHED */
   } else {
        P3();
   thread syscall return(SUCCESS);
}
example_continue() {
   recover arg2 from TCB;
   P2(recovered arg2);
   thread_syscall_return(SUCCESS);
```



Stateless Kernel

System calls cannot block within the kernel

- If syscall must block (resource unavailable)
 - Modify user-state such that syscall is restarted when resources become available
 - Stack content is discarded (functions all return)

Preemption within kernel difficult to achieve.

⇒ Must (partially) roll syscall back to a restart point

Avoid page faults within kernel code

- ⇒ Syscall arguments in registers
 - Page fault during roll-back to restart (due to a page fault) is fatal.

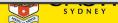


IPC implementation examples – Per thread stack

```
msg send rcv(msg, option,
       send_size, rcv_size, ...) {
   rc = msg_send(msg, option,
       send_size, ...);
   if (rc != SUCCESS)
   return rc;
   rc = msg_rcv(msg, option, rcv_size, ...);
   return rc;
```

Send and Receive system call implemented by a non-blocking send part and a blocking receive part.

Block inside msg_rcv if no message available



IPC examples - Continuations

```
msg_send_rcv(msg, option,
         send size, rcv size, ...) {
   rc = msg send(msg, option,
         send size, ...);
   if (rc != SUCCESS)
         return rc;
   cur thread->continuation.msg = msg;
   cur thread->continuation.option = option;
   cur thread->continuation.rcv size = rcv size;
   rc = msg rcv(msg, option, rcv size, ...,
         msg rcv continue);
   return rc;
msg rcv continue() {
   msg = cur thread->continuation.msg;
   option = cur thread->continuation.option;
   rcv size = cur thread->continuation.rcv size;
   rc = msg rcv(msg, option, rcv size, ...,
         msg rcv continue);
   return rc;
```

The function to continue with if blocked



IPC Examples – stateless kernel

```
msg send rcv(cur thread) {
   rc = msg_send(cur_thread);
   if (rc != SUCCESS)
        return rc;
                                                  Set user-level PC
   rc = msg_rcv(cur_thread);
                                                  to restart msg_rcv
   if (rc == WOULD_BLOCK) {
                                                  only
       set_pc(cur_thread, msg_rcv_entry);
       return RESCHEDULE;
   return rc;
                              RESCHEDULE changes
                              curthread on exiting the
```

kernel



Single Kernel Stack

per Processor, event model

either continuations

- complex to program
- must be conservative in state saved (any state that *might* be needed)
- Mach (Draves), L4Ka::Strawberry, NICTA Pistachio, OKL4

or stateless kernel

- no kernel threads, kernel not interruptible, difficult to program
- request all potentially required resources prior to execution
- blocking syscalls must always be re-startable
- Processor-provided stack management can get in the way
- system calls need to be kept simple "atomic".
- » e.g. the fluke kernel from Utah

low cache footprint

- » always the same stack is used!
- » reduced memory footprint



Per-Thread Kernel Stack

simple, flexible

- » kernel can always use threads, no special techniques required for keeping state while interrupted / blocked
- » no conceptual difference between kernel mode and user mode
- » e.g. traditional L4, Linux, Windows, OS/161

but larger cache footprint and larger memory consumption



Yet Another Simple Example



What is this?

